

# **Current Transducer LF 305-S**

For the electronic measurement of currents: DC, AC, pulsed..., with galvanic separation between the primary circuit and the secondary circuit.



### **Electrical data**

$I_{ m PN}$ $I_{ m PM}$	Primary nominal RMS current Primary current, measuring range		300 0 ±500				A A
$R_{M}$	Measuring resistance @		$T_{\rm A} = 70  {\rm ^{\circ}C}$		$T_{_{\rm A}}$ = 85 °C		
			$R_{ m M\ mi}$	$_{_{ m N}}$ $R_{_{ m Mmax}}$	$R_{ m Mm}$	$_{ m nin}R_{ m M\ max}$	
	with ±12 V	@ $\pm 300  A_{max}$	0	37	0	35	Ω
		@ $\pm 500 A_{max}$	0	10	0	8	Ω
	with ±15 V	@ ±300 A <sub>max</sub>	0	56	0	54	Ω
		@ ±500 A <sub>max</sub>	0	21	0	19	Ω
	with ±20 V	@ ±300 A <sub>max</sub>	0	88	0	86	Ω
		@ ±500 A <sub>max</sub>	0	40	0	38	Ω
$I_{\mathrm{SN}}$	Secondary nomina			150	)		mΑ
$N_{\rm P}/N_{\rm S}$	Turns ratio			1:	2000		
$U_{\rm c}$	Supply voltage (±5	%)		±12	2 20		V
$I_{\text{c}}$	Current consumpti	on		26	(@ ±20	$V)+I_{\rm S}$	mΑ

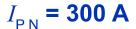
# Accuracy - Dynamic performance data

$\varepsilon_{\mathrm{tot}}$	Total error @ $I_{PN}$ , $T_A = 25 ^{\circ}C$	±0.5		%
$arepsilon_{L}$	Linearity error	< 0.1		%
		Тур	Max	
$I_{\text{OE}}$	Electrical offset current @ $I_P = 0$ , $T_A = 25$ °C		±0.2	mΑ
$I_{OM}$	Magnetic offset current $^{1)}$ @ $I_{P}$ = 0 and specified $R_{M}$			
	after an overload of 3 x $I_{PN}$		±0.2	mΑ
$I_{_{OT}}$	Temperature variation of $I_0$ $-10 ^{\circ}\text{C} \dots +70 ^{\circ}\text{C}$	±0.1	±0.3	mΑ
	<b>−</b> 40 °C +85 °C	±0.2	±0.7	mΑ
t <sub>D 10</sub>	Delay time to 10 % of the final output value for $I_{PN}$ ste	эр	< 500	ns
t <sub>D 90</sub>	Delay time to 90 % of the final output value for $I_{PN}$ ste	ep <sup>2)</sup>	< 1	μs
BW	Frequency bandwidth (-1 dB)	DC	100	kHz

# **General data**

$T_{A}$	Ambient operating temperature	<del>-</del> 40 +85	°C
$T_{Ast}$	Ambient storage temperature	<del>-</del> 40 +85	°C
$R_{\rm S}$	Resistance of secondary winding @ $T_A$ = 70 °C	30	Ω
Ü	@ $T_{A} = 85  ^{\circ}\text{C}$	32	Ω
m	Mass	95	g
	Standards	EN 50178: 1997	
		UL 508: 2010	

Notes:1) The result of the coercive field of the magnetic circuit





#### **Features**

- Closed loop (compensated) current transducer using the Hall effect
- Insulating plastic case recognized according to UL 94-V0.

# **Advantages**

- Excellent accuracy
- Very good linearity
- Low temperature drift
- Optimized response time
- Wide frequency bandwidth
- No insertion losses
- High immunity to external interference
- Current overload capability.

# **Applications**

- AC variable speed drives and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications.

#### **Application domain**

Industrial.

N° 97.14.46.000.0

<sup>&</sup>lt;sup>2)</sup> With a di/dt of 100 A/µs.



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Insulation coordination			
$U_{d}$	RMS voltage for AC insulation test, 50 Hz, 1 min	3.8	kV
$U_{Ni}^{u}$	Impulse withstand voltage 1.2/50 µs	10	kV
141		Min	
$d_{Cp}$	Creepage distance	11.1	mm
$d_{Cp} \ d_{Cl}$	Clearance	10.6	mm
CTI	Comparative tracking index (group IIIa)	175	

# **Applications examples**

According to EN 50178 and IEC 61010-1 standards and following conditions:

- Over voltage category OV 3
- Pollution degree PD2
- Non-uniform field

	EN 50178	IEC 61010-1		
$d_{\mathrm{Cp}},d_{\mathrm{Cl}},U_{\mathrm{Ni}}$	Rated insulation voltage	Nominal voltage		
Basic insulation	1000 V	1000 V		
Reinforced insulation	500 V	500 V		

# **Safety**

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary busbar, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

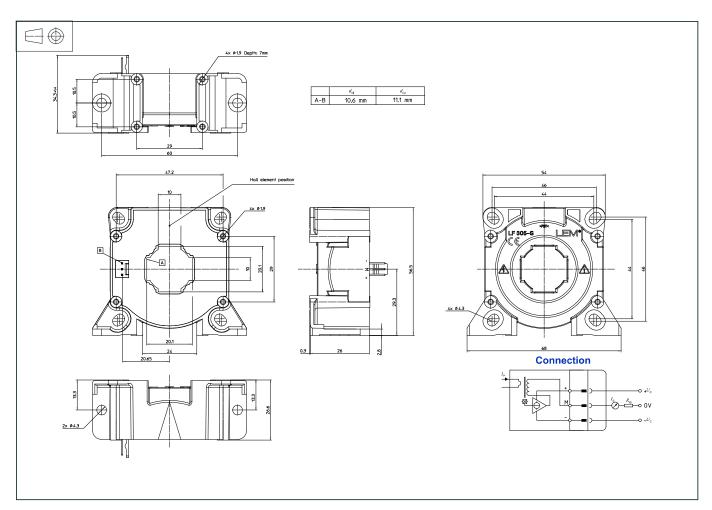
This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used.

Main supply must be able to be disconnected.



#### **Dimensions LF 305-S** (in mm)



#### **Mechanical characteristics**

 General tolerance ±0.5 mm

Transducer fastening

2 holes Ø 4.3 mm Vertical position

2 M4 steel screws

Recommended fastening torque 3.2 N m

or

4 holes Ø 1.9 mm.

depth: 7 mm 4 PTKA 25 screws length: 6 mm

Recommended fastening torque 0.7 N·m

Transducer fastening

Horizontal position 4 holes Ø 4.3 mm

4 M4 steel screws

Recommended fastening torque 3.2 N·m

4 holes Ø 1.9 mm or

crossing

4 PTKA 25 screws,

length: 10 mm

Recommended fastening torque 0.75 N·m Primary through-hole Ø 20.1 mm

Connection of secondary Molex 6410 3 Tin plated pins

# **Remarks**

- $I_{\rm S}$  is positive when  $I_{\rm P}$  flows in the direction of the arrow.
- Temperature of the primary conductor should not exceed 100 °C.
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: https://www.lem.com/en/file/3137/download/.
- Dynamic performances (di/dt and response time) are best with a single bar completely filling the primary hole.
- This is a standard model. For different versions (supply voltages, turns ratios, unidirectional measurements...), please contact us.

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