

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



Features

- Bipolar and insulated current measurement
- Current output
- Closed loop (compensated) current transducer
- Panel mounting.

Advantages

- High accuracy
- Very low offset drift over temperature.

Applications

- Windmill inverters
- Test and measurement
- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications.

Standards

- IEC 61010-1: 2010
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- UL 508 : 2013.

Application Domain

- Industrial.

Absolute maximum ratings

| Parameter | Symbol | Unit | Value |
|--|------------------|------|-------|
| Maximum supply voltage (working) (−40 °C ... 85 °C) | $\pm U_{C \max}$ | V | ±25.2 |
| Maximum primary conductor temperature | $T_{B \max}$ | °C | 100 |
| Maximum steady state primary current (−40 °C ... 85 °C)) | $I_{P N \max}$ | A | 2000 |

Stresses above these ratings may cause permanent damage.
Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13.

Ratings

| Parameter | Unit | Value |
|-------------------------------------|---------|------------|
| Primary involved potential | V AC/DC | 1500 |
| Maximum surrounding air temperature | °C | 85 |
| Primary current | A | 0 ... 2000 |
| Secondary supply voltage | V DC | 0 ... 24 |
| Secondary current | mA | 0 ... 400 |

Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 1500 V AC/DC, consideration shall be given to the following:

- 1 - *These products must be mounted in a suitable end-use enclosure.*
- 2 - *The secondary pin terminals have not been evaluated for field wiring.*
- 3 - *Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).*
- 4 - *Based on the temperature test performed on LF 2010-S series, the primary bar or conductor shall not exceed 120 °C in the end use application when the primary current does not exceed 2500 A and 100 °C when the primary current is up to 3500 A.*
- 5 - *LF 2010-S series shall be used in a pollution degree 2.*

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

Insulation coordination

| Parameter | Symbol | Unit | Value | Comment |
|---|----------|------|-------|--|
| RMS voltage for AC insulation test, 50 Hz, 1 min | U_d | kV | 6 | |
| Impulse withstand voltage 1.2/50 μ s | U_{Ni} | kV | 23 | |
| Clearance (pri. - sec.) | d_{cl} | mm | 28.0 | Shortest distance through air |
| Creepage distance (pri. - sec.) | d_{cp} | mm | 29.8 | Shortest path along device body |
| Application example Rated insulation RMS voltage | U_{Nm} | V | 3600 | Basic insulation according to IEC 61800-5-1, CAT III, PD2 |
| Application example Rated insulation RMS voltage | U_{Nm} | V | 1000 | Reinforced insulation according to IEC 61800-5-1, CAT III, PD2 |
| Case material | - | - | V0 | According to UL 94 |
| Comparative tracking index | CTI | | 600 | |

Environmental and mechanical characteristics

| Parameter | Symbol | Unit | Min | Typ | Max | Comment |
|-------------------------------|------------------|--------------|-----|------|-----|---------|
| Ambient operating temperature | T_A | $^{\circ}$ C | -40 | | 85 | |
| Ambient storage temperature | $T_{A\text{st}}$ | $^{\circ}$ C | -50 | | 90 | |
| Mass | m | g | | 1500 | | |

Electrical data

At $T_A = 25\text{ °C}$, $\pm U_C = \pm 24\text{ V}$, $R_M = 1\ \Omega$, unless otherwise noted.

Lines with a * in the conditions column apply over the $-40 \dots 85\text{ °C}$ ambient temperature range.

| Parameter | Symbol | Unit | Min | Typ | Max | Conditions |
|---|---------------------|---------------|--------------|----------|------------|--|
| Primary nominal DC current | I_{PN} | A | | | 2000 | * |
| Primary current, measuring range | I_{PM} | A | -4250 | | 4250 | * With $\pm U_C = \pm 22.8\text{ V}$; $T_A = 85\text{ °C}$; $R_M = 1\ \Omega$ For other conditions, see figure 1 |
| Measuring resistance | R_M | Ω | 0 | | | * Max value of R_M is given in figure 1 |
| Secondary nominal RMS current | I_{SN} | A | | | 0.4 | * |
| Resistance of secondary winding | R_S | Ω | | | 18.6 | $R_S(T_A) = R_S \times (1 + 0.004 \times (T_A + \Delta\text{temp} - 25))$ Estimated temperature increase @ I_{PN} is $\Delta\text{temp} = 15\text{ °C}$ |
| Secondary current | I_S | A | -0.85 | | 0.85 | * |
| Number of secondary turns | N_S | | | 5000 | | |
| Theoretical sensitivity | S_{th} | mA/A | | 0.2 | | |
| Supply voltage | $\pm U_C$ | V | ± 14.25 | | ± 25.2 | * |
| Current consumption @ $I_{PN} = 0$ | I_C | mA | | 42 48 | | $\pm U_C = \pm 15\text{ V}$ $\pm U_C = \pm 24\text{ V}$ |
| Offset current, referred to primary | I_O | A | -1 | | 1 | |
| Temperature variation of I_O , referred to primary | I_{OT} | A | -1 | | 1 | * |
| Magnetic offset current after $3 \times I_{PN}$ referred to primary | I_{OM} | A | | ± 1 | | |
| Sensitivity error | ε_S | % | -0.15 | | 0.15 | * |
| Linearity error | ε_L | % of I_{PN} | -0.1 | | 0.1 | * |
| Total error at I_{PN} | ε_{tot} | % of I_{PN} | -0.2 -0.3 | | 0.2 0.3 | * 25 ... 70 ... 85 °C -40 ... 85 °C |
| Output RMS noise current, referred to primary | I_{no} | mA | | 90 | | 1 Hz to 20 kHz (see figure 4) |
| Delay time to 10 % of the final output value I_{PN} step | t_{D10} | μs | | < 0.5 | | 0 to 1 kA, 200 A/ μs |
| Delay time @ 90 % of the final output value I_{PN} step | t_{D90} | μs | | < 0.5 | | 0 to 1 kA, 200 A/ μs |
| Frequency bandwidth | BW | kHz | | 150 | | -3 dB, small signal bandwidth (see figure 5) |

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, maximal and minimal values are determined during the initial characterization of the product.

Typical performance characteristics

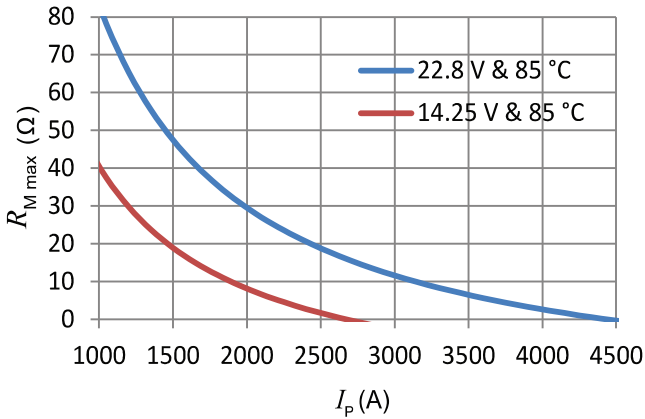


Figure 1: Maximum measuring resistance

$$R_{M \max} = N_S \times \frac{U_{C \min} - 0.6 \text{ V}}{I_P} - R_{S \max}$$

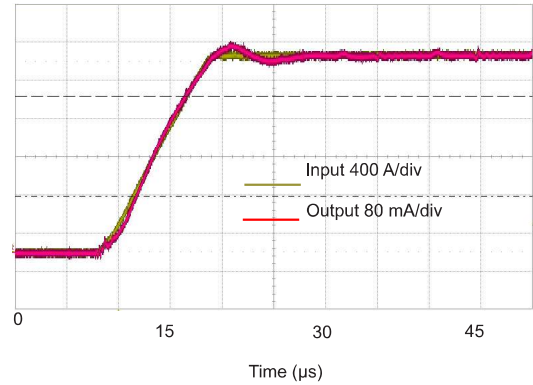


Figure 2: Typical delay time (0 to 2 kA, 400 A/μs)

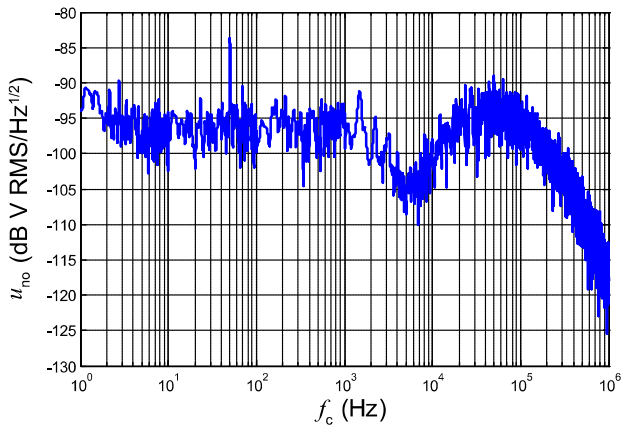


Figure 3: Typical output noise voltage spectral density e_{no} with $R_M = 100 \Omega$

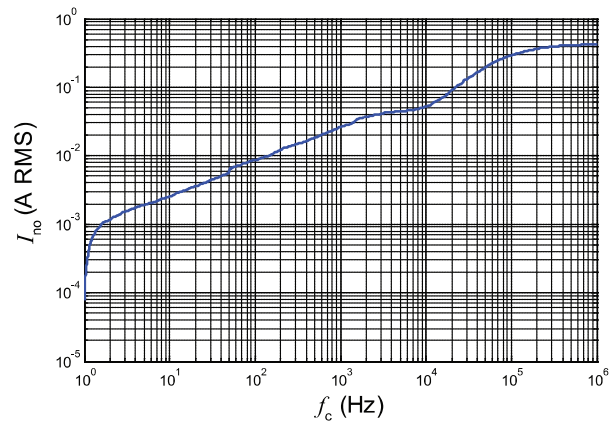


Figure 4: Typical total output RMS noise current with $R_M = 100 \Omega$ (primary referred)

Figure 3 (output noise voltage spectral density) shows that there are no significant discrete frequencies in the output. Figure 4 confirms the absence of steps in the total output RMS noise current that would indicate discrete frequencies.

To calculate the noise in a frequency band f_1 to f_2 , the formula is:

with $I_{no}(f)$ read from figure 4 (typical, RMS value).

$$I_{no}(f_1 \text{ to } f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

Example:

What is the noise from 1 to 10^6 Hz?

Figure 4 gives $I_{no}(1 \text{ Hz}) = 0.2 \text{ mA}$ and $I_{no}(10^6 \text{ Hz}) = 400 \text{ mA}$.

The output RMS noise current is therefore:

$$\sqrt{(400 \times 10^{-3})^2 - (0.2 \times 10^{-3})^2} = 400 \text{ mA referred to primary}$$

Typical performance characteristics continued

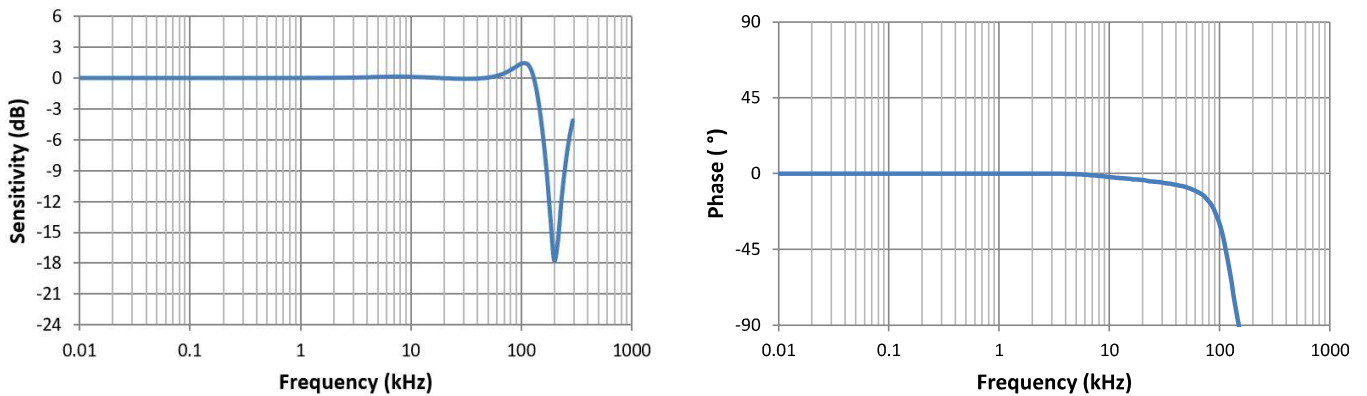


Figure 5: Typical frequency response, small signal bandwidth

Performance parameters definition

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to I_{PM} , then to $-I_{PM}$ and back to 0 (equally spaced $I_{PM}/10$ steps).

The sensitivity S is defined as the slope of the linear regression line for a cycle between $\pm I_{PM}$.

The linearity error ϵ_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Magnetic offset

The magnetic offset I_{OM} is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

Electrical offset

The electrical offset current I_{OE} is the residual output current when the input current is zero.

Total error

The total error ϵ_{tot} is the error at $\pm I_{PN}$, relative to the rated value I_{PM} . It includes all errors mentioned above.

Delay times

The delay time t_{D10} and the delay time t_{D90} are shown in the next figure.

Both slightly depend on the primary current di/dt . They are measured at nominal current.

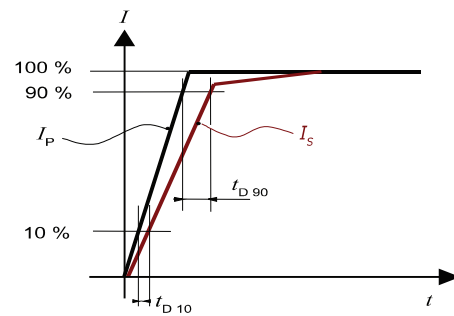
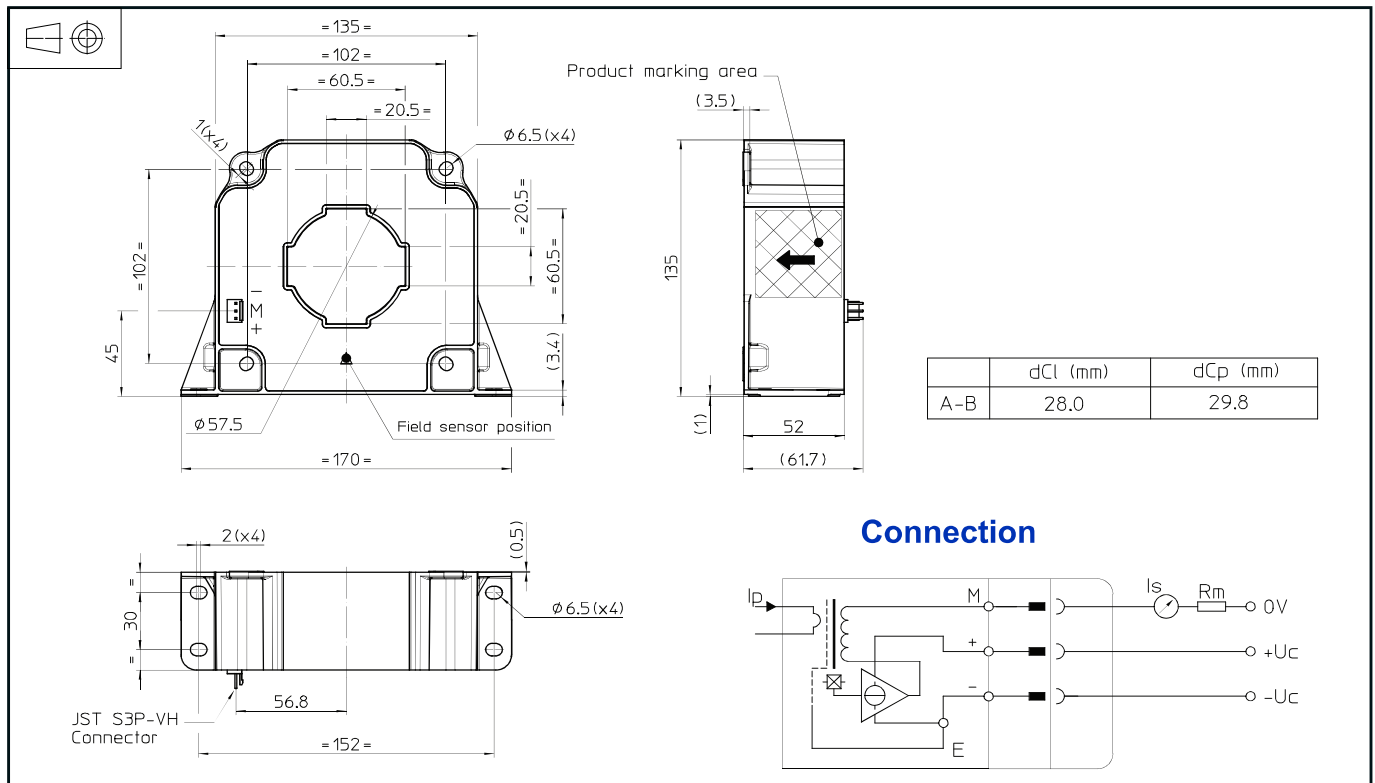


Figure 6: t_{D10} (delay time @ 10 %) and t_{D90} (delay time @ 90 %)

Dimensions (in mm)

Mechanical characteristics

- General tolerance ± 0.5 mm
- Transducer fastening
 - Vertical position
 - 4 slotted holes $\phi 6.5$ mm
 - 4 M6 steel screws
 - Recommended fastening torque 5.5 N·m (± 10 %)
- Primary through-hole
 - Or
 - $\phi 57$ mm
 - 60 mm \times 20 mm
- Transducer fastening
 - Horizontal position
 - 4 slotted holes $\phi 6.5$ mm
 - 4 M6 steel screws
 - Recommended fastening torque 5.5 N·m (± 10 %)
- Connection of secondary JST S3P-VH.

Remarks

- I_s is positive when I_p flows in the direction of arrow.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary current or secondary voltage present.
- Maximum temperature of primary conductor: see page 2.
- This is a standard model. For different versions (supply voltages, turns ratios, unidirectional measurements...), please contact us
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: [Products/Product Documentation](#).

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary connection, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used. Main supply must be able to be disconnected.