

# **PEL 105**



Power energy logger





Thank you for purchasing a PEL 105 power and energy logger.

For best results from your instrument:

- read these operating instructions carefully,
- **comply** with the precautions for use.

MARNING, risk of DANGER! The operator must refer to these instructions whenever this danger symbol appears.		
Equipment protected by double insulation.	= Earth.	
<b>←</b> USB.	Ethernet (RJ45).	
SD card.	Mains plug.	
Useful information or tip.		
The product is declared recyclable following an analysis of the lif	ife cycle in accordance with standard ISO 14040.	
CE The CE marking indicates conformity with European directives, i	in particular LVD and EMC.	
The rubbish bin with a line through it indicates that, in the Europe in compliance with Directive WEEE 2002/96/EC. This equipment		

### Definitions of the measurement categories

- Measurement category IV corresponds to measurements taken at the source of low-voltage installations. Example: power feeders, meters and protection devices.
- Measurement category III corresponds to measurements on building installations.
   Example: distribution panel, circuit-breakers, machines or fixed industrial devices.
- Measurement category II corresponds to measurements taken on circuits directly connected to low-voltage installations.
   Example: power supply to domestic electrical appliances and portable tools.

### PRECAUTIONS FOR USE

This instrument is compliant with safety standard IEC 61010-2-30, the leads are compliant with IEC 61010-031, and the current sensors are compliant with IEC 61010-2-032, for voltages up to 1,000V in category IV.

Failure to observe the safety instructions may result in electric shock, fire, explosion, or destruction of the instrument and of the installations.

- The operator and/or the responsible authority must carefully read and clearly understand the various precautions to be taken in use. Sound knowledge and a keen awareness of electrical hazards are essential when using this instrument.
- Use only the leads and accessories supplied. The use of leads (or accessories) of a lower voltage or category limits the voltage or category of the combined instrument and leads (or accessories) to that of the leads (or accessories).
- Before each use, check the condition of the insulation on the leads, housing, and accessories. Any item of which the insulation is deteriorated (even partially) must be set aside for repair or scrapping.
- Do not use the instrument on networks of which the voltage or category exceeds those mentioned.
- Do not use the instrument if it seems to be damaged, incomplete, or poorly closed.
- Use only the mains power unit supplied by the manufacturer.
- Use personal protection equipment systematically.
- When handling the leads, test probes, and crocodile clips, keep your fingers behind the physical guard.
- If the instrument is wet, dry it before connecting it.
- The instrument cannot be used to verify the absence of voltage in a network. For that, use the appropriate tool (a VAT) before doing any work on the installation.
- All troubleshooting and metrological checks must be performed by competent and accredited personnel.

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# 1. FIRST USE

### 1.1. DELIVERY CONDITION

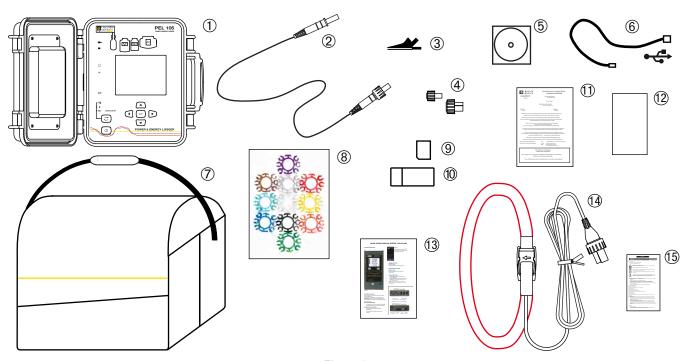


Figure 1

No.	Designation	Quantity
1	PEL 105.	1
2	Black safety leads, 3m, banana-banana, straight-straight, tight and lockable.	5
3	Lockable black crocodile clips.	5
4	Tight plugs for the terminals (mounted on the instrument).	9
(5)	CD containing the user manuals and PEL Transfer software.	1
6	USB cord, type A-B, 1.5m.	1
7	Carrying case.	1
8	Set of inserts and rings used to identify the phases on the measurement leads and on the current sensors.	12
9)	8GB SD card (in the instrument).	1
(10)	SD card-USB adapter.	1
(11)	Certificate of verification.	1
(12)	Safety data sheet of the PEL 105.	1
(13)	Getting started guide to the PEL 105.	15
(14)	AmpFlex® A196 tight current sensors.	4
(15)	Safety data sheets of the current sensor and of the leads.	2

Table 1

### 1.2. ACCESSORIES

MiniFlex® MA193 250 mm

MiniFlex® MA193 350 mm

MN93 clamp

MN93A clamp

C193 clamp

PAC93 clamp

E3N clamp

BNC adapter for E3N clamp

J93 clamp

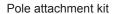
5A adapter (three-phase)

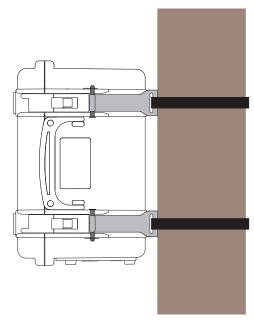
Essailec® 5A adapter

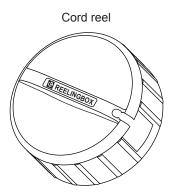
Mains power unit + E3N clamp

DataView software

PA30W mains power unit / charger







### 1.3. SPARE PARTS

Set of 5 black safety cables, banana-banana straight-straight,  $3m \log$ , tight and lockable.

Set of 5 lockable crocodile clips.

AmpFlex® A196 450 mm

USB-A - USB-B cord

No. 23 carrying case

Set of 4 black safety cables, banana-banana straight-straight, 4 crocodile clips, and 12 phase identification inserts and rings for the voltage leads and the current sensors.

For accessories and spares, visit our web site:

www.chauvin-arnoux.com

### 2. PRESENTATION OF THE INSTRUMENT

### 2.1. DESCRIPTION

PEL: Power & Energy Logger (power and energy logger)

The PEL 105 is a DC, single-phase, two-phase, and three-phase (wye and  $\Delta$ ) power and energy logger in a rugged sealed housing.

The PEL has all power/energy recording functions needed for most of the world's 50Hz, 60Hz, 400Hz, and DC distribution networks, with many connection possibilities to suit different installations. It is designed to operate in 1,000V CAT IV environments, both indoors and out.

The PEL has a battery with which to continue to operate if there is a power outage. The battery is recharged during the measurements.

The instrument has the following functions:

- Direct measurements of voltages up to 1,000V CAT IV.
- Direct measurements of currents from 50mA to 10,000A with A196 current sensors.
- Measurements of the neutral current on the 4<sup>th</sup> current terminal.
- Measurements of the voltage between earth and neutral on the 5th voltage terminal.
- Measurements of active power (W), reactive power (var), and apparent power (VA).
- Measurements of the fundamental, unbalance, and harmonic active powers.
- Measurement of current and voltage unbalances by the IEEE 1459 method.
- Measurements of active energy at source and load (Wh), 4-quadrant reactive energy (varh), and apparent energy (VAh).
- Power factor (PF),  $\cos \varphi$  and  $\tan \Phi$ .
- Crest factor.
- Total harmonic distortion (THD) of voltages and currents.
- Voltage and current harmonics up to the 50th at 50/60Hz.
- Frequency measurements.
- Simultaneous RMS and DC measurements on each phase.
- LCD display unit with blue backlighting (simultaneous display of 4 quantities).
- Storage of measured and calculated values on SD or SDHC card.
- Automatic recognition of the various types of current sensor.
- Configuration of the transformation ratios for the current and voltage inputs.
- Management of 17 types of connection or power distribution networks.
- USB, LAN (Ethernet), Wi-Fi, and Bluetooth communication.
- PEL Transfer software for data recovery, configuration, and real-time communication with a PC.

### 2.2. FRONT PANEL

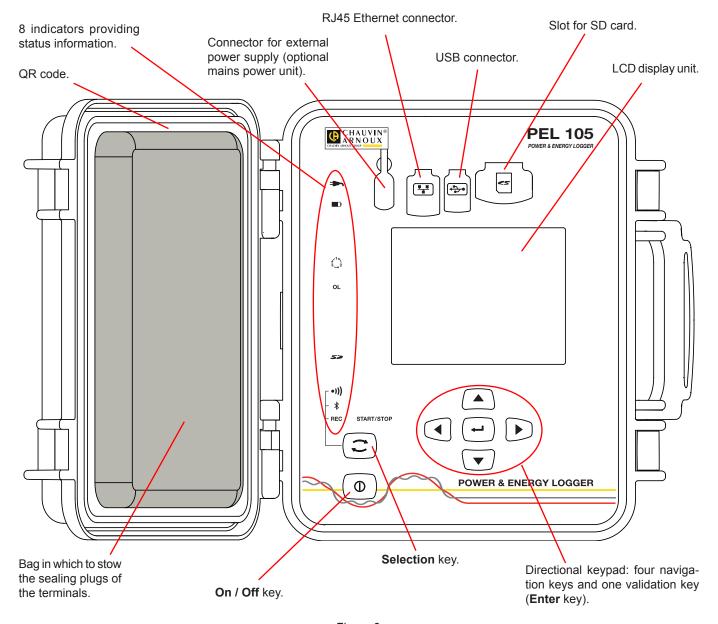


Figure 2

The connectors have elastomer caps that make them tight (IP67).

The mains power unit for recharging the battery is optional. It is not essential because the battery is recharged whenever the instrument is connected to mains (if supply via the voltage inputs has not been deactivated; see § 3.1.3).

### 2.3. TERMINAL BLOCK

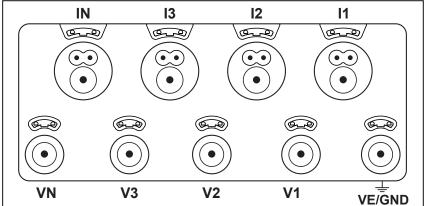


Figure 3

4 current inputs (specific 4-point connectors).

5 voltage inputs (safety connectors).

The plugs keep the terminals tight (IP67) when they are not in use.

When you connect a current sensor or a voltage lead, screw it tight to keep the instrument tight. Stow the plugs in the bag attached to the cover of the instrument.



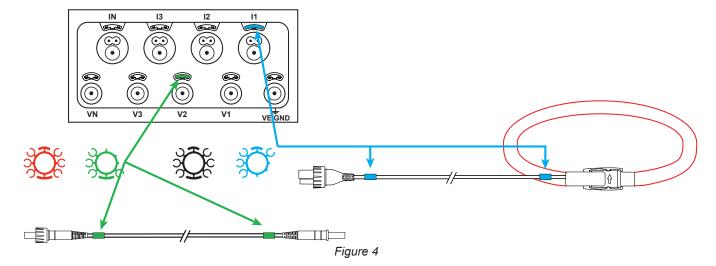
Before connecting a current sensor, refer to its operating instructions.

The small holes above the terminals are for the insertion of the coloured inserts used to identify the current or voltage inputs.

### 2.4. INSTALLATION OF THE COLOURED INSERTS

For polyphase measurements, start by marking the accessories and terminals with the coloured rings and inserts provided with the instrument, assigning a different colour to each terminal.

- Detach the appropriate inserts and place them in the holes above the terminals (the large ones for the current terminals, the small ones for the voltage terminals).
- Clip a ring of the same colour to each end of the cord that will be connected to the terminal.



### 2.5. FUNCTIONS OF THE KEYS

Key	Description
	On / Off Key: Switches the instrument on or off.
	<b>Remark:</b> The instrument cannot be switched off when it is connected to mains (whether by the measurement inputs or by the mains power unit) or when recording is in progress or pending.
	Selection key: A long press activates or deactivates Wi-Fi or the Bluetooth link and starts or stops recording.
	Enter key: In the Configuration mode, this is used to select a parameter to be changed. In the measurement and power display modes, it is used to display the phase angles and the partial energies.
<b>▲▼∢</b> ►	Navigation keys: These are used to browse and select the data displayed on the LCD screen.

Table 2

### 2.6. LCD DISPLAY UNIT

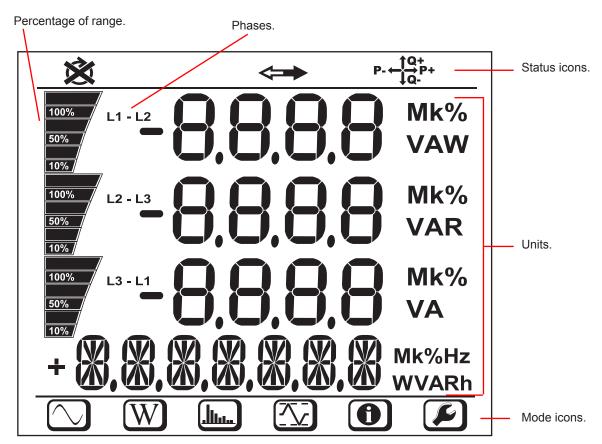


Figure 5

When there is no user activity for 3 minutes, the backlighting is switched off. To switch it back on, press one of the navigation keys  $(\blacktriangle \nabla \blacktriangleleft \blacktriangleright)$ .

The bottom and top strips provide the following indications:

Icon	Description
×	Indicator of a reversal of phase order or a missing phase (displayed for three-phase distribution networks, and only in measurement mode; see the explanation below)
<b>⇐</b>	Data available for recording.
P- ← ↑ Q+ ↓ Q-	Indication of the power quadrant.
	Measurement mode (instantaneous values). See § 4.3.1.
W	Power and energy mode. See § 4.3.2.
	Harmonics mode. See § 4.3.3.
	Max. mode See § 4.3.4.
•	Information mode. See § 3.6.
P	Configuration mode. See § 3.5.

Table 3

### Phase order

The phase order icon is displayed only when the measurement mode is selected.

The phase order is determined every second. If it is not correct, the symbol is displayed.

- The phase order for the voltage inputs is displayed only when the voltages are displayed.
- The phase order for the current inputs is displayed only when the currents are displayed.
- The phase order for the voltage and current inputs is displayed only when the powers are displayed.
- The source and load must be parameterized to define the direction of the energy (imported or exported).

### 2.7. INDICATORS

Indicators	Colour and function
<b>*</b>	Green indicator: Mains Indicator blinking: the instrument is connected to mains via the external power supply (optional mains power unit). Indicator off: the instrument is powered by the battery or via the voltage inputs.
	Orange / red indicator: Battery When the instrument is connected to mains, the battery is charged. Indicator off: battery fully charged. Indicator orange and blinking: battery charging. Indicator red and blinking twice per second: battery low (and no mains power).
3_2	Red indicator: Phase order Indicator off: phase rotation order correct. Indicator blinking: phase rotation order incorrect, i.e., one of the following cases:  ■ the phase difference between the phase currents is 30° greater than normal (120° in three-phase and 180° in two-phase).  ■ the phase difference between the phase voltages is 10° greater than normal.  ■ the phase difference between the currents and voltages of each phase is greater than 60° with respect to 0° (on a load) or 180° (on a source).

Indicators	Colour and function
OL	Red indicator: Overshoot of the measurement range Indicator off: no overshoot on the inputs. Indicator blinking: overshoot on at least one input. Indicator lit: a lead is missing or connected to the wrong terminal.
53	Green / red indicator: SD card Green indicator lit: the SD card is recognized and not locked. Red indicator lit: SD card missing or locked or not recognized. Red indicator blinking: SD card being initialized. Indicator blinking alternately red and green: SD card full. Red indicator blinking once every 5 s: the SD card will be full before the end of the recording session in progress.
-1))	Green indicator: Wi-Fi Indicator off: the Wi-Fi is not activated Indicator lit: the Wi-Fi is activated but fails to transmit. Indicator blinking: transmission by Wi-Fi in progress.
*	Blue indicator: Bluetooth Indicator off: Bluetooth link deactivated. Indicator lit: Bluetooth link activated, but no transmission. Indicator blinking: Bluetooth link activated and transmitting.
REC	Green indicator: Recording Indicator blinking once every 5 s: recorder waiting. Indicator blinking twice every 5 s: recorder in record mode.
(1)	Green/orange indicator: On / Off Green indicator lit: The instrument is in operation and is supplied by the voltage inputs. Orange indicator blinking: Supply by the voltage inputs is deactivated (See § 3.1.3).

Table 4

### 2.8. MEMORY CARD

The PEL accepts SD and SDHC cards, FAT32 formatted, up to a capacity of 32 GB.

The PEL is delivered with a formatted SD card. If you want to install a new SD card:

Attention: do not withdraw the SD card if recording is in progress.

- Open the elastomer cap marked **>>**.
- Press on the SD card in the instrument, then withdraw it.
- Check that the new SD card is not locked.
- It is best to format the SD card using the PEL Transfer software (see § 5), otherwise, format it using a PC.
- Insert the new card and push it home.
- Put the elastomer cap back on to keep the instrument tight.



### 3. CONFIGURATION

The PEL must be configured before any recording. The various steps in this configuration are:

- Set up the Wi-Fi link, the Bluetooth link, the USB link, or the Ethernet link.
- Choose the connection according to the type of distribution network.
- Connect the current sensors.
- Define the nominal primary and secondary voltages if necessary.
- Define the nominal primary current and the nominal primary current of the neutral if necessary.
- Choose the aggregation period.

This configuration is done in the Configuration mode (see § 3.5) or using the PEL Transfer software (see § 5). To forestall accidental modifications, the PEL cannot be reconfigured while recording.

### 3.1. SWITCHING THE INSTRUMENT ON AND OFF

### 3.1.1. SWITCHING ON

■ Connect the PEL to an electrical network (at least 100 Vac or 140 Vbc) and it is switched on automatically (if supply via the voltage inputs has not been deactivated; see § 3.1.3). Otherwise, press the On / Off key for more than 2 seconds. The green indicator below the On / Off key lights.



The battery automatically starts charging when the PEL is connected to a power or voltage source. The battery life is approximately one hour when it is fully charged. This enables the instrument to continue to operate if there is a brief power outage.

### 3.1.2. SWITCHING OFF

You cannot switch the PEL off while it is connected to a power source or while recording is in progress (or pending). This is a precaution intended to forestall any involuntary stoppage of a recording session by the user.

When it is disconnected from the power source and recording is over, the PEL switches itself off automatically after 3, 10, or 15 minutes, depending on the setting chosen.

Otherwise, to switch the PEL off:

- Disconnect all input terminals and the external power unit, if it is connected.
- Press the On / Off key for more than 2 seconds, until all indicators light, then release it.
- The PEL switches itself off and all indicators and the display unit go off.

### 3.1.3. DE-ACTIVATION OF SUPPLY BY THE VOLTAGE INPUTS

Supply by the voltage inputs consumes from 10 to 15W. Some voltage generators cannot withstand this load. This applies to voltage calibrators and to capacitive voltage dividers. If you want to make measurements on these devices, supply to the instrument by the voltage inputs must be deactivated.

To deactivate supply to the instrument by the voltage inputs, press the **Selection** and **On / Off** keys simultaneously for more than 2 seconds. The **On / Off** key blinks orange.

To supply the instrument and recharge the battery, it is necessary to use the mains power unit sold as an option (see § 1.2).

### 3.2. BATTERY CHARGING

120 V ± 10 %, 60 Hz

The battery is charged when the instrument is connected to a voltage source. But if supply by the voltage inputs has been deactivated (see previous section), the mains power unit must be used (optional).

230 V ± 10 %, 50 Hz

Figure 6

- Withdraw the elastomer cap that protects the power supply connector.
- Connect the mains power unit to the instrument and to mains.

The instrument comes on.

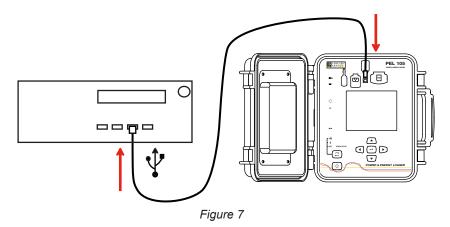
The indicator blinks until the battery is fully charged.

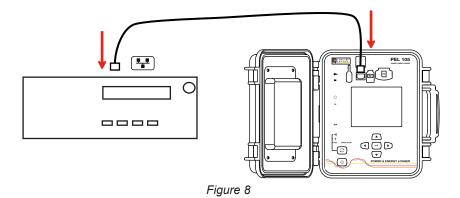
### 3.3. CONNECTION BY USB OR BY ETHERNET LAN LINK

The USB and Ethernet links can be used to configure the instrument using PEL Transfer software, to display the measurements, and to upload records to the PC.

- Withdraw the elastomer cap that protects the connector.
- Connect the USB cable provided or an Ethernet cable (not provided) between the instrument and the PC.







Then, whichever link was chosen, open the PEL Transfer software (see § 5) to connect the instrument to the PC.



Connecting the USB or Ethernet cable does not power up the instrument or charge the battery.

For the Ethernet LAN link, the PEL has an IP address.

When you configure the instrument with the PEL Transfer software, if the "Activate DHCP" (dynamic IP address) box is checked, the instrument sends a request to the network's DHCP server to obtain an IP address automatically.

The Internet protocol used is UDP or TCP. The port used by default is 3041. It can be modified in PEL Transfer so as to enable connections between the PC and several instruments behind a router.

The auto IP address mode is also available when the DHCP is selected and the DHPC server has not been detected within 60 seconds. The PEL will use 169.254.0.100 as default address. This auto IP address mode is compatible with APIPA. A crossed cable may be necessary.

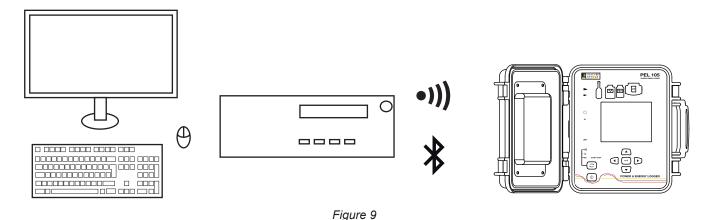


You can change the network parameters while connected via an Ethernet LAN link, but once the network parameters have been changed, you will lose connection. It is better to use a USB connection for this.

### 3.4. CONNECTION BY WI-FI OR BY THE BLUETOOTH LINK

The Wi-Fi or Bluetooth link can be used to configure the instrument using the PEL Transfer software, to display the measurements, and to upload records to the PC.

- Press the **Selection** (こ) key and hold it down. The **REC**, •)) and ≯ indicators light in turn for 3 seconds each.
- Release the **Selection** (こ) key while the desired function is lit.
  - If you release it while the REC indicator is lit, recording starts or stops.
  - If you release it while the •)) indicator is lit, the Wi-Fi is activated or deactivated.
  - If you release it while the \* indicator is lit, the Bluetooth link is activated or deactivated.



If your computer does not generate Bluetooth, use a USB-Bluetooth adapter. If you have no driver for this peripheral, Windows installs one automatically.

The pairing procedure depends on your operating system, on the Bluetooth equipment, and on the driver. If needed, the pairing code is 0000. This code cannot be modified in PEL Transfer.

### 3.5. CONFIGURING THE INSTRUMENT

It is possible to configure some main functions directly on the instrument. For a complete configuration, use the PEL Transfer software (see § 5).

To enter the Configuration via the instrument mode, press the ◀ or ▶ key until the symbol is selected.

The following screen is displayed:

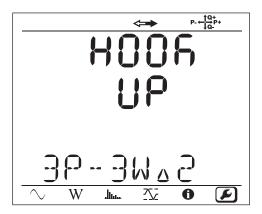


Figure 10

If the PEL is already being configured via the PEL Transfer software, it is impossible to enter the Configuration mode in the instrument. In this case, when there is an attempt to configure it, the instrument displays LOCK.

### 3.5.1. TYPE OF NETWORK

To change the network, press the **Enter** key. The name of the network blinks. Use the ▲ and ▼ keys to choose another network from among those in the list below.

Designation	Network
1P-2W	Single-phase, 2-wire
1P-3W	Single-phase, 3-wire
3P-3W∆2	Three-phase, 3-wire $\Delta$ (2 current sensors)
3P-3W∆3	Three-phase, 3-wire $\Delta$ (3 current sensors)
3P-3W∆b	Three-phase, 3-wire ∆, balanced
3P-4WY	Three-phase, 4-wire, wye
3P-4WYb	Three-phase, 4-wire, wye, balanced (voltage measurement, fixed)
3P-4WY2	Three-phase, 4-wire, wye 2½
3P-4W∆	Three-phase, 4-wire $\Delta$
3P-3WY2	Three-phase, 3-wire, wye (2 current sensors)
3P-3WY3	Three-phase, 3-wire, wye (3 current sensors)
3P-3WO2	Three-phase, 3-wire open $\Delta$ (2 current sensors)
3P-3WO3	Three-phase, 3-wire open $\Delta$ (3 current sensors)
3P-4WO∆	Three-phase, 4-wire, open $\Delta$
dC-2W	DC 2-wire
dC-3W	DC 3-wire
dC-4W	DC 4-wire

Table 5

Validate your choice by pressing the **Enter** key.

### 3.5.2. CURRENT SENSORS

Connect the current sensors to the instrument.

The current sensors are automatically detected by the instrument. It looks at the L1 terminal. If there is nothing, it looks at the L2 terminal, or the L3 terminal. If the chosen network is not balanced, it also looks at the N terminal.

Once the sensors have been recognized, the instrument displays their ratio.



The current sensors must all be the same, except for the neutral current sensor, which may be different. Otherwise, only the type of sensor connected to L1 will be used on the instrument.

### 3.5.3. NOMINAL PRIMARY VOLTAGE

Press the ▼ key to go to the next screen.

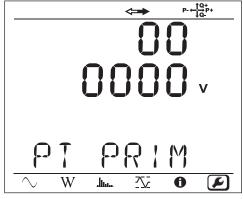


Figure 11

To change the nominal primary voltage, press the **Enter** key. Use the  $\blacktriangle$ ,  $\blacktriangledown$ ,  $\blacktriangle$  and  $\blacktriangleright$  keys to choose the voltage, between 50 and 650,000 V. Then validate by pressing the **Enter** key.

### 3.5.4. NOMINAL SECONDARY VOLTAGE

Press the ▼ key to go to the next screen.

To change the nominal secondary voltage, press the **Enter** key. Use the ▲, ▼, ▲ and ▶ keys to choose the voltage, between 50 and 1,000 V. Then validate by pressing the **Enter** key.

### 3.5.5. NOMINAL PRIMARY CURRENT

Press the ▼ key to go to the next screen.

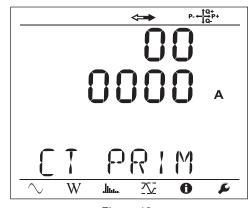


Figure 12

Depending on the type of current sensor, MiniFlex®/AmpFlex®, MN clamp, or adapter unit, enter the nominal primary current. To do this, press the **Enter** key. Use the  $\blacktriangle$ ,  $\blacktriangledown$ ,  $\blacktriangle$  and  $\blacktriangleright$  keys to choose the current.

- AmpFlex® A196 or A193 and MiniFlex® MA 193 : 100, 400, 2,000 or 10,000A
- PAC93 clamp and C193 clamp: automatic at 1,000A
- MN93A clamp, 5A range, 5A Adapter: 5 to 25,000A
- MN93A clamp, 100A range: automatic at 100A
- MN93 clamp: automatic at 200A
- E3N clamp: 10 or 100A
- J93 clamp: automatic at 3,500 A

Validate the value by pressing the **Enter** key.

### 3.5.6. NOMINAL PRIMARY CURRENT OF THE NEUTRAL

Press the ▼ key to go to the next screen.

If you connect a current sensor to the current terminal of the neutral, enter its nominal primary current too in the same way as before.

### 3.5.7. AGGREGATION PERIOD

Press the ▼ key to go to the next screen.



Figure 13

To change the aggregation period, press the **Enter** key, then use the ▲ and ▼ keys to choose the value (1 to 6, 10, 12, 15, 20, 30, or 60 minutes).

Validate by pressing the **Enter** key.

### 3.6. INFORMATION

To enter the Information mode, press the ◀ or ▶ key until the symbol is selected.

Use the  $\blacktriangle$  and  $\blacktriangledown$  keys to scroll the information of the instrument:

■ Type of network



■ Nominal primary voltage

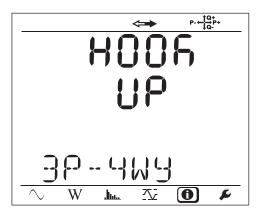


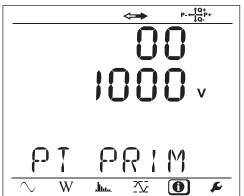
■ Nominal secondary voltage

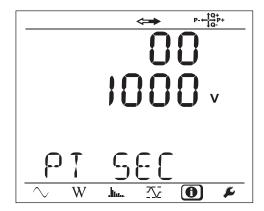


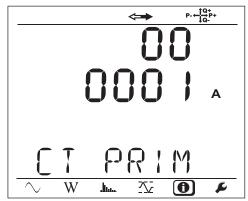
Nominal primary current











 $\blacksquare$  Nominal primary current of the neutral (if a sensor is connected to the  $I_{_{\rm N}}$  terminal)



■ Aggregation period

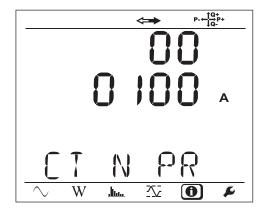


■ Date and time

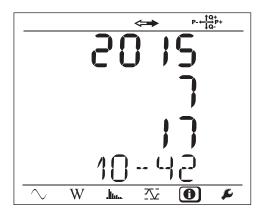


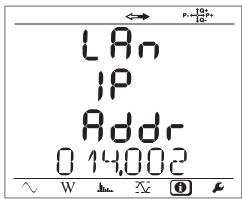
■ IP address (scrolling)









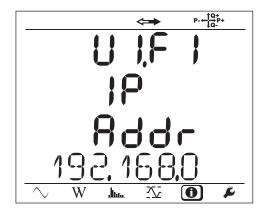


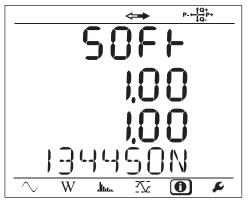
■ Wi-Fi address (scrolling)



- Software version
  - 1<sup>st</sup> number = software version of the DSP
  - 2<sup>nd</sup> number = software version of the microprocessor
  - Scrolling serial number (also on the QR code label glued to the inside of the cover of the PEL)







After 3 minutes with no action on the **Enter** or **Navigation** key, the display returns to the measurement screen .

When the instrument has been configured, you can use it.

### 4.1. DISTRIBUTION NETWORKS AND CONNECTIONS OF THE PEL

Start by connecting the current sensors and the voltage measurement leads to your installation according to the type of distribution network. The PEL must be configured (see § 3.5) for the distribution network selected.

Source



Load

Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

However, when a recording session has ended and been uploaded to a PC, it is possible to change the direction of the current (I1, I2, or I3) using the PEL Transfer software. This makes it possible to correct the power calculations.

The crocodile clips can be screwed onto the voltage leads, keeping the assembly tight. Only the AmpFlex® A196 sensors delivered with the instrument are tight.

### 4.1.1. SINGLE-PHASE, 2-WIRE

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth (optional on this type of network).
- Connect the V1 terminal to the L1 phase.
- Connect the I1 current sensor to the L1 phase.
- i

Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

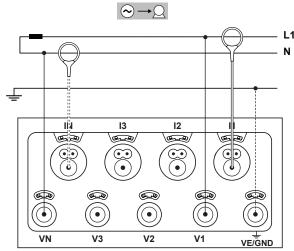


Figure 14

### 4.1.2. SPLIT-PHASE, 3-WIRE (SPLIT-PHASE FROM A CENTRE-TAP TRANSFORMER)

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth (optional on this type of network).
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the IN current sensor to the neutral (optional on this type of network).
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.



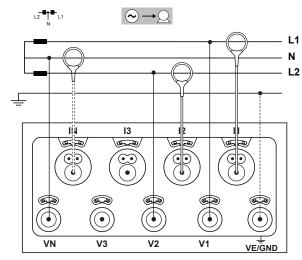


Figure 15

### 4.1.3. THREE-PHASE 3-WIRE SUPPLY NETWORKS

### 4.1.3.1. Three-phase, 3-wire, $\Delta$ (with 2 current sensors)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the I1 current sensor to the L1 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

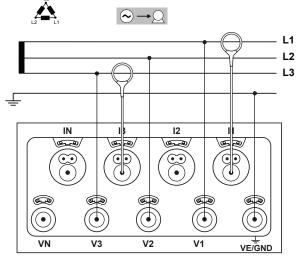


Figure 16

### 4.1.3.2. Three-phase, 3-wire, $\Delta$ (with 3 current sensors)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

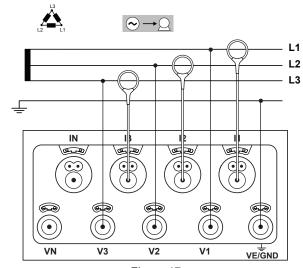


Figure 17

### 4.1.3.3. Three-phase, 3-wire open $\Delta$ (with 2 current sensors)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the I1 current sensor to the L1 phase.
- Connect the I3 current sensor to the L3 phase.



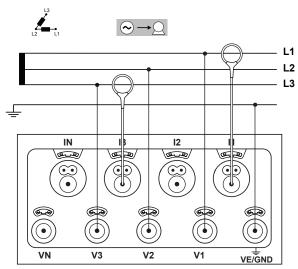


Figure 18

### 4.1.3.4. Three-phase, 3-wire open $\Delta$ (with 3 current sensors)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

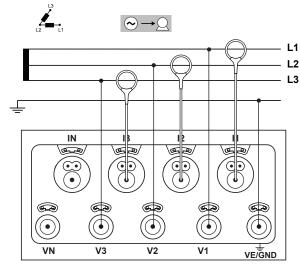


Figure 19

### 4.1.3.5. Three-phase, 3-wire, wye (with 2 current sensors)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the I1 current sensor to the L1 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

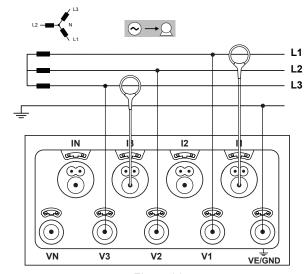


Figure 20

### 4.1.3.6. Three-phase, 3-wire, wye (with 3 current sensors)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



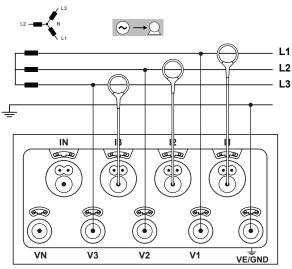


Figure 21

### 4.1.3.7. Three-phase, 3-wire $\Delta$ balanced (with 1 current sensor)

- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

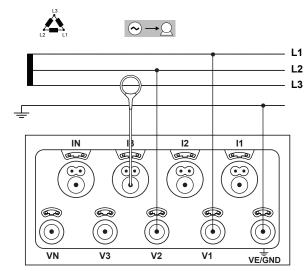


Figure 22

### 4.1.4. THREE-PHASE 4-WIRE WYE SUPPLY NETWORKS

### 4.1.4.1. Three-phase, 4-wire, wye (with 3 current sensors)

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the IN current sensor to the neutral.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.
- Alway

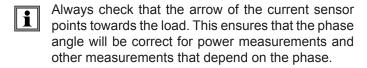
Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

# VN V3 V2 V1 VEĞND

Figure 23

### 4.1.4.2. Three-phase, 4-wire, wye, balanced

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the IN current sensor to the neutral.
- Connect the I1 current sensor to the L1 phase.



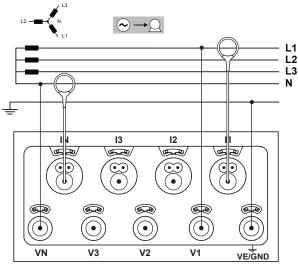


Figure 24

### 4.1.4.3. Three-phase, 4-wire, wye 21/2-elements

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the IN current sensor to the neutral.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

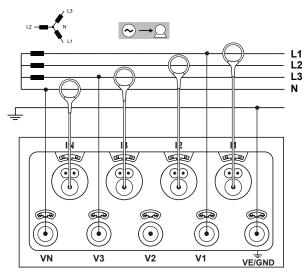


Figure 25

### 4.1.5. THREE-PHASE, 4-WIRE $\Delta$

Three-phase 4-wire  $\Delta$  (High Leg) configuration. No voltage transformer is connected: the installation measured is assumed to be a LV (low-voltage) distribution network.

### 4.1.5.1. Three-phase, 4-wire $\Delta$

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the IN current sensor to the neutral.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



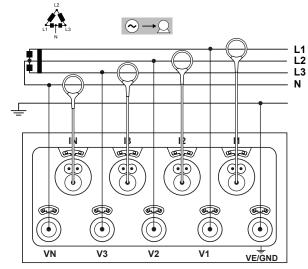


Figure 26

### 4.1.5.2. Three-phase, 4-wire, open $\Delta$

- Connect the N terminal to the neutral.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the L1 phase.
- Connect the V2 terminal to the L2 phase.
- Connect the V3 terminal to the L3 phase.
- Connect the IN current sensor to the neutral.
- Connect the I1 current sensor to the L1 phase.
- Connect the I2 current sensor to the L2 phase.
- Connect the I3 current sensor to the L3 phase.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

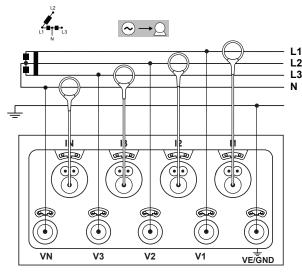


Figure 27

### 4.1.6. DC SUPPLY NETWORKS

### 4.1.6.1. DC 2-wire

- Connect the N terminal to the common conductor.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the +1 conductor.
- Connect the IN current sensor to the common conductor.
- Connect the current sensor I1 to the +1 conductor.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

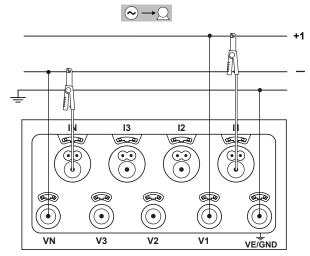
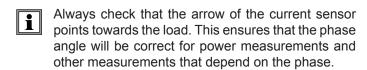


Figure 28

### 4.1.6.2. DC 3-wire

- Connect the N terminal to the common conductor.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the +1 conductor.
- Connect the V2 terminal to the +2 conductor.
- Connect the IN current sensor to the common conductor.
- Connect the current sensor I1 to the +1 conductor.
- Connect the current sensor I2 to the +2 conductor.



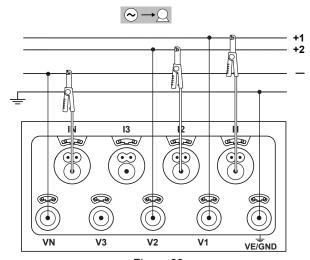


Figure 29

### 4.1.6.3. DC 4-wire

- Connect the N terminal to the common conductor.
- Connect the VE/GND terminal to the earth.
- Connect the V1 terminal to the +1 conductor.
- Connect the V2 terminal to the +2 conductor.
- Connect the V3 terminal to the +3 conductor.
- Connect the IN current sensor to the common conductor.
- Connect the current sensor I1 to the +1 conductor.
- Connect the current sensor I2 to the +2 conductor.
- Connect the current sensor I3 to the +3 conductor.



Always check that the arrow of the current sensor points towards the load. This ensures that the phase angle will be correct for power measurements and other measurements that depend on the phase.

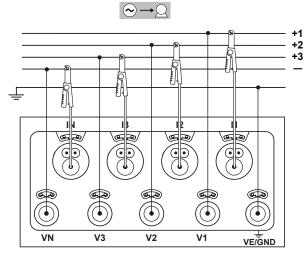


Figure 30

### 4.2. RECORDING

To start recording:

- Check that there is in fact an SD card (not locked and not full) in the PEL.
- Press the **Selection** (こ) key and hold it down. The **REC**, •)) and 🕏 indicators light in turn for 3 seconds each.
- Release the **Selection** key while the **REC** indicator is lit. Recording starts and the **REC** indicator starts blinking twice every 5 seconds.

To stop recording, proceed in exactly the same way. The **REC** indicator starts blinking once every 5 seconds.

It is possible to manage recording from PEL Transfer (see § 5).

### 4.3. MEASURED-VALUE DISPLAY MODES

The PEL has 4 display modes, represented by the icons at the bottom of the display unit. To change from one mode to the other, use the  $\triangleleft$  or  $\triangleright$  key.

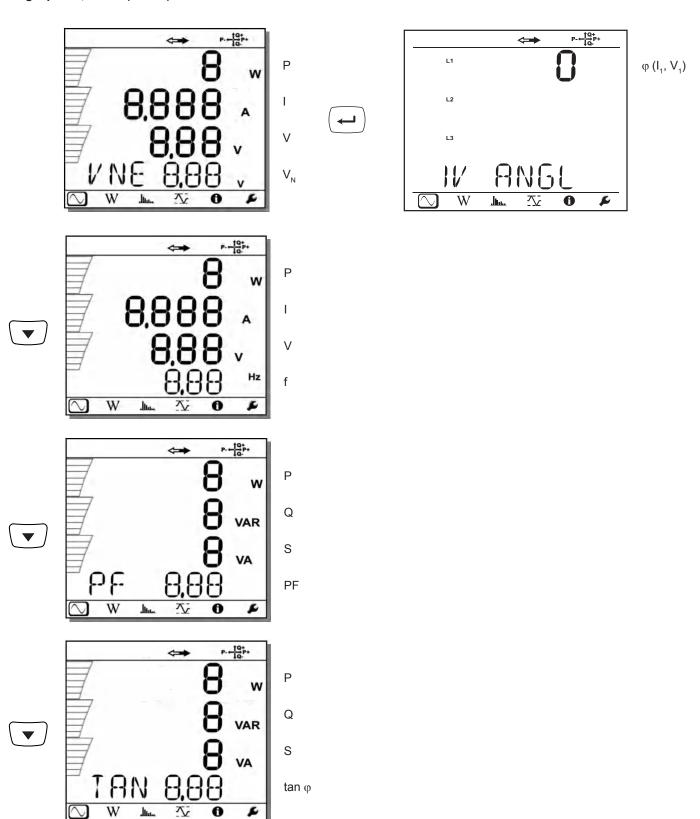
Icon	Display mode
	Instantaneous values display mode: voltage (V), current (I), active power (P), reactive power (Q), apparent power (S), frequency (f), power factor (PF), tan Φ.
W	Power and energy display mode: active energy of the load (Wh), reactive energy of the load (Varh), apparent energy of the load (VAh).
	Current and voltage harmonics display mode.
	Maximum values display mode: maximum aggregated values of the measurements and energy of the last recording.

The displays are accessible as soon as the PEL is on, but the values are zero. As soon as there is a voltage or current on the inputs, the values are updated.

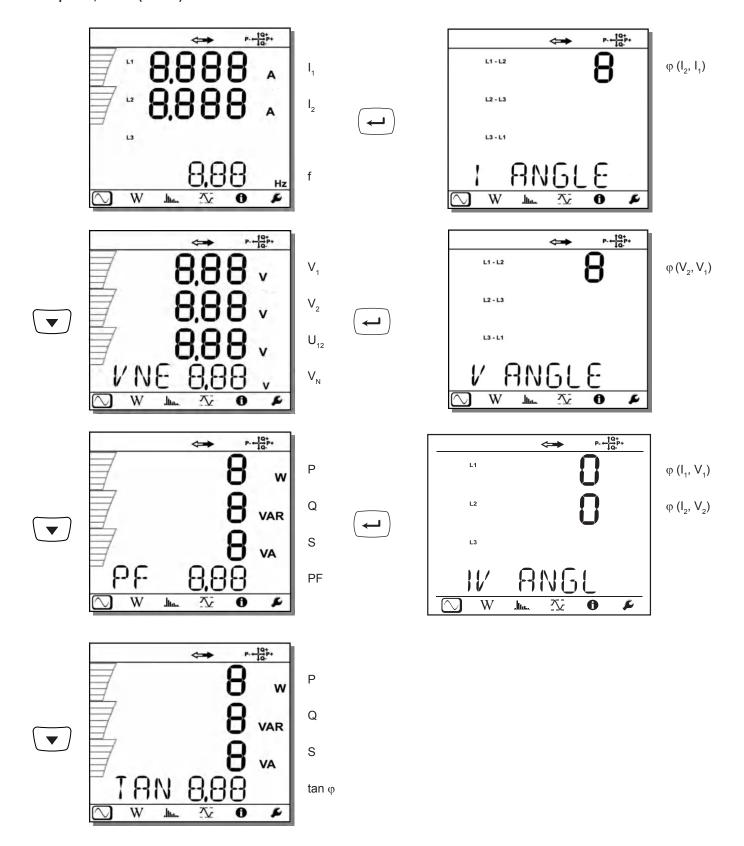
# 4.3.1. MEASUREMENT MODE

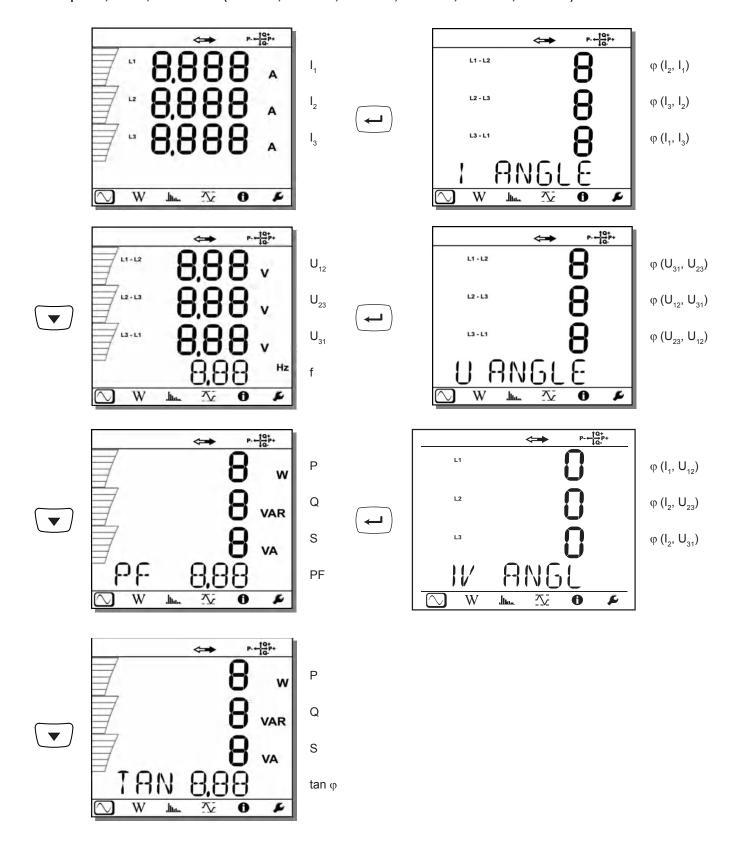
The display depends on the network configured. Press the  $\blacktriangledown$  key to go from one screen to the next.

### Single-phase, 2-wire (1P-2W)

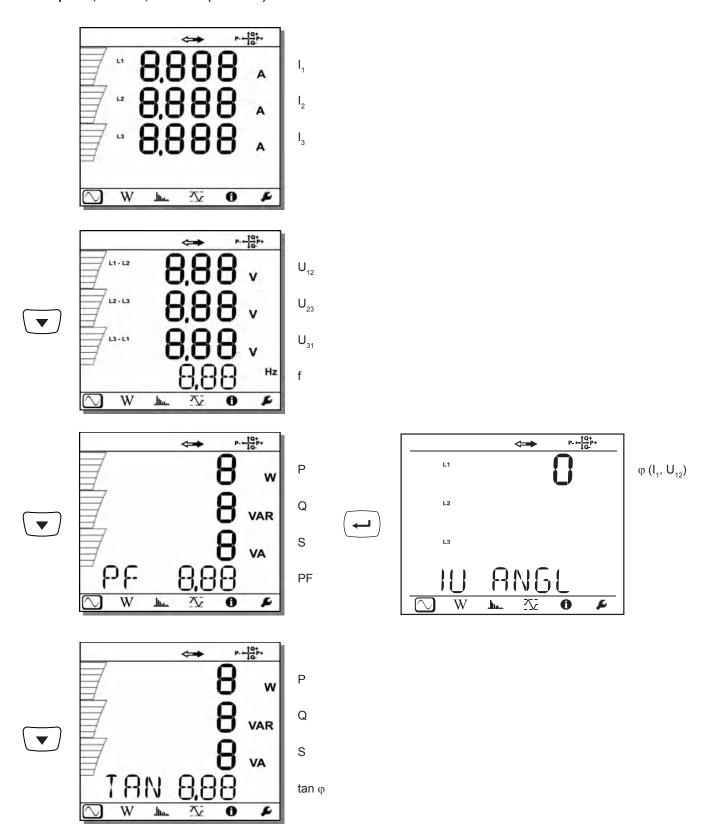


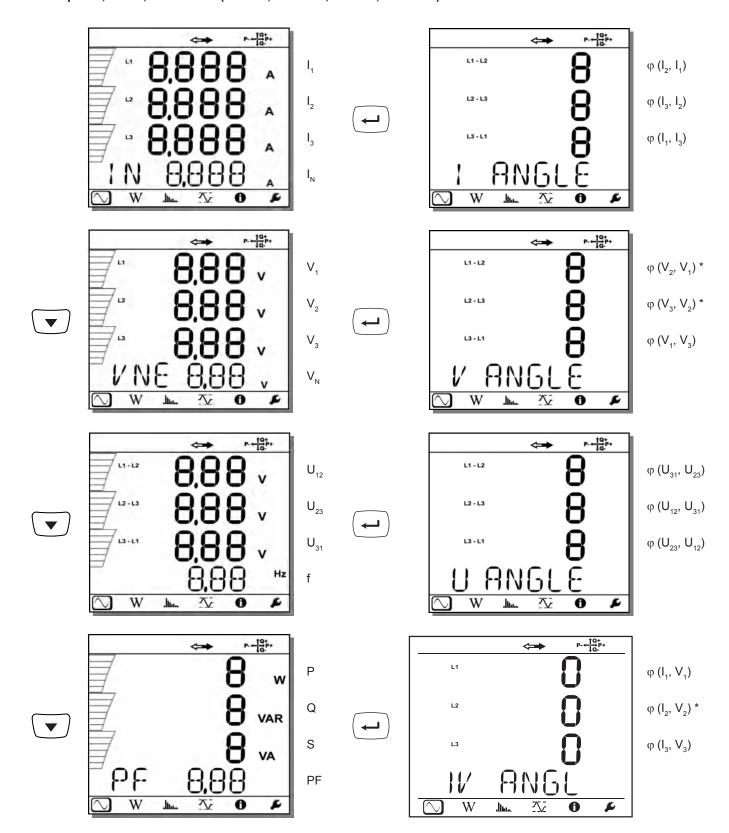
### Two-phase, 3-wire (2P-3W)



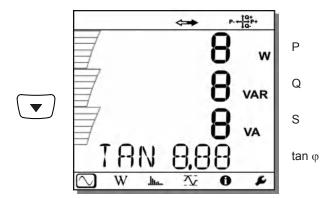


### Three-phase, 3-wire $\Delta$ , balanced (3P-3W $\Delta$ b)

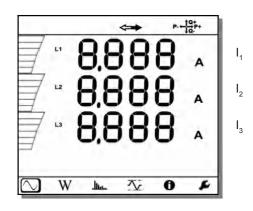


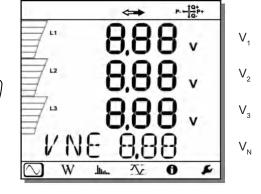


<sup>\*:</sup> For 3P-4W $\Delta$  and 3P-4WO $\Delta$  networks

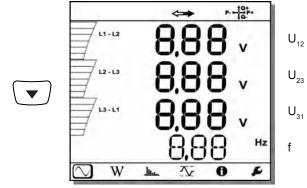


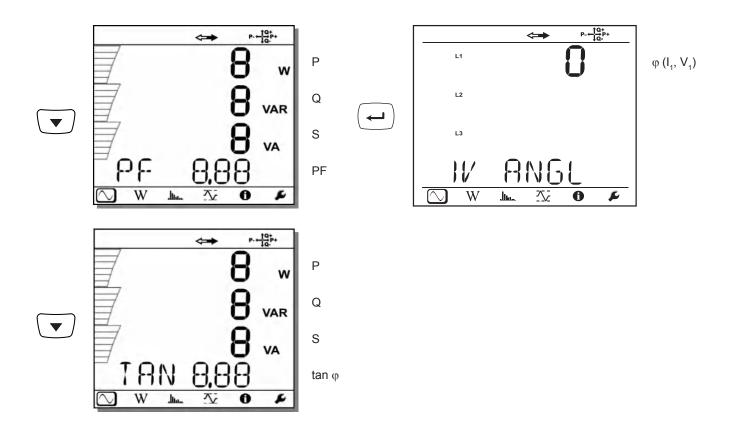
Three-phase, 4-wire, wye, balanced (3P-4WYb)



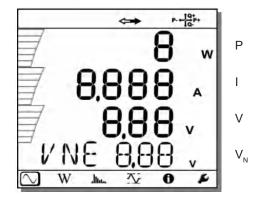


•

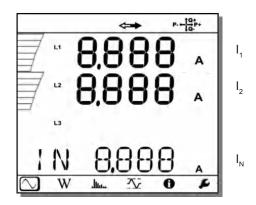


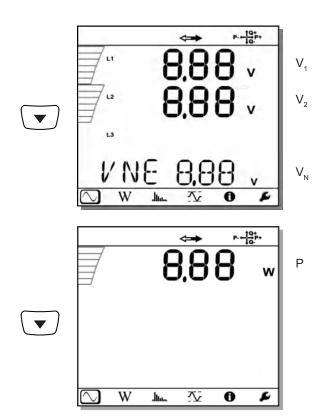


DC 2-wire, (dC-2W)

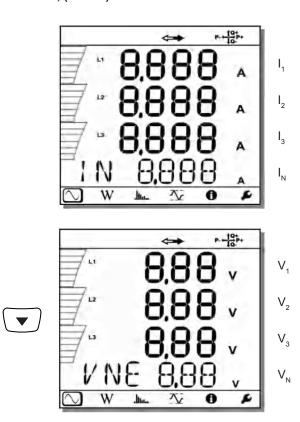


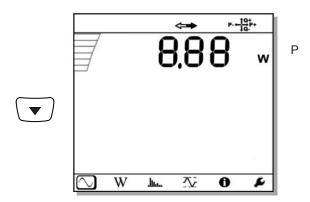
DC 3-wire, (dC-3W)





### DC 4-wire, (dC-4W)





# 4.3.2. Energy mode $\overline{W}$

The powers displayed are the total powers. The energy depends on the duration; typically it is available at the end of 10 or 15 minutes or at the end of the aggregation period.

Press the **Enter** key for more than 2 seconds to obtain the powers by quadrant (IEC 62053-23). The display unit indicates **PArt** to specify that the values are partial.

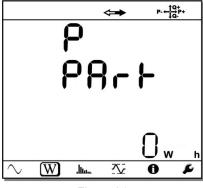


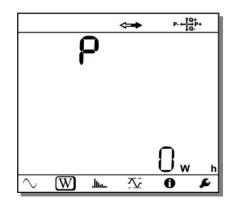
Figure 31

Press the lacktriangledown key to return to display of the total powers.

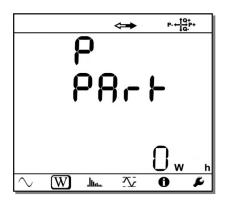
The display screens for AC and DC networks are different

### **AC** networks

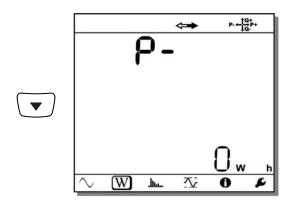
Ep+: Total active energy consumed (by the load) in kWh

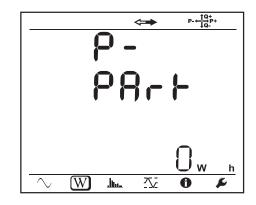




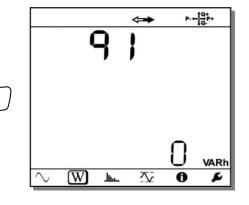


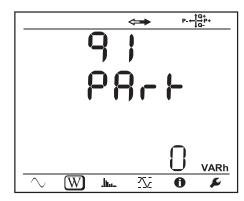
Ep-: Total active energy delivered (by the source) in kWh



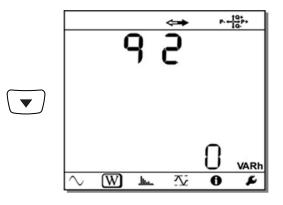


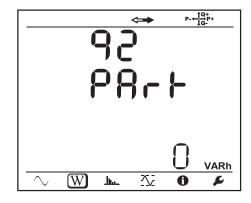
Eq1: Reactive energy consumed (by the load) in the inductive quadrant (quadrant 1) in kvarh.



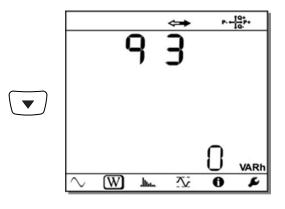


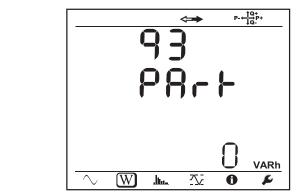
Eq2: Reactive energy delivered (by the source) in the capacitive quadrant (quadrant 2) in kvarh.



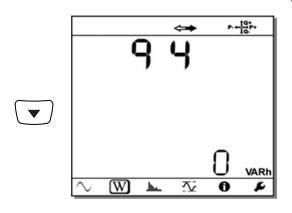


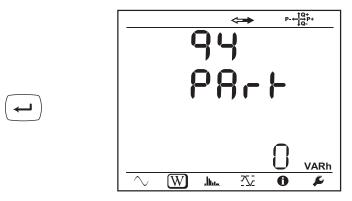
Eq3: Reactive energy delivered (by the source) in the inductive quadrant (quadrant 3) in kvarh.



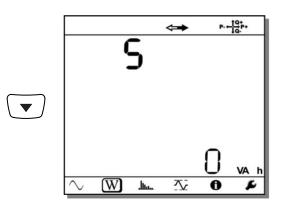


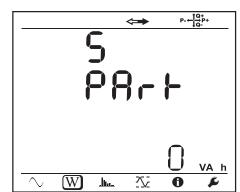
Eq4: Reactive energy consumed (by the load) in the capacitive quadrant (quadrant 4) in kvarh.



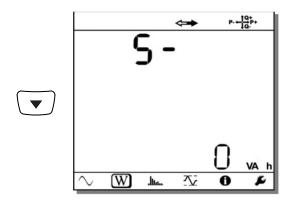


Es+: Total apparent energy consumed (by the load) in kVAh

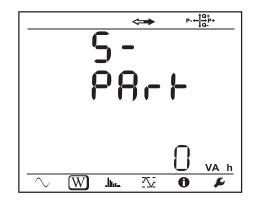




Es-: Total apparent energy delivered (by the source) in kVAh

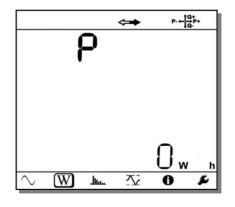




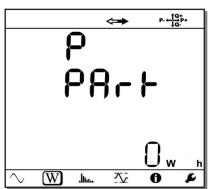


DC networks

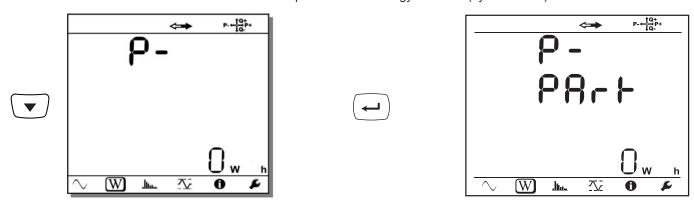
Ep+: Total active energy consumed (by the load) in kWh







Ep-: Total active energy delivered (by the source) in kWh

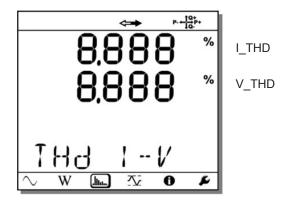


# 4.3.3. HARMONICS MODE

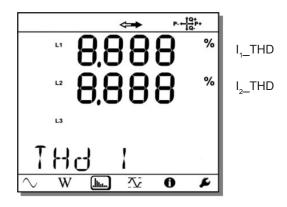
The display depends on the network configured.

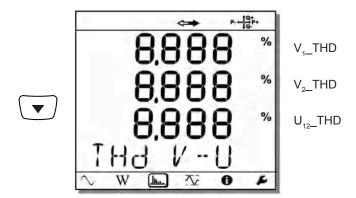
The harmonics display is not available for DC networks. The display unit indicates "No THD in DC mode".

# Single-phase, 2-wire (1P-2W)

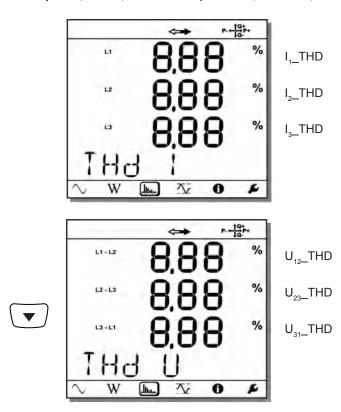


# Two-phase, 3-wire (1P-3W)

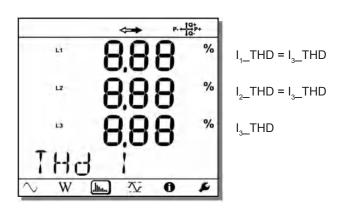


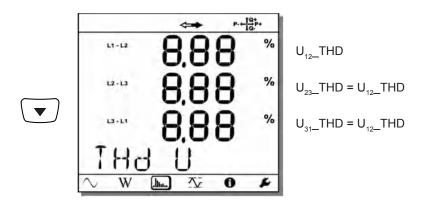


Three-phase, 3-wire, unbalanced (3P-3W∆2, 3P-3W∆3, 3P-3WO2, 3P-3WO3, 3P-3WY2, 3P-3WY3)

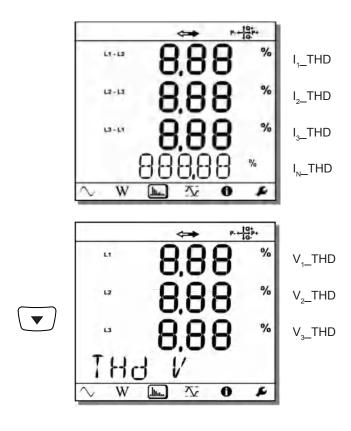


Three-phase, 3-wire  $\Delta$ , balanced (3P-3W $\Delta$ b)

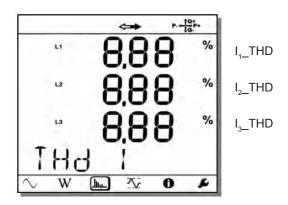


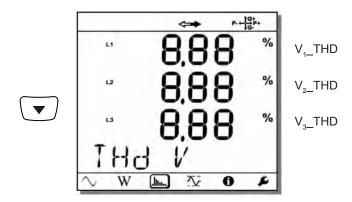


Three-phase, 4-wire, unbalanced (3P-4WY, 3P-4WY2, 3P-4WΔ, 3P-4WOΔ)



Three-phase, 4-wire, wye, balanced (3P-4WYb)



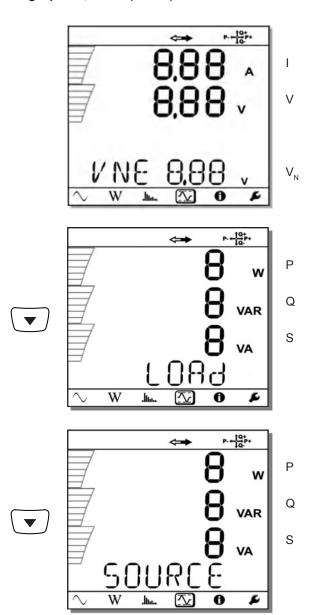


# 4.3.4. MAXIMUM MODE

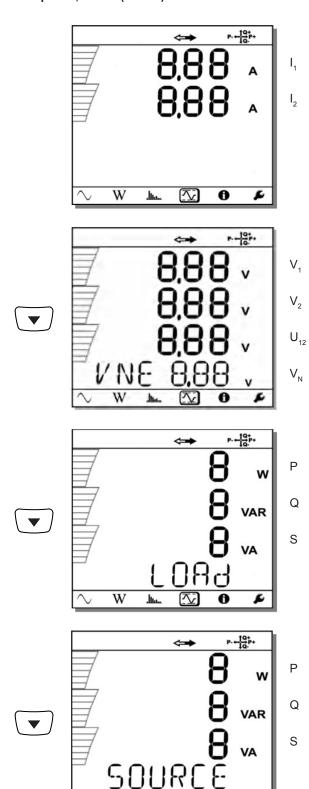
Depending on the option selected in PEL Transfer, these may be the maximum aggregated values of the recording in progress or of the last record, or the maximum aggregated values since the last reset.

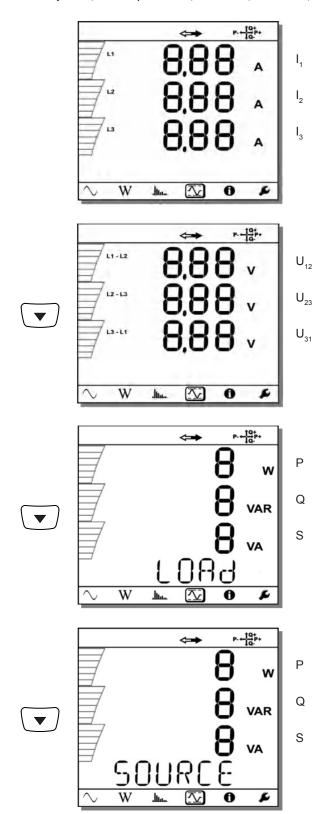
The maximum display is not available for DC networks. The display unit indicates "No Max in DC Mode".

# Single-phase, 2-wire (1P-2W)

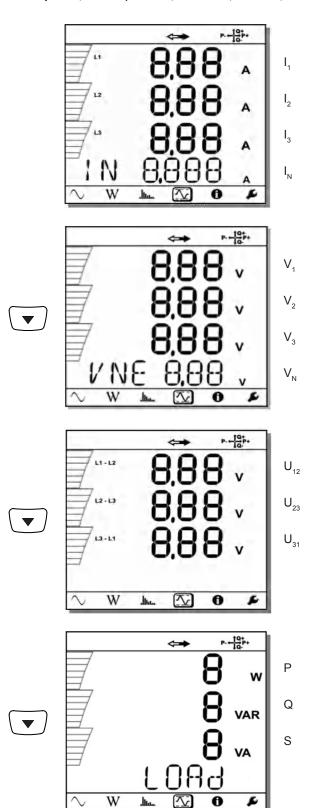


# Two-phase, 3-wire (1P-3W)

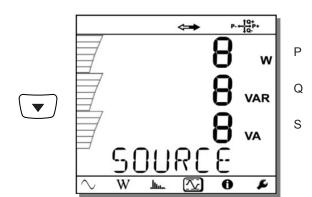




# Three-phase, 4-wire (3P-4WY, 3P-4WY2, 3P-4WA, 3P-4WOA), 3P-4WYb)



For the balanced network (3p-4WYb),  $\boldsymbol{I}_{_{\mathrm{N}}}$  is not displayed.



# 5. PEL TRANSFER SOFTWARE

# 5.1. FUNCTIONS

PEL transfer software is used to:

- Connect the instrument to the PC by Wi-Fi, Bluetooth, USB, or Ethernet.
- assign a name to the instrument, choose the brightness and contrast of the display unit, disable the Selection key of the instrument, set the date and time, format the SD card, etc.
- Configure communication between the instrument and the PC.
- Configure the measurement: choose the distribution network, the transformation ratio, the frequency, the transformation ratios
  of the current sensors.
- Configure the records: choose their names, their duration, their starting and ending dates, the aggregation period, whether or not "1s" values and harmonics are recorded.
- Manage energy meters, the operating time of the instrument, the time voltages are present on the measurement inputs, the time currents are present on the measurement inputs, etc.

PEL Transfer can also be used to open records, upload them to the PC, export them to a spreadsheet, view the corresponding curves, and create and print reports.

It is also used to update the internal software of the instrument when a new update is available.

### **5.2. INSTALLING PEL TRANSFER**

i

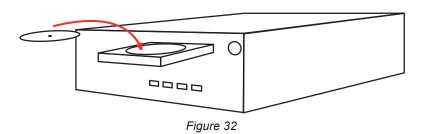
Do not connect the instrument to the PC until the software and the driver have been installed.

#### Minimum computer configuration required:

- Windows® 7 (32/64 bits) or Windows® 8
- 2GB to 4GB of RAM
- 10GB of disc space
- 1 CD-ROM drive

Windows® is a registered trade mark of Microsoft®.

1. Insert the CD provided with the instrument in your CD-ROM drive.



Go to the **PEL\_Transfer\_software** directory and run **setup.exe**. Then follow the installation instructions.

2. A warning message like the one shown below appears. Click on **OK**.

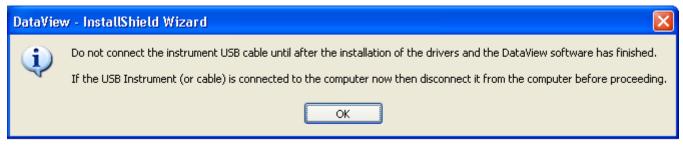


Figure 33

- Installing the driver may take some time. Windows may even indicate that the program is no longer responding, even though it is in fact running. Wait for it to terminate.
- 3. When the driver has been installed, the Installation succeeded dialogue box is displayed. Click on OK.
- 4. The Install Shield Wizard terminated window is then displayed. Click on Terminate.
- **5.** A **Question** dialogue box opens. Click on **Yes** to read the procedure for connecting the instrument to the USB port of the computer.
- The browser window remains open. You can select another option to download (for example Adobe® Reader), or user manuals to read, or close the window.
- **6.** If necessary, reboot the computer.



A shortcut has been added to your desktop.

You can now open PEL Transfer and connect your PEL to the computer.

For context-sensitive information about the use of PEL Transfer, refer to the Help menu of the software.

# 6. TECHNICAL CHARACTERISTICS

Uncertainties are expressed as a percentage (%) of the reading (R) and number of display points (pt):  $\pm$  (a%R + b pt)

# **6.1. REFERENCE CONDITIONS**

Parameter	Reference conditions
Ambient temperature	23 ± 2 °C
Relative humidity	45% RH to 75% RH
Voltage	No DC component in the AC, no AC component in the DC (< 0.1%)
Current	No DC component in the AC, no AC component in the DC (< 0.1%)
Network frequency	50Hz ± 0.1Hz and 60Hz ± 0.1Hz
Voltage-current phase difference	0° (active power) or 90° (reactive power)
Harmonics	< 0.1%
Voltage unbalance	0%
Warming up	The instrument must have been on for at least one hour.
Common mode	The instrument is powered by the battery; the USB is disconnected.
Magnetic field	0 Aac/m
Electric field	0 Vac/m

Table 6

# 6.2. ELECTRICAL CHARACTERISTICS

#### **6.2.1. VOLTAGE INPUTS**

Range of operation: up to 1,000 VRMs for phase-neutral voltages, voltages between phases, and the neutral-earth

voltage, from 42.5 to 69Hz (600 V<sub>RMS</sub> from 340 to 460Hz) and up to 600 V<sub>DC</sub>.

ightharpoonup Phase-neutral voltages below 2V and voltages between phases below  $2\sqrt{3}V$  are set to zero.

**Input impedance:** 1,908k $\Omega$  (phase-neutral and neutral-earth)

Maximum overload: 1,100 VRMS

#### **6.2.2. CURRENT INPUTS**

Range of operation:

The outputs of the current sensors are voltages.

**Input impedance:**  $1M\Omega$  (except AmpFlex® / MiniFlex® current sensors):

12.4kΩ (current sensors AmpFlex® / MiniFlex®)

0.5mV to 1.2V (1V = Inom) with a crest factor =  $\sqrt{2}$ 

Maximum overload: 1.7V

# 6.2.3. INTRINSIC UNCERTAINTY (NOT COUNTING THE CURRENT SENSORS)

The uncertainties in the tables below are given for the "1s" and aggregated values. For the "200ms" measurements, the uncertainties must be doubled

# 6.2.3.1. Specifications at 50/60Hz

Quantities	Measurement range	Intrinsic uncertainty
Frequency (f)	[42.5; 69Hz]	± 0.1Hz
Phase-neutral voltage (V)	[10V; 1,000V]	± 0.2% R ± 0.2 V
Neutral-earth voltage (V <sub>PE</sub> )	[10V; 1,000V]	± 0.2% R ± 0,2 V
Phase-phase voltage (U)	[17 V; 1,000 V]	± 0.2% R ± 0,4 V
Current (I)	[0.2% Inom; 120% Inom]	± 0.2% R ± 0.02% Inom
Neutral current (I <sub>N</sub> )	[0.2% Inom; 120% Inom]	± 0.2% R ± 0.02% Inom
Active power (P)	PF = 1 V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.5% R ± 0.005% Pnom
kW	PF = [0.5 inductive; 0.8 capacitive] V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.7% R ± 0.007% Pnom
	Sin $\varphi$ = 1 V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 1% R ± 0.01% Qnom
Reactive power (Q)	Sin $\varphi$ = [0.5 inductive; 0.5 capacitive] V = [100V; 1,000V] I = [10% Inom; 120% Inom]	± 1.5% R ± 0.01% Qnom
kvar	Sin $\varphi$ = [0,5 inductive; 0,5 capacitive] V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 1% R ± 0.01% Qnom
	Sin $\varphi$ = [0.25 inductive; 0.25 capacitive] V = [100V; 1,000V] I = [10% Inom; 120% Inom]	± 1.5% R ± 0.015% Qnom
Apparent power (S) kVA	V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.5% R ± 0.005% Snom
Power factor (PF)	PF = [0.5 inductive; 0.5 capacitive] V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.05
Fower factor (FF)	PF = [0.2 inductive; 0.2 capacitive] V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.1
ton (h	tan $\Phi = [\sqrt{3} \text{ inductive}; \sqrt{3} \text{ capacitive}]$ V = [100  V; 1,000  V] I = [5%  Inom; 120%  Inom]	± 0.02
tan Φ	tan Φ = [3.2 inductive; 3.2 capacitive V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.05
Active energy (Ep)	PF = 1 V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.5% R
kWh	PF = [0.5 inductive; 0.8 capacitive] V = [100V; 1,000V] I = [10% Inom; 120% Inom]	± 0.7 % R
	Sin φ = 1 V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 2% R
Reactive energy (Eq) kvarh	Sin $\varphi$ = [0.5 inductive; 0.5 capacitive] V = [100V; 1,000V I = [10% Inom; 120% Inom	± 2% R
	Sin φ = [0.5 inductive; 0.5 capacitive] V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 2.5% R

Quantities	Measurement range	Intrinsic uncertainty
Apparent energy (Es) kVAh	V = [100V; 1,000V] I = [5% Inom; 120% Inom]	± 0.5% R
THD %	PF = 1 V = [100V; 1,000V] I = [10 % Inom; 120% Inom]	± 1% R

Table 7

- Inom is the measured current when the output from the current sensor is 1V.
- Pnom and Snom are the active and apparent powers for V = 1,000 V, I = Inom, and PF = 1.
- Qnom is the reactive power for V = 1,000 V, I = Inom, and  $\sin \varphi = 1$ .
- The intrinsic uncertainty of the current inputs is specified for an isolated voltage input of 1V, corresponding to Inom. The intrinsic uncertainty of the current sensor used must be added to it to determine the total uncertainty of the measurement system. With the AmpFlex® and MiniFlex® current sensors, the intrinsic uncertainty given in Table 20 must be used.
- If there is no current sensor, the intrinsic uncertainty on the neutral current is the sum of the intrinsic uncertainties on I1, I2, and I3.

#### 6.2.3.2. Specifications at 400Hz

Quantities	Measurement range	Intrinsic uncertainty
Frequency (f)	[340 Hz; 460 Hz]	± 0.3 Hz
Phase-neutral voltage (V)	[5 V; 600 V]	± 0.2% R ± 0.5 V
Neutral-earth voltage (V <sub>PE</sub> )	[4 V; 600 V]	± 0.2% R ± 0.5 V
Phase-phase voltage (U)	[10 V; 600 V]	± 0.2% R ± 0.5 V
Current (I)	[0.2% Inom; 120% Inom]	± 0.5% R ± 0.05% Inom
Neutral current (I <sub>N</sub> )	[0.2% Inom; 120% Inom]	± 0.5% R ± 0.05% Inom
Active power (P)	PF = 1 V = [100V; 600 V] I = [5% Inom; 120% Inom]	±2% R ± 0.02% Pnom ¹
kW	PF = [0.5 inductive; 0.8 capacitive] V = [100V; 600 V] I = [5% Inom; 120% Inom]	±3% R ± 0.03% Pnom ¹
Active energy (Ep) kWh	PF = 1 V = [100V; 600 V] I = [5% Inom; 120% Inom]	± 2% R

Table 8

- Inom is the measured current when the output from the current sensor is 1V.
- Pnom is the active power for V = 600 V, I = Inom, and PF = 1.
- The intrinsic uncertainty of the current inputs is specified for an isolated voltage input of 1V, corresponding to Inom. The intrinsic uncertainty of the current sensor used must be added to it to determine the total uncertainty of the measurement system. With the AmpFlex® and MiniFlex® current sensors, the intrinsic uncertainty given in Table 20 must be used.
- If there is no current sensor, the intrinsic uncertainty on the neutral current is the sum of the intrinsic uncertainties on 11, 12, and 13.
- With the AmpFlex® and MiniFlex® current sensors, the maximum current is limited to 60% Inom at 50/60Hz.
- 1: Value given for guidance.

#### 6.2.3.3. Specifications in DC

Quantities	Measurement range	Typical intrinsic uncertainty
Voltage (V)	V = [100V; 600 V]	± 0.2% R ± 0.2 V
Neutral-earth voltage (V <sub>PE</sub> )	V = [2 V; 600 V]	± 0.2% R ± 0.2 V
Current (I)	I = [5% Inom; 120% Inom]	± 0.2% R ± 0.02% Inom
Neutral current (I <sub>N</sub> )	I = [5% Inom; 120% Inom]	± 0.2% R ± 0.02% Inom
Power (P) kW	V = [100 V; 1,000 V] I = [5% Inom; 120% Inom]	± 0.5% R ± 0.005% Pnom
Energy (Ep) kWh	V = [100 V; 1,000 V] I = [5% Inom; 120% Inom]	± 1.5% R

Table 9

- Inom is the measured current when the output from the current sensor is 1V.
- Pnom is the active power for V = 600 V, I = Inom
- The intrinsic uncertainty of the current inputs is specified for an isolated voltage input of 1V, corresponding to Inom. The intrinsic uncertainty of the current sensor used must be added to it to determine the total uncertainty of the measurement system.
- If there is no current sensor, the intrinsic uncertainty on the neutral current is the sum of the intrinsic uncertainties on I1, I2, and I3.

### 6.2.3.4. Temperature

For V, U, I, P, Q, S, PF and E:

- 300ppm/°C, with 5% < I < 120% and PF = 1
- 500ppm/°C, with 10% < I < 120% and PF = 0.5 inductive

#### Offset in DC

- V: 10mV/°C typical
- I: 30ppm x Inom /°C typical

#### 6.2.3.5. Common mode rejection

The common mode rejection on the neutral is 140 dB typical.

For example, a voltage of 230V applied to the neutral will add 23µV to the output of the AmpFlex® and MiniFlex® current sensors, which amounts to an error of 230mA at 50Hz. On the other current sensors, it will amount to an additional error of 0.01% Inom.

#### 6.2.3.6. Influence of the magnetic field

On current inputs to which MiniFlex® or AmpFlex® flexible current sensors are connected: 10 mA/A/m typical at 50/60Hz.

#### 6.2.4. CURRENT SENSORS

### 6.2.4.1. Precautions for use

∕N Re

Refer to the safety data sheet or user manual provided with your current sensors.

Current clamps and flexible current sensors make it possible to measure the current flowing in a cable without opening the circuit. They also isolate the user from the dangerous voltages in the circuit.

Which current sensor to use will depend on the current to be measured and the diameter of the cables.

When you install current sensors, have the arrow on the sensor point toward the load.

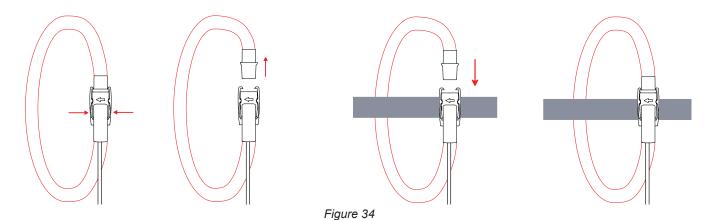
Only the AmpFlex® A196 current sensors delivered with the instrument ensure tightness (IP67 when the instrument is closed).

#### 6.2.4.2. Characteristics

The measurement ranges are those of the current sensors. These are sometimes different from those of the PEL. Refer to the user manual provided with the current sensor.

### a) AmpFlex® A196 or AmpFlex® A193

■ Press on both sides of the opening device to unlock the flexible coil. Open it, then place it around the conductor carrying the current to be measured (only one conductor per coil).



- Close the coil. You must hear it "click". For better measurement quality, centre the conductor in the coil and keep the coil as circular as possible.
- To disconnect the current sensor, open it and withdraw it from the conductor. Then disconnect the current sensor from the instrument.

AmpFlex® A196 (tight, IP67) and AmpFlex® A193		
Nominal range	100 / 400 / 2,000 / 10,000Aac	
Measurement range	0.2 to 12,000 Aac	
Maximum clamping diameter (depending on model)	A196: Length = 450mm; Ø = 190mm A193: Length = 450mm; Ø = 120 mm A193: Length = 800 mm; Ø = 235 mm	
Influence of the position of the conductor in the sensor	≤ 2 % everywhere and ≤ 4 % near of snap	
Influence of an adjacent conductor carrying an AC current	≤ 1 % everywhere and ≤ 2 % near of snap	
Safety	IEC 61010-2-032, degree of pollution 2, 1,000V CAT IV	

Table 10

**Remark:** Currents < 0.05 % of the nominal range will be set to zero.

The nominal ranges are reduced to 50/200/1,000/5,000Aac at 400Hz.

# b) MiniFlex® MA193

MiniFlex® MA193		
Nominal range	100 / 400 / 2,000 / 10,000Aac (provided that the conductor can be clamped)	
Measurement range	200mA to 2,400Aac	
Maximum clamping diameter	Length = 250 mm; Ø = 70 mm Length = 350 mm; Ø = 100 mm	
Influence of the position of the conductor in the sensor	≤ 1.5% typical, 2.5% maximum	
Influence of an adjacent conductor carrying an AC current	$\leq$ 1% for a conductor touching the sensor and $\leq$ 2% near the snap	
Safety	IEC 61010-2-032, degree of pollution 2, 600V CAT IV, 1,000V CAT III	

Table 11

**Remark:** Currents < 0.05 % of the nominal range will be set to zero.

The nominal ranges are reduced to 50/200/1,000/5,000Aac at 400Hz.

The 10,000A range operates provided that the conductor can be clamped in the MiniFlex® sensor.

# c) PAC93 clamp

**Remark:** The power calculations are set to zero while the current zero is adjusted.

PAC93 clamp		
Nominal range	1,000Aac, 1,300Adc	7
Measurement range	1 to 1,000Aac, 1 to 1,300 Apeak ac+dc	(-( )-)
Maximum clamping diameter	One 42mm conductor or two 25.4mm conductors, or two 50 x 5mm bus bars	
Influence of the position of the conductor in the clamp	< 0.5%, from DC to 440Hz	
Influence of an adjacent conductor carrying an AC current	< 10 mA/A, at 50/60Hz	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Safety	IEC 61010-2-032, degree of pollution 2, 300 V CAT IV, 600 V CAT III	

Table 12

**Remark:** Currents < 1 Aac/dc will be set to zero in AC networks.

# d) C193 clamp

C193 clamp		
Nominal range	1,000 Aac for f ≤ 10 kHz	
Measurement range	1A to 1,200Aac max (I >1,000A for 5 minutes at most)	
Maximum clamping diameter	52 mm	
Influence of the position of the conductor in the clamp	< 0.5%, from DC to 440Hz	0.000
Influence of an adjacent conductor carrying an AC current	< 10 mA/A, at 50/60Hz	
Safety	IEC 61010-2-032, degree of pollution 2, 600 V CAT IV, 1,000 V CAT III	

Table 13

Remark: Currents < 0.5A will be set to zero.

# e) PMN93 clamp

MN93 clamp		
Nominal range	200 Aac for f ≤ 10 kHz	
Measurement range	0.5 at 240Aac max (I >200A non-permanent)	
Maximum clamping diameter	20 mm	
Influence of the position of the conductor in the clamp	< 0.5%, at 50/60Hz	
Influence of an adjacent conductor carrying an AC current	≤ 15 mA/A	
Safety	IEC 61010-2-032, degree of pollution 2, 300 V CAT IV, 600 V CAT III	

Table 14

Remark: Currents < 100mA will be set to zero.

# f) MN93A clamp

MN93A clamp		
Nominal range	5A and 100Aac	
Measurement range	5A range: 0.005 to 6Aac max 100 A range: 0.2 to 120 Aac max	
Maximum clamping diameter	20 mm	
Influence of the position of the conductor in the clamp	< 0.5%, at 50/60Hz	
Influence of an adjacent conductor carrying an AC current	≤ 15 mA/A, at 50/60Hz	A
Safety	IEC 61010-2-032, degree of pollution 2, 300 V CAT IV, 600 V CAT III	

Table 15

The 5A range of MN93A clamps is suited to secondary current measurements on current transformers.

**Remark:** Currents < 2.5mA  $\times$  ratio in the 5A range and < 50mA in the 100A range will be set to zero.

# g) E3N clamp

E3N clamp		
Nominal range	10Aac/dc, 100Aac/dc	[D] m
Measurement range	100mV/A range: 0.05 o 10 Aac/bc 10 mV/A range: 0.5 o 100 Aac/bc	
Maximum clamping diameter	11.8 mm	H Ä
Influence of the position of the conductor in the clamp	< 0.5%	
Influence of an adjacent conductor carrying an AC current	-33 dB typical, from DC to 1kHz	
Safety	IEC 61010-2-032, degree of pollution 2, 300 V CAT IV, 600 V CAT III	

Table 16

Remark: Currents < 50mA will be set to zero in AC networks

# h) J93 clamps

J93 clamps						
Nominal range	3,500AAC, 5,000ADC					
Measurement range	50 - 3,500Aac; 50 - 5,000Adc					
Maximum clamping diameter	72 mm					
Influence of the position of the conductor in the clamp	< ± 2%					
Influence of an adjacent conductor carrying an AC current	> 35 dB typical, from DC to 2 kHz	) / \				
Safety	IEC 61010-2-032, degree of pollution 2, 600 V CAT IV, 1,000 V CAT III					

Table 17

Remark: Currents < 5 A will be set to zero in AC networks

# h) 5A adapter unit and Essailec®

5A adapter unit and Essailec®								
Nominal range	5Aac							
Measurement range	0.005 to 6 Aac	BILATIO C TRANSMICTOR REIL M.						
Number of inputs for transformer	3							
Safety	IEC 61010-2-032, degree of pollution 2, 300V CAT III							

Table 18

Remark: Currents < 2.5 mA will be set to zero.

# 6.2.4.3. Intrinsic uncertainty



The intrinsic uncertainties of the current measurements and of the phase must be added to the intrinsic uncertainties of the instrument for the quantity concerned: power, energies, power factors,  $\tan \Phi$ , etc.

The following characteristics are given for the reference conditions of the current sensors.

# Characteristics of the current sensors (output 1V at Inom)

Current sensor	l nominal	Current (RMS or DC)	Intrinsic uncertainty at 50/ 60Hz	Intrinsic uncertainty on φ at 50/60 Hz	Typical uncertainty on φ at 50/60Hz	Typical uncertainty on φ at 400 Hz
		[1A; 50A[	± 1.5% R ± 1 A	-	-	
PAC193 clamps		[50 A; 100 A[	± 1.5% R ± 1 A	± 2.5°	-0.9°	
	1,000 Aac 1,300Adc	[100 A; 800 A[	± 2.5% R		- 0.8°	
	1,300ADC	[800 A; 1,000 A[	± 4% R	± 2°	- 0.65°	- 4.5°@ 100A
		]1,000 Apc; 1,300 Apc[	± 4% R		- 0.65°	
		[1 A; 50 A[	± 1% R	-	-	
C193 clamps	1,000 Aac	[50 A; 100 A[	± 0.5% R	± 1°	+ 0.25°	+ 0.1°@ 1,000A
		[100 A; 1,200 A[	± 0.3% R	± 0.7°	+ 0.2°	1+0.1 @ 1,000A
	200 Aac	[0.5 A; 5 A[	± 3% R ± 1 A	-	-	-
MN93 clamps		[5 A; 40 A[	± 2.5% R ± 1 A	± 5°	+ 2°	- 1.5°@ 40 A
		[40 A; 100 A[	± 2% R ± 1 A	± 3°	+ 1.2°	- 0.8°@ 100A
		[100 A; 240 A[	± 1% R + 1A	± 2.5°	± 0.8°	- 1°@ 200 A
	100 <b>A</b> ac	[200 mA; 5 A[	± 1% R ± 2 mA	± 4°	-	-
MN93A		[5 A; 120 A[	± 1% R	± 2.5°	+ 0.75°	- 0.5°@100A
clamps	<b>5</b> A	[5 mA; 250 mA[	± 1.5% R ± 0.1 mA	-	-	-
	5 Aac	[250 mA; 6 A[	± 1% R	± 5°	+ 1.7°	- 0.5°@ 5 A
	100Aac/dc	[50 mA; 40 A[	± 4% R ± 50 mA	± 1°	-	-
E3N clamps	TOUAAC/DC	[40 A; 100 A[	± 15% R	± 1°	-	-
	10 Aac/dc	[50 mA; 10 A[	± 3% R ± 50 mA	± 1.5°	-	-
		[50 A; 250 A[	± 2% R ± 2.5 A	± 3°	-	-
J93	3,500 <b>A</b> ac	[250 A; 500 A[	± 1.5% R ± 2.5 A	± 2°	-	-
clamps	5,000 ADC	[500 A; 3,500 A[	± 1% R	± 1.5°	-	-
		]3,500 Adc; 5,000 Adc[	± 1% R	-	-	-
Adapter	5 Aac	[5 mA; 250 mA[	± 0.5% R ± 2 mA	± 0.5°		
5A/ Essailec®	5 AAC	[250 mA; 6 A[	± 0.5% R ± 1 mA	± 0.5°		-

Table 19

# Characteristics of the AmpFlex® and Min/Flex®

Current sensor	I nominal	Current (RMS or DC)	Intrinsic uncertainty at 50/ 60Hz	Intrinsic uncertainty at 400Hz	Intrinsic uncertainty on φ at 50/60 Hz	Typical uncer- tainty on φ at 400 Hz	
	100 Aac	[200 mA; 5 A[	± 1.2% R ± 50mA	± 2 % R ± 0.1 A	-	-	
	100 AAC	[5 A; 120 A[ *	1 1.270 K 1 30IIIA	12 % N 1 0.1A	± 0.5°	- 0.5°	
AmpFlex®	400 4.0	[0.8 A; 20 A[	± 1.2% R ± 0.2 A	± 2 % R ± 0.4 A	-	-	
A196	1 4UU AAC	[20 A; 500 A[ *	± 1.2% R ± 0.2 A	± 2 % R ± 0.4 A	± 0.5°	- 0.5°	
AmpFlex®	2.000 4.0	[4 A; 100 A[	± 1.2 % R ± 1 A	± 2 % R ± 2 A	-	-	
A193	2,000 Aac	[100 A; 2,400 A[ *	±1.2 % K±1A	±2%R±2A	± 0.5°	- 0.5°	
Γ	40 000 A	[20 A; 500 A[	. 4 0 0/ D . 5 4	± 2% R ± 10A	-	-	
	10,000 Aac	[500 A; 12,000 A[ *	± 1.2 % R ± 5 A	± 2% R ± 10A	± 0.5°	- 0.5°	
	400 A	[200 mA; 5 A[	± 1 % R ± 50mA	± 2 % R ± 0.1 A	-	-	
	100 <b>A</b> AC	[5 A; 120 A[ *	± 1 % K ± 50IIIA	±2% K±0.1A	± 0.5°	- 0.5°	
	400 Aac	[0.8 A; 20 A[	±1%R±0.2A	± 2 % R ± 0.4 A	-	-	
MiniFlex®	400 AAC	[20 A; 500 A[ *	±1%R±0.2A	± 2 % R ± 0.4 A	± 0.5°	- 0.5°	
MA193	2 000 0 0	[4 A; 100 A[	±1%R±1A	±2%R±2A	-	-	
	2,000 Aac	[100 A; 2,400 A[ *	±1%R±1A	±2%R±2A	± 0.5°	- 0.5°	
	10.0004.01	[20 A; 500 A[	±1%R±1A	± 2 % R ± 2 A	-	-	
	10,000 <b>A</b> ac <sup>1</sup>	[500 A; 12,000 A[ *	±1%K±1A	IZ % R IZA	± 0.5°	- 0.5°	

Table 20

# 6.3. COMMUNICATION

### 6.3.1. WI-FI

2.4 GHz band, IEEE 802.11 B/G/N radio

TX power: +17 dBm RX sensitivity: -97 dBm Rate: 72.2 MB/s max Safety: WPA / WPA2

Access Point (AP): up to five clients

### 6.3.2. BLUETOOTH

Bluetooth 2.1

Class 1 (range up to 100m in line of sight)

Default pairing code: 000 Nominal output power: +15 dBm Nominal sensitivity: -82 dBm

Rate: 115.2 kbits/s

# 6.3.3. USB

Type B connector USB 2

### **6.3.4. NETWORK**

RJ45 connector with 2 built-in LEDs 100 Base T Ethernet

<sup>\*:</sup> The nominal ranges are halved at 400Hz.

<sup>1:</sup> Provided that the conductor can be clamped.

### 6.4. POWER SUPPLY

#### Mains supply

■ Range of operation: 100V to 1,000V for a frequency from 42.5 to 69Hz

100V to 600 V for a frequency from 340 to 460 Hz

140V to 1,000V in DC

■ Maximum power: 30VA

#### **Battery**

■ Type: Rechargeable NiMH battery

■ Number of charging/discharging cycles: > 1,000

Charging time: Approximately 5h
 Charging temperature: -20 to +55 °C

■ Life between charges: approximately 1h with neither Bluetooth nor Wi-Fi activated

i

When the instrument is powered down, the clock is preserved for 20 days.

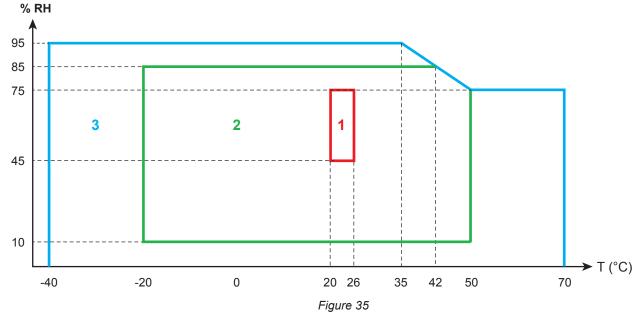
### 6.5. ENVIRONMENTAL CHARACTERISTICS

■ Indoor and outdoor use.

■ Altitude:

Operation: 0 to 2,000 mStorage: 0 to 10,000 m

■ Temperature and relative humidity:



1 = Reference range 1 + 2 = Operation range 1 + 2 + 3 = Storage range

# 6.6. MECHANICAL CHARACTERISTICS

■ **Dimensions:** 270 (+50mm with the leads connected) × 245 × 180mm

■ Weight: approximately 3.4kg

■ **Drop:** 20cm in the worst position without permanent mechanical damage or functional deterioration. 1m in its packaging.

#### ■ Degrees of protection per IEC 60529

- IP 67 when the cover of the instrument is closed, the voltage leads are screwed, and the leads of the AmpFlex® A196 are screwed.
- IP 67 when the cover of the instrument is closed and the plugs on the terminals are in place.
- IP 54 when the cover is open, the instrument is in a horizontal position, and the plugs on the terminals are in place.
- IP 40 when the cover is open, the instrument is in a horizontal position, and the plugs are not in place.

#### 6.7. ELECTRICAL SAFETY

The instruments are compliant with standards IEC 61010-1 and IEC 61010-2-30:

Measurement inputs and enclosure: 1,000V CAT IV, degree of pollution 3 (4 with instrument closed)

The current sensors are compliant with standard IEC 61010-2-032.

The measurement leads and the crocodile clips are compliant with standard IEC 61010-031

### 6.8. ELECTROMAGNETIC COMPATIBILITY

Emissions and immunity in an industrial environment per IEC 61326-1.

With the AmpFlex® and the MiniFlex®, the typical influence on the measurement is 0.5% of full scale, with a maximum of 5A.

### 6.9. MEMORY CARD

The PEL accepts FAT32-formatted SD and SDHC cards up to a capacity of 32GB.

Number of insertions and withdrawals: 1,000.

The transfer of a large quantity of data may take a long time. Moreover, some computers may have difficulty processing such large quantities of information, and spread sheets accept only a limited quantity of data.

We recommend optimizing the data on the SD card and recording only the necessary measurements. For guidance, a 5-day record, with an aggregation time of 15 minutes, a record of the "1s" data and the harmonics on a three-phase four-wire network occupies approximately 530MB. If the harmonics are not essential and if recording of them is deactivated, the size is reduced to approximately 67MB.

The maximum durations of records for a 2GB card are the following:

- 19 days for recording with an aggregation time of 1 minute, the "1s" data, and the harmonics;
- 12 weeks for recording with an aggregation time of 1 minute, the "1s" data, but no harmonics;
- 2 years for recording with an aggregation time of 1 minute.

Do not exceed 32 records on the SD card.

For records that are long (duration greater than one week) or include the harmonics, use class 4 or higher SDHC cards.

Do not use the Bluetooth link to upload large records: it would take too long. If only one record per Bluetooth link is possible, shrink the record by removing the "1s" data and the harmonics. Without these last, a 30-day record occupies only 2.5MB.

On the other hand, uploading by USB or Ethernet link can be acceptable, depending on the length of the record and the transmission rate. To transfer the data more rapidly, use the SD card/USB adapter.

# 7. MAINTENANCE



Except for the attachments of the tight connectors and the caps of the terminals, the instrument contains no parts that can be replaced by personnel who are not specially trained and accredited. Any unauthorized repair or replacement of a part by an "equivalent" may gravely impair safety.

Regularly check the condition of the O-rings in the leads. If they fail, tightness is no longer ensured.

#### 7.1. CLEANING



### Disconnect the instrument completely.

Use a soft cloth, dampened with soapy water. Rinse with a damp cloth and dry rapidly with a dry cloth or forced air. Do not use alcohol, solvents, or hydrocarbons.

Do not use the instrument if the terminals or the keypad are wet. Dry it first.

For the current sensors:

- Make sure that no foreign body interferes with the operation of the snap locking device of the current sensor.
- Keep the jaws of the clamp perfectly clean. Do not spray water directly on the clamp.

# 7.2. BATTERY

The instrument uses a NiMH battery. This technology has several advantages:

- Long life between charges but compact and light;
- Memory effect substantially reduced: you can recharge your battery even if it is not fully discharged;
- Protection of the environment: no pollutants such as lead or cadmium, in accordance with the applicable regulations.

The battery may be fully discharged after prolonged storage. In this case, charging may take several hours. It will then take at least 5 charging/discharging cycles for the battery to recover 95% of its capacity.

To optimize the use of your battery and prolong its useful life:

- Charge the instrument only at temperatures between -20 and +55°C.
- Use as prescribed.
- Store as prescribed.

#### 7.3. UPDATING THE EMBEDDED SOFTWARE

With a view to providing, at all times, the best possible service in terms of performance and technical improvements, Chauvin Arnoux offers you the possibility of updating the internal software of this instrument by downloading, free of charge, the new version available on our web site.

See you on our site:

www.chauvin-arnoux.com

Then go to "Support", then "Download our software", then "PEL 105".

Connect the instrument to your PC using the USB cord provided.

The PEL Transfer software informs you when an update is available and makes it easy to install it.



Updating the embedded software may reset the configuration and cause the loss of the recorded data. As a precaution, save the data in memory to a PC before updating the embedded software.

# 8. WARRANTY

Except as otherwise stated, our warranty is valid for **twelve months** starting from the date on which the equipment was sold. Extract from our General Conditions of Sale provided on request.

The warranty does not apply in the following cases:

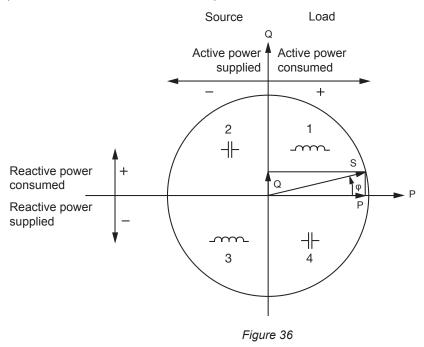
- Inappropriate use of the equipment or use with incompatible equipment;
- Modifications made to the equipment without the explicit permission of the manufacturer's technical staff;
- Work done on the device by a person not approved by the manufacturer;
- Adaptation to a particular application not anticipated in the definition of the equipment or not indicated in the user's manual;
- Damage caused by shocks, falls, or floods.

#### 9.1. MEASUREMENTS

#### 9.1.1. DEFINITION

The calculations are performed in accordance with standards IEC 61557-12, IEC 61000-4-30, and IEEE 1459.

Geometrical representation of the active and reactive powers:



The quadrants are given for the fundamental power values.

The reference of this diagram is the current vector (fixed on the right-hand part of the axis).

Voltage vector V varies in direction according to phase angle  $\varphi$ .

The phase angle  $\varphi$ , between the voltage V and the current I, is considered positive in the anticlockwise direction.

#### 9.1.2. SAMPLING

#### 9.1.2.1. Sampling period

This depends on the network frequency: 50, 60 or 400Hz.

The sampling period is calculated every second.

- Network frequency f = 50Hz
  - Between 42.5 and 57.5Hz (50Hz ± 15%), the sampling period is locked to the network frequency. 128 samples are available for each period of the network.
  - Outside of the 51–69Hz band, the sampling period is 128 x 50 Hz.
- Network frequency f = 60 Hz
  - Between 51 and 69 Hz (60 Hz ± 15%), the sampling period is locked to the network frequency. 128 samples are available for each period of the network.
  - Outside of the 51–69Hz band, the sampling period is 128 x 60Hz.
- Network frequency f = 400 Hz
  - Between 340 and 460 Hz (400 Hz ± 15%), the sampling period is locked to the network frequency. 16 samples are available for each period of the network.
  - Outside of the 340–460Hz band, the sampling period is 16 x 400Hz.

A DC signal is treated as outside of the frequency ranges. The sampling frequency is then, depending on the preset network frequency, 6.4 kHz (50/400Hz) or 7.68 kHz (60Hz).

#### 9.1.2.2. Locking of the sampling frequency

- As default, the sampling frequency is locked to V1.
- If V1 is missing, the instrument attempts to lock to V2, then to V3, I1, I2, and I3.

#### 9.1.2.3. AC/DC

The PEL makes AC and DC measurements for AC and DC distribution networks. AC or DC is selected by the user.

The AC + DC values are available with PEL Transfer.

#### 9.1.2.4. Neutral current measurement

Depending on the distribution network, if there is no current sensor on the  $I_N$  terminal, the neutral current is determined by calculation.

#### 9.1.2.5. "200ms" quantities

The instrument calculates the following quantities every 200 ms on the basis of measurements on 10 periods for 50Hz, 12 periods for 60Hz, and 80 periods for 400Hz, as indicated by Table 21.

The "200ms" quantities are used for:

- the trends on the "1s" quantities
- the aggregation of the values for the "1s" quantities (See § 9.1.2.6).

All of the "200ms" quantities can be recorded on the SD card during the recording session.

#### 9.1.2.6. "1 s" quantities (one second)

The instrument calculates the following quantities every 200 ms on the basis of measurements on 50 periods for 50Hz, 60 periods for 60Hz, and 400 periods for 400Hz, as indicated by Table 21.

The "1s" quantities are used for:

- the real-time values
- the trends
- the aggregation of the values for the "aggregated" quantities (See § 9.1.2.7).
- the determination of the values and maximum/minimum for the values of the "aggregated" trends

All of the "1s" quantities can be recorded on the SD card during the recording session.

#### 9.1.2.7. Aggregation

An aggregated quantity is a value calculated over an aggregation period as indicated by Table 22.

The aggregation period always starts at the beginning of an hour or of a minute. The aggregation period is the same for all quantities. The possible periods are the following: 1, 2, 3, 4, 5, 6, 10, 12, 15, 20, 30 and 60 min.

All aggregated quantities are recorded on the SD card during the recording session. They can be displayed in PEL Transfer (See § 5).

# 9.1.2.8. Minimum and maximum

The Min and Max are the minimum and maximum values observed during the aggregation period considered. They are recorded with their dates and times (see Table 22). The Max of some aggregated values are displayed directly on the instrument.

#### 9.1.2.9. Energy calculations

The energies are calculated every second.

The total energy is the demand during the recording session.

The partial energy can be determined for one of the following integration periods: 1h, 1 day, 1 week or 1 month. The partial energy index is available only in real time. It is not recorded.

On the other hand, the total energies are available with the data of the recorded session.

# 9.2. MEASUREMENT FORMULAS

Most of the formulas are taken from standard IEEE 1459.

The PEL measures or calculates the values below for one cycle (128 samples per period from 16 to 400Hz. These values are not accessible to the user.

The PEL then calculates a value aggregated over 10 cycles (50Hz), 12 cycles (60Hz), or 80 cycles (400Hz) ("200ms" quantities ), then 50 cycles (50Hz), 60 cycles (60Hz), or 400 cycles (400Hz) ("1s" quantities).

Quantities	Formulas	Remarks
	AC measurements	
Crest factor in AC voltage (V <sub>L-CF</sub> )	$V_{L-CF}[T] = \frac{\frac{1}{n} \times \sum_{x=1}^{n} V_{L-peak_x}}{V_L}$	L = 1, 2 or 3
AC inverse voltage unbalance (u <sub>2</sub> )	$u_2 = 100 \times \frac{V^-}{V^+}$	*
AC homopolar voltage unbalance $(u_0)$	$u_0 = 100 \times \frac{V^0}{V^+}$	*
Crest factor of the current $(I_{L-CF})$	$I_{L-CF}[T] = \frac{\frac{1}{n} \times \sum_{x=1}^{n} I_{L-peak_x}}{I_L}$	L = 1, 2 or 3
AC inverse current unbalance (i <sub>2</sub> )	$i_2 = 100 \times \frac{I^-}{I^+}$	*
AC homopolar current unbalance $(i_0)$	$i_0 = 100 \times \frac{I^0}{I^+}$	*
AC reactive power (Q <sub>L</sub> )	$Q_{L} = V_{L-H1} \times I_{L-H1} \times \sin \varphi (I_{L-H1}, V_{L-H1})$ $Q_{T} = Q_{1} + Q_{2} + Q_{3}$	L = 1, 2 or 3
AC apparent power (S <sub>L</sub> )	$S_L = V_L \times I_L$ $S_T = S_1 + S_2 + S_3$	L = 1, 2 or 3
$ \begin{array}{c} \text{Fundamental angles} \\ \phi \left( \textbf{I}_{\textbf{L}}, \textbf{V}_{\textbf{L}} \right) \\ \phi \left( \textbf{I}_{\textbf{L}}, \textbf{I}_{\textbf{M}} \right) \\ \phi \left( \textbf{I}_{\textbf{M}}, \textbf{V}_{\textbf{M}} \right) \end{array} $	FFT calculation	$\phi$ is the phase difference between the fundamental current ${\rm I_L}$ and the fundamental voltage ${\rm V_L}$
AC non-active power (N <sub>L</sub> )	$N_L = \sqrt{{S_L}^2 - {P_L}^2}$	L = 1, 2, 3 or T
AC deforming power (D <sub>L</sub> )	$D_L = \sqrt{N_L^2 - Q_L^2}$	L = 1, 2, 3 or T
Quadrant (q)	The quadrants are defined as follows:  ■ when Pf <sub>L</sub> [10/12] > 0 and Q <sub>L</sub> [10/12] > 0: quadrant 1  ■ when Pf <sub>L</sub> [10/12] < 0 and Q <sub>L</sub> [10/12] > 0: quadrant 2  ■ when Pf <sub>L</sub> [10/12] < 0 and Q <sub>L</sub> [10/12] < 0: quadrant 3  ■ when Pf <sub>L</sub> [10/12] > 0 and Q <sub>L</sub> [10/12] < 0: quadrant 4	
AC fundamental active power (Pf <sub>L</sub> )	$Pf_{L} = V_{L-H1} \times I_{L-H1} \times \cos \varphi (I_{L-H1}, V_{L-H1})$ $Pf_{T} = Pf_{1} + Pf_{2} + Pf_{3}$	L = 1, 2 or 3
AC fundamental direct active power (P+)	$P^{+} = 3 \times V^{+} \times I^{+} \times \cos \theta \left(I^{+}, V^{+}\right)$	

Quantities	Formulas	Remarks
AC fundamental apparent power (Sf <sub>L</sub> )	$Sf_{L} = V_{L-H1} \times I_{L-H1}$ $Sf_{T} = Sf_{1} + Sf_{2} + Sf_{3}$	L = 1, 2 or 3
AC power factor (PF <sub>L</sub> )	$PF_L = \frac{P_L}{S_L}$	L = 1, 2 or 3
AC active power unbalance (Pu)	$P_U = Pf_T - P^+$	
AC harmonic active powers (P <sub>H</sub> )	$P_H = P_T - Pf_T$	
DPF <sub>L</sub> / Cos φ <sub>L</sub> AC	$DPF_L = \cos \phi_L = \cos \phi \; (I_{L-H1}, V_{L-H1})$ $\cos \phi_T = \frac{Pf_T}{Sf_T}$	L = 1, 2 or 3
Tan Φ AC	$Tan\Phi = rac{Q_T}{P_T}$	
	DC measurements	
DC voltage (V <sub>Ldc</sub> )	$V_{Ld.c.}[T] = \frac{1}{n} \times \sum_{x=1}^{n} V_{Ld.c.x}$	L = 1, 2, 3 or E
DC current (I <sub>Ldc</sub> )	$I_{Ld.c.}[T] = \frac{1}{n} \times \sum_{x=1}^{n} I_{Ld.c.x}$ When there is no current sensor on $I_{\rm N}$ , $I_{\rm N}$ is calculated: $I_{\rm Ndc} = I_{\rm 1dc} + I_{\rm 2dc} + I_{\rm 3dc}$	L = 1, 2, 3 or N
	Energy measurements	
AC consumed active energy (E <sub>P+</sub> )	$E_{P+} = \sum P_{T+x}$	
AC generated active energy (E <sub>p.</sub> )	$E_{P-} = (-1) \times \sum P_{T-x}$	
AC reactive energy in quadrant 1 ( $E_{q_1}$ )	$E_{Q1} = \sum Q_{Tq1_x}$	
AC reactive energy in quadrant $2 (E_{Q2})$	$E_{\mathcal{Q}2} = \sum \mathcal{Q}_{T_{\mathcal{Q}2_x}}$	
AC reactive energy in quadrant 3 ( $E_{Q3}$ )	$E_{\mathcal{Q}3} = (-1) \times \sum_{q_{q_{3_x}}} Q_{T_{q_{3_x}}}$	
AC reactive energy in quadrant 4 $(E_{_{\mathrm{Q4}}})$	$E_{Q4} = (-1) \times \sum Q_{T_{q4_x}}$	
AC consumed apparent energy $(E_{s+})$	$E_{S+} = \sum S_{T+x}$	
AC generated apparent energy (E <sub>s</sub> .)	$E_{S-} = \sum S_{T-x}$	
DC consumed energy (E <sub>Pdc+</sub> )	$E_{P_{dc^+}} = \sum P_{Tdc_{+x}}$	
DC consumed energy (E <sub>Pdc</sub> .)	$E_{P_{dc^-}} = (-1) \times \sum P_{Tdc_{-x}}$	

Table 21

T is the period

n is the number of samples.

The lower-case v1, v2, v3 designate the sampled values.

U1, U2, U3 are the voltages between phases of the installation measured.

Lower-case designates the sampled values [u12 = v1-v2; u23= v2-v3; u31=v3-v1].

<sup>\*:</sup> The direct, inverse, and homopolar voltages and currents (V<sup>+</sup>, I<sup>+</sup>, V<sup>-</sup>, I<sup>-</sup>, V°, I°) are calculated using the Fortescue transform. V1, V2, V3 are the phase-neutral voltages of the installation measured. [V1=VL1-N; V2=VL2-N; V3=VL3-N].

I1, I2, I3 are the currents flowing in the phase conductors of the installation measured.  $\rm I_{N}$  is the current flowing in the neutral conductor of the installation measured. The lower-case i1, i2, i3 designate the sampled values.

For some quantities linked to the powers, the "generated" and "consumed" quantities are counted separately for the values aggregated from the "1s" values.

Quantities	Formulas	Remarks
	AC measurements	
AC consumed active power (P <sub>L+</sub> )	$P_{L+} = \frac{1}{n} \times \sum_{x=1}^{n} P_{L+x}$	L = 1, 2, 3 or T
AC generated active power (P <sub>L</sub> )	$P_{L-} = (-1) \times \frac{1}{n} \times \sum_{x=1}^{n} P_{L-x}$	P <sub>L</sub> > 0 L = 1, 2, 3 or T
AC consumed reactive power $(Q_{L_*})$	$Q_{L+} = \frac{1}{n} \times \sum_{x=1}^{n} Q_{L+x}$	$Q_{L_{+}}$ can be > 0 or < 0 $Q_{L_{+}}[agg] = Q_{L_{1}}[agg] - Q_{L_{4}}[agg]$ L = 1, 2, 3 or T
AC generated active power (Q <sub>L</sub> )	$Q_{L-} = (-1) \times \frac{1}{n} \times \sum_{x=1}^{n} Q_{L-x}$	$Q_{L}$ can be > 0 or < 0 $Q_{L}[agg] = -Q_{L}[agg] + Q_{L}[agg]$ L = 1, 2, 3 or T
AC consumed apparent power $(S_{L})$	$S_{L+} = \frac{1}{n} \times \sum_{x=1}^{n} S_{L+x}$	$S_{L+}$ is used for the calculation $PF_{L+}$ and of $E_{L+}$ . L = 1, 2, 3  or  T
AC generated apparent power (S <sub>L</sub> )	$S_{L-} = \frac{1}{n} \times \sum_{x=1}^{n} S_{L-x}$	$S_{L}$ is used for the calculation $PF_{L}$ and of $E_{L}$ . L = 1, 2, 3  or  T
AC consumed fundamental active power (Pf <sub>L+</sub> )	$Pf_{L+} = \frac{1}{n} \times \sum_{x=1}^{n} Pf_{L+x}$ $Pf_{T+} = Pf_{1+} + Pf_{2+} + Pf_{3+}$	L = 1, 2 or 3
AC generated fundamental active power (Pf <sub>L</sub> )	$Pf_{L-} = \frac{1}{n} \times \sum_{x=1}^{n} Pf_{L-x}$	L = 1, 2, 3 or T
AC consumed fundamental apparent power (Sf <sub>L+</sub> )	$Sf_{L+} = \frac{1}{n} \times \sum_{x=1}^{n} Sf_{L+x}$	L = 1, 2, 3 or T
AC generated fundamental apparent power (Sf <sub>L</sub> )	$Sf_{L-} = \frac{1}{n} \times \sum_{x=1}^{n} Sf_{L-x}$ $Sf_{T-} = Sf_{1-} + Sf_{2-} + Sf_{3-}$	L = 1, 2 or 3
AC consumed power factor (PF <sub>L+</sub> )	$PF_{L+} = \frac{P_{L+}}{S_{L+}}$	L = 1, 2, 3 or T
AC generated power factor (PF <sub>L</sub> )	$PF_{L-} = \frac{P_{L-}}{S_{L-}}$	PF <sub>L</sub> > 0 L = 1, 2, 3 or T
Cos $\phi_L$ AC consumed (Cos $\phi_{L^4}$ )	$Cos \varphi_{L+} = \frac{Pf_{L+}}{Sf_{L+}}$	L = 1, 2, 3 or T
Cos $\phi_L$ AC on the source (Cos $\phi_L$ )	$Cos \varphi_{I_{-}} = \frac{Pf_{L_{-}}}{T}$	Cos φ <sub>L</sub> > 0 L = 1, 2, 3 or T
Tan $\Phi$ AC on the load ( $\Phi$ +)	$Tan\Phi_{+} = \frac{Q_{T+}}{P_{T+}}$	

Quantities	Formulas	Remarks						
AC generated Tan $\Phi$ ( $\Phi$ -)	$Tan\Phi_{-} = \frac{Q_{T-}}{P_{T-}}$							
DC measurements								
DC consumed active power (P <sub>L+dc</sub> )	$P_{L+d.c.} = \frac{1}{n} \times \sum_{x=1}^{n} P_{L+d.c.x}$	L = 1, 2, 3 or T						
DC generated active power (P <sub>L-dc</sub> )	$P_{L-d.c.} = (-1) \times \frac{1}{n} \times \sum_{x=1}^{n} P_{L-d.c.x}$	L = 1, 2, 3 or T						
	AC+DC measurements							
	$P_{L+a.c.+d.c.} = P_{L+} + P_{L+d.c.}$	L = 1, 2, 3 or T						
AC+DC generated active power (P $_{\rm L}$ $_{\rm -ac+dc}$ )	$P_{L-a.c.+d.c.} = P_{L-} + P_{L-d.c.}$	L = 1, 2, 3 or T						
AC+DC consumed apparent power $(S_{L+ac+dc})$	$S_{L+a.c.+d.c.} = \frac{1}{n} \times \sum_{x=1}^{n} S_{L+a.c.+d.cx}$	L = 1, 2, 3 or T						
	$S_{L-a.c.+d.c.} = \frac{1}{n} \times \sum_{x=1}^{n} S_{L-a.c.+d.c.x}$	L = 1, 2, 3 or T						

Table 22

<sup>+ =</sup> load

<sup>- =</sup> source

q = quadrant = 1, 2, 3 or 4

# 9.3. ELECTRICAL NETWORKS ALLOWED

The following types of distribution network are managed:

Distribution network	Abbreviation	Phase order	Remarks	Reference diagram
Single-phase (single-phase 2-wire)	1P- 2W	No	The voltage is measured between L1 and N. The current is measured on the L1 conductor.	See § 4.1.1.
Two-phase (split-phase single-phase 3-wire)	1P-3W	No	The voltage is measured between L1, L2 and N. The current is measured on the L1 and L2 conductors. The neutral current is calculated: $i_N = i_1 + i_2$	See § 4.1.2.
Three-phase, 3-wire ∆ [2 current sensors]	3P-3W∆2		The power measurement method is based on the two-	See § 4.1.3.1.
Three-phase, 3-wire open ∆ (2 current sen- sors)	3P-3WO2	Yes	wattmeter method with a virtual neutral.  The voltage is measured between L1, L2 and L3.  The current is measured on the L1 and L3 conductors. The current I₂ is calculated (no current sensor on L2): i₂ = -i₁ -i₃  The neutral is not available for the measurement of the	See § 4.1.3.3.
Three-phase 3-wire wye [2 current sensors]	3P-3WY2		current and of the voltage	See § 4.1.3.5.
Three-phase, 3-wire ∆ (3 current sensors)	3P-3W∆3		The power measurement is based on the three-wattmeter	See § 4.1.3.2.
Three-phase, 3-wire open Δ (3 current sensors)	3P-3WO3	Yes	method with a virtual neutral.  The voltage is measured between L1, L2 and L3.  The current is measured on the L1, L2 and L3 conductors.  The neutral is not available for the measurement of the	See § 4.1.3.4.
Three-phase, 3-wire, wye [3 current sensors]	3P-3WY3		current and of the voltage	See § 4.1.3.6.
Three-phase, 3-wire ∆, balanced	3P-3W∆B	No	The power measurement is based on the one-wattmeter method.  The voltage is measured between L1 and L2.  The current is measured on the L3 conductor. $U_{23} = U_{31} = U_{12}$ . $I_1 = I_2 = I_3$	See § 4.1.3.7.
Three-phase 4-wire wye	3P-4WY	Yes	The power measurement is based on the three-wattmeter method with neutral. The voltage is measured between L1, L2 and L3. The current is measured on the L1, L2 and L3 conductors. The neutral current is calculated: $i_N = i_1 + i_2 + i_3$ .	See § 4.1.4.1.
Three-phase, 4-wire, wye, balanced	3P-4WYB	No	The power measurement is based on the one-wattmeter method. The voltage is measured between L1 and N. The current is measured on the L1 conductor. $V_1 = V_2 = V_3$ $U_{23} = U_{31} = U_{12} = V_1 \times \sqrt{3}.$ $I_1 = I_2 = I_3$ $I_N = 3 \times I_1$	See § 4.1.4.2.
Three-phase, 3-wire, wye 2½	3P-4WY2	Yes	This method is called the $2\frac{1}{2}$ -element method The power measurement is based on the three-wattmeter method with a virtual neutral. The voltage is measured between L1, L3 and N. V2 is calculated: $v_2 = -v_1 - v_3$ , $u1_2 = 2v_1 + v_3$ , $u_{23} = -v_1 - 2v_3$ . $V_2$ is assumed to be balanced. The current is measured on the L1, L2 and L3 conductors. The neutral current is calculated: $i_N = i_1 + i_2 + i_3$ .	See § 4.1.4.3.

Distribution network	Abbreviation	Phase order	Remarks	Reference diagram
Three-phase, 4-wire $\Delta$	3P-4W∆	No	The current is measured on the L1, L2 and L3 conductors.	
Three-phase, 4-wire, open $\Delta$	3P-4WO∆		The neutral current is calculated for only one branch of the transformer: $i_N = i_1 + i_2 + i_3$ .	See § 4.1.5.2.
DC 2-wire	DC-2W	No	The voltage is measured between L1 and N. The current is measured on the L1 conductor.	See § 4.1.6.1.
DC 3-wire	DC-3W	No	The voltage is measured between L1, L2 and N.	
DC 4-wire	DC-4W	No	The voltage is measured between L1, L2, L3 and N. The current is measured on the L1, L2 and L3 conductors. The negative (return) current is calculated: $i_N = i_1 + i_2 + i_3$ .	See § 4.1.6.3.

# 9.4. QUANTITY ACCORDING TO THE DISTRIBUTION NETWORK

•	= Yes		= No
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Quant	ities	1P-2W	1P-3W	3P-3W∆2 3P-3WO2 3P-3WY2	3P-3W∆3 3P-3WO3 3P-3WY3	3P-3W∆B	3P-4WY	3P-4WYB	3P-4WY2	3P-4W∆ 3P-4WO∆	DC-2W	DC-3W	DC-4W
$V_{1}$	AC RMS	•	•				•	•	•	•			
V <sub>2</sub>	AC RMS		•				•	● = V <sub>1</sub>	•(10)	•			
V <sub>3</sub>	AC RMS						•	● = V <sub>1</sub>	•	•			
V <sub>NE</sub>	AC RMS	•	•				•	•	•	•			
V <sub>1</sub>	DC										•	•	•
V <sub>2</sub>	DC											•	•
$V_3$	DC												•
$V_{NE}$	DC	•	•				•	•	•	•	•	•	•
$V_1$	AC + DC RMS	•	•				•	•	•	•			
$V_2$	AC + DC RMS		•				•	•(1)	•(10)	•			
V <sub>3</sub>	AC + DC RMS						•	•(1)	•	•			
$V_{_{\rm NE}}$	AC + DC RMS	•	•				•	•	•	•			
U <sub>12</sub>	AC RMS		•	•	•	•	•	•(1)	•(10)	•			
U <sub>23</sub>	AC RMS			•	•	•(1)	•	•(1)	•(10)	•			
U <sub>31</sub>	AC RMS			•	•	•(1)	•	•(1)	•	•			
I <sub>1</sub>	AC RMS	•	•	•	•	•	•	•	•	•			
l <sub>2</sub>	AC RMS		•	•(2)	•	•(1)	•	•(1)	•	•			
l <sub>3</sub>	AC RMS			•	•	•(1)	•	•(1)	•	•			
I <sub>N</sub>	AC RMS		•				•	•	•	•			
I <sub>1</sub>	DC										•	•	•
l <sub>2</sub>	DC											•	•
I <sub>3</sub>	DC												•

Quant	ities	1P-2W	1P-3W	3P-3W∆2 3P-3WO2 3P-3WY2	3P-3W∆3 3P-3WO3 3P-3WY3	3P-3W∆B	3P-4WY	3P-4WYB	3P-4WY2	3P-4W∆ 3P-4WO∆	DC-2W	DC-3W	DC-4W
I <sub>N</sub>	DC											•	•
I <sub>1</sub>	AC + DC RMS	•	•	•	•	•(1)	•	•	•	•			
I <sub>2</sub>	AC + DC RMS		•	•(2)	•	•(1)	•	•(1)	•	•			
I <sub>3</sub>	AC + DC RMS			•	•	•	•	•(1)	•	•			
I <sub>N</sub>	AC + DC RMS		•				•	•	•	•			
V <sub>1-CF</sub>		•	•				•	•	•	•			
$V_{2\text{-CF}}$			•				•	•(1)	•(10)	•			
V <sub>3-CF</sub>							•	•(1)	•	•			
I <sub>1-CF</sub>		•	•	•	•	•	•	•	•	•			
l <sub>2-CF</sub>			•	•(2)	•	•(1)	•	•(1)	•	•			
I <sub>3-CF</sub>				•	•	•(1)	•	•(1)	•	•			
V <sub>+</sub>				•	•	•	•	•	<b>(10)</b>				
V_				•	•	•(4)	•	•(4)	<b>(10)</b>				
V <sub>o</sub>				•	•	•(4)	•	•(4)	<b>(</b> 10)				
I <sub>+</sub>				•	•	•	•	•	•				
I,				•	•	•(4)	•	•(4)	•				
I <sub>o</sub>				•	•	•(4)	•	•(4)	•				
u <sub>o</sub>				•	•	•(4)	•	•(4)	•(4)	•(3)			İ
u <sub>2</sub>				•	•	•(4)	•	•(4)	•(4)	•(3)			
i <sub>o</sub>				•	•	•(4)	•	•(4)	•	•(3)			
i <sub>2</sub>				•	•	•(4)	•	•(4)	•	•(3)			
F		•	•		•	•	•	•	•	•			
P <sub>1</sub>	AC	•	•	†			•	•	•	•			
P <sub>2</sub>	AC		•	†			•	<b>●</b> (1)	<b>(10)</b>	•			i –
P <sub>3</sub>	AC			1			•	●(1)	•	•			
P <sub>T</sub>	AC	•(7)	•	•	•	•	•	•(1)	•	•			
P <sub>1</sub>	DC	= (. )	_					- (.,			•	•	•
P <sub>2</sub>	DC			†								•	•
P <sub>3</sub>	DC			1									•
³ P <sub>⊤</sub>	DC			†							•(7)	•	•
P <sub>1</sub>	AC+DC	•	•				•	•	•	•	ì		İ
P <sub>2</sub>	AC+DC		•	1			•	<b>(</b> 1)	<b>(10)</b>	•			İ
P <sub>3</sub>	AC+DC			1			•	•(1)	•	•			İ
$P_{\scriptscriptstyle T}$	AC+DC	•(7)	•	•	•	•	•	•(1)	•	•			
Pf <sub>1</sub>		•	•				•	•	•	•			İ
Pf <sub>2</sub>			•				•	<b>(</b> 1)	<b>(10)</b>	•			İ
Pf <sub>3</sub>							•	•(1)	•	•			
Pf <sub>T</sub>		•(7)	•	•	•	•	•	•(1)	•	•			İ
P,				•	•	•	•	•(1)	•				İ
P <sub>U</sub>				•	•	•(4)	•	•(4)	•				İ
P <sub>h</sub>		•	•	•	•	•	•	•	•				
Q <sub>1</sub>		•	•	<del>                                     </del>			•	•	•	•			
Q <sub>2</sub>			•	<u> </u>			•	•(1)	•(10)	•			
$Q_3$				<del>                                     </del>			•	•(1)	•	•			
		(7)											
$Q_{T}$		•(7)	•	•	•	•	•	•(1)	•	•			<u> </u>

Quantities		1P-2W 1P-3W		3P-3W∆2 3P-3WO2 3P-3WY2	3P-3W∆3 3P-3WO3 3P-3WY3	3P-3W∆B	3P-4WY	3P-4WYB	3P-4WY2	3P-4W∆ 3P-4WO∆	DC-2W	DC-3W	DC-4W
S <sub>1</sub>	AC	•	•				•	•	•	•			
S <sub>2</sub>	AC		•				•	•(1)	•(10)	•			
S <sub>3</sub>	AC						•	•(1)	•	•			
S <sub>T</sub>	AC	•(7)	•	•	•	•	•	•(1)	•	•			
S <sub>1</sub>	AC+DC	•	•				•	•	•	•			
S <sub>2</sub>	AC+DC		•				•	•(1)	<b>(</b> 10)	•			
S <sub>3</sub>	AC+DC						•	•(1)	•	•			
S <sub>⊤</sub>	AC+DC	•(7)	•	•	•	•	•	•(1)	•	•			
Sf₁		•	•				•	•	•	•		İ	
Sf <sub>2</sub>			•				•	<b>●</b> (1)	<b>(10)</b>	•			
Sf <sub>3</sub>							•	<b>●</b> (1)	•	•			
Sf <sub>⊤</sub>		•(7)	•	•	•	•	•	•(1)	•	•			
N <sub>1</sub>	AC	•	•				•	•	•	•			
N <sub>2</sub>	AC		•				•	<b>●</b> (1)	<b>(10)</b>	•	<u> </u>		
N <sub>3</sub>	AC						•	<b>●</b> (1)	•	•			
N <sub>T</sub>	AC	•(7)	•	•	•	•	•	<b>●</b> (1)	•	•			
N <sub>1</sub>	AC+DC	•	•				•	•	•	•			<u> </u>
N <sub>2</sub>	AC+DC		•				•	•(1)	<b>(10)</b>	•			<u> </u>
N <sub>3</sub>	AC+DC						•	•(1)	•	•	-		
N <sub>T</sub>	AC+DC	•(7)	•	•	•	•	•	•(1)	•	•		<del>                                     </del>	
D <sub>1</sub>	AC	• (1)	•				•	(1)	•	•		-	<u> </u>
	AC		•					<del></del>	<u> </u>	•			<u> </u>
D <sub>2</sub>	AC		_				•	<b>(</b> 1)	(10)	•		-	
D <sub>3</sub>								<b>(</b> 1)	-				<u> </u>
D <sub>T</sub>	AC	(7)	•	•	•	•	•	•(1)	•	•			<u> </u>
D <sub>1</sub>	AC+DC	•	•				•	•		•			<u> </u>
D <sub>2</sub>	AC+DC		•				•	•(1)	(10)	•		-	
D <sub>3</sub>	AC+DC						•	•(1)	•	•		-	
D <sub>T</sub>	AC+DC	•(7)	•	•	•	•	•	•(1)	•	•	-	<u> </u>	
PF <sub>1</sub>		•	•				•	•	•	•		<u> </u>	<u> </u>
PF <sub>2</sub>			•				•	•(1)	<b>(</b> 10)	•			
PF <sub>3</sub>							•	•(1)	•	•			
PF <sub>T</sub>		●(7)	•	•	•	•	•	•(1)	•	•			
Cos φ <sub>1</sub>		•	•				•	•	•	•			
Cos φ <sub>2</sub>			•				•	•(1)	<b>(</b> 10)	•			
Cos φ <sub>3</sub>							•	•(1)	•	•			
Cos φ <sub>τ</sub>		•(7)	•	•	•	•	•	<b>●</b> (1)	•	•			
Tan Φ		•	•	•	•	•(3)	•	•	●(10)	•			
V₁-Hi	i=1	•	•				•	•	•	•			
V <sub>2</sub> -Hi	at 50 (6) %f		•				•	•(1)	<b>(</b> 10)	•			
V <sub>3</sub> -Hi	%f						•	•(1)	•	•			
U <sub>12</sub> -Hi	i=1		•	•	•	•	•	•(1)	•(10)	•			
U <sub>23</sub> -Hi	at 50 (6) %f			•	•	•(1)	•	•(1)	•(10)	•			
U <sub>31</sub> -Hi	%f			•	•	•(1)	•	<b>●</b> (1)	•	•			
I₁-Hi		•	•	•	•	•	•	•	•	•			
I <sub>2</sub> -Hi	i=1 at 50		•	•(2)	•	<b>●</b> (1)	•	•(1)	•	•			
I <sub>3</sub> -Hi	(6) %f			•	•	<b>●</b> (1)	•	•(1)	•	•			
I <sub>N</sub> -Hi	"		•(2)				•(2)	•(4)	•(2)	•(2)			
V₁-THD	%f	•	•				•	•	•	•			

Quanti	ties	1P-2W	1P-3W	3P-3W∆2 3P-3WO2 3P-3WY2	3P-3W∆3 3P-3WO3 3P-3WY3	3P-3W∆B	3P-4WY	3P-4WYB	3P-4WY2	3P-4W∆ 3P-4WO∆	DC-2W	DC-3W	DC-4W
V <sub>2</sub> -THD	%f		•				•	•(1)	<b>(</b> 10)	•			
V <sub>3</sub> -THD	%f						•	•(1)	•	•			
U <sub>12</sub> -THD	%f		•	•	•	•	•	•(1)	•	•			
U <sub>23</sub> -THD	%f			•	•	•(1)	•	•(1)	•	•			
U <sub>31</sub> -THD	%f			•	•	•(1)	•	<b>(</b> 1)	•	•			
I₁-THD	%f	•	•	•	•	•	•	•	•	•			
I <sub>2</sub> -THD	%f		•	•(2)	•	•(1)	•	<b>●</b> (1)	•	•			
I <sub>3</sub> -THD	%f			•	•	•(1)	•	•(1)	•	•			
I <sub>N</sub> -THD	%f		•(2)				•(2)	•(4)	•(2)	•(2)			
	I			•	•	•	•		•	•			
Phase order	V			•	•	•	•		•	•			
Oraci	I, V	•	•	•	•	•	•	•	•	•			
$\varphi(V_2, V_1)$			•				•	•(9)					
$\varphi(V_3, V_2)$							•	•(9)					
$\varphi(V_1, V_3)$							•	•(9)	•	•			
$\phi (V_{23}, V_{12})$				•	•	•(9)	•	•(9)		•			
$\begin{pmatrix} \varphi & (V_{12}, V_{31}) \end{pmatrix}$				•	•	•(9)	•	•(9)		•			
φ (V <sub>31</sub> , V <sub>23</sub> )				•	•	•(9)	•	•(9)		•			
$\varphi(V_2, V_1)$			•		•	•(9)	•	•(9)	•	•			
$\varphi(V_3, V_2)$					•	•(9)	•	•(9)	•	•			
$\varphi(V_1, V_3)$				•	•	•(9)	•	•(9)	•	•			
$\varphi(V_1, V_1)$		•	•			●(8)	•	•	•	•			
$\phi(V_2, V_2)$			•				•	•					
$\varphi(V_3, V_3)$							•	•	•	•			
E <sub>PT</sub>	Source AC	•	•	•	•	•	•	•	•	•	•(5)	•(5)	•(5)
E <sub>PT</sub>	Load AC	•	•	•	•	•	•	•	•	•	•(5)	•(5)	•(5)
E <sub>QT</sub>	Quad 1	•	•	•	•	•	•	•	•	•	•(5)	•(5)	•(5)
E <sub>QT</sub>	Quad 2	•	•	•	•	•	•	•	•	•	•(5)	•(5)	•(5)
E <sub>QT</sub>	Quad 3	•	•	•	•	•	•	•	•	•	•(5)	•(5)	<b>(</b> 5)
E <sub>QT</sub>	Quad 4	•	•	•	•	•	•	•	•	•	(5)	(5)	(5)
E <sub>ST</sub>	Source	•	•	•	•	•	•	•	•	•	(5)	(5)	(5)
E <sub>ST</sub>	Load Source			<del></del>				<del></del>			(5)	(5)	(5)
E <sub>PT</sub>	DC Load	(5)	<b>(</b> 5)	•(5)	•(5)	•(5)	• (5)	(5)	(5)	• (5)	•	•	•
E <sub>PT</sub>	DC	•(5)	•(5)	<b>(</b> 5)	•(5)	•(5)	•(5)	<b>(</b> 5)	•(5)	•(5)	•	•	•

- (1) Extrapolated
- (2) Calculated
- (3) Value not significant (4) Always = 0 (5) AC+DC when selected (6) 7th max at 400Hz
- (7)  $P_1 = P_T$ ,  $\varphi_1 = \varphi_T$ ,  $S_1 = S_T$ ,  $PF_1 = PF_T$ ,  $Cos \varphi_1 = Cos \varphi_T$ ,  $Q_1 = Q_T$ ,  $N_1 = N_T$ ,  $D_1 = D_T$ (8)  $\varphi(I_3, U_{12})$ (9) Always = 120°

- (10) Interpolated

### 9.5. GLOSSARY

Phase shift of the phase-neutral voltage with respect to the phase-neutral current.

Inductive phase shift.

Capacitive phase shift.

Degree.Percentage.

A Ampere (unit of current).

AC AC component (current or voltage).

Aggregation Various means defined in § 9.2.

Crest factor of the current or voltage: ratio of the crest (peak) value of a signal to the RMS value.
 cos φ
 Cosine of the phase shift of the phase-neutral voltage with respect to the phase-neutral current.

**DC** DC component (current or voltage).

Ep Active energy.Eq Reactive energy.Es Apparent energy.

**f** (Frequency) Number of complete periods of voltage or current per second.

Fundamental component: component at the fundamental frequency.

**Harmonics** In electrical systems, voltages and currents at multiples of the fundamental frequency.

Hz Hertz (unit of frequency).

I Symbol of the current.

I-CF Crest factor of the current.

**I-THD** Total harmonic distortion of the current.

I, RMS current (L = 1, 2 or 3)

Value or percentage of current of the  $n^{th}$  harmonic (L = 1, 2 or 3).

**L** Phase of a polyphase electrical network.

MAX Maximum value.

Measurement method: Any measurement method associated with an individual measurement.

MIN Minimum value.

Nominal voltage: Nominal voltage of a network.

Order of a harmonic: ratio of the frequency of the harmonic to the fundamental frequency; a whole number.

P Active power

PF Power Factor - ratio of the active power to the apparent power.

Phase Time relation between current and voltage in AC circuits.

Q Reactive power.

**RMS** Root Mean Square of the current or voltage. Square root of the mean of the squares of the instantaneous values

of a quantity during a specified interval.

**S** Apparent power.

 $tan \Phi$  Ratio of the reactive power to the active power.

**THD** Total Harmonic Distortion. This characterizes the proportion of harmonics of a signal with respect to the RMS

value of the fundamental component or the total RMS value without the DC component.

**U** Voltage between two phases.

U-CF Crest factor of the phase-phase voltage.u2 Unbalance of the phase-neutral voltages.

**U**<sub>1,thp</sub> Value or percentage of phase-phase voltage of the n<sup>th</sup> harmonic (L = 1, 2 or 3)

Unbalance of the voltages of a polyphase network: State in which the RMS voltages between conductors (fundamental com-

ponent) and/or the phase differences between successive conductors are not equal.

**Uxy-THD** Total harmonic distortion of the voltage between two phases.

**V** Phase-neutral voltage or Volt (unit of voltage).

V-CF Crest factor of the voltage

**V-THD** Total harmonic distortion of the phase-neutral voltage.

**VA** Unit of apparent power (Volt x Ampere).

var Unit of reactive power.varh Unit of reactive energy.

 $V_L$  RMS voltage (L = 1, 2, or 3)

 $V_{L+ln}$  Value or percentage of phase-neutral voltage of the n<sup>th</sup> harmonic (L = 1, 2 or 3).

W Unit of active power (Watt).

**Wh** Unit of active energy (Watt x hour).

# Prefixes of the units of the international system (SI)

Prefix	Symbol	Multiplies by					
milli	m	10 <sup>-3</sup>					
kilo	k	10³					
Mega	М	106					
Giga	G	10 <sup>9</sup>					
Tera	Т	10 <sup>12</sup>					
Peta	Р	10 <sup>15</sup>					
Exa	E	10 <sup>18</sup>					

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