OptiSure Automated Optical Inspection Operating Manual





You have selected a reliable, high-quality dispensing system from Nordson EFD, the world leader in fluid dispensing. Nordson EFD automated dispensing systems are designed specifically for industrial dispensing and will provide you with years of trouble-free, productive service.

This manual will help you maximize the usefulness of your automated dispensing system.

Please spend a few minutes to become familiar with the controls and features. Follow our recommended testing procedures. Review the helpful information we have included, which is based on more than 50 years of industrial dispensing experience.

Most questions you will have are answered in this manual. However, if you need assistance, please do not hesitate to contact EFD or your authorized EFD distributor. Detailed contact information is provided on the last page of this document.

The Nordson EFD Pledge

Thank You!

You have just purchased the world's finest precision dispensing equipment.

I want you to know that all of us at Nordson EFD value your business and will do everything in our power to make you a satisfied customer.

If at any time you are not fully satisfied with our equipment or the support provided by your Nordson EFD Product Application Specialist, please contact me personally at 800.556.3484 (US), 401.431.7000 (outside US), or Ferran.Ayala@nordsonefd.com.

I guarantee that we will resolve any problems to your satisfaction.

Thanks again for choosing Nordson EFD.



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Introduction

This manual provides operating instructions for the OptiSure™ Automated Optical Inspection (AOI) integrated software add-on and confocal laser accessory. This advanced technology add-on includes features that provide optical assurance and improve deposit accuracy and process control using closed loop feedback. The OptiSure AOI add-on is compatible with all EFD vision-guided automated dispensing systems and is available within the DispenseMotion software (version 2.36-RS and higher).

This OptiSure AOI technology allows a vision-guide system to inspect fluid deposit widths and diameters with exceptional certainty and determine if dispense requirements have been met. For PROPlus / PRO Series systems, the OptiSure AOI confocal laser produces 3D images of deposits and detects deposit measurements regardless of the transparency of the fluid.

Applicability of this Manual

This manual applies only to the optional OptiSure AOI software add-on and the confocal laser. The OptiSure AOI add-on can be unlocked on any vision-guided automated dispensing system. The confocal laser can be installed only on PROPlus / PRO systems.

NOTE: For all other information pertaining to an automated dispensing system, refer to the respective system's operating manual.



The OptiSure Automated Optical Inspection add-on can be unlocked on any vision-guided automated dispensing system



The confocal laser is an optional accessory for PROPlus / PRO Series systems that allows 3D verification of deposit accuracy

About OptiSure AOI

All OptiSure AOI functions are accessed by selecting the Arrow icon on the Camera screen and then by rightclicking in the Primary View screen.

The OptiSure AOI feature includes the following capabilities:

- Optical two-dimensional (X and Y) inspection and verification of deposits to determine if the dispense requirements are met; if they are not met, the system can automatically adjust the dispense program to correct the inaccuracy. All vision-based automated dispensing systems can perform this verification.
- On systems with the optional confocal laser, optical three-dimensional (X, Y, and Z) inspection to determine if the dispense requirements are met, including dispense volume; if they are not met, the system can automatically adjust the dispense program to correct the inaccuracy.
- · Advanced methods for making a mark easier for the system to find by adding details to it based on its characteristics. These functions are similar to the Area function of the Template Match window, but are specifically designed for workpiece surfaces that present unique challenges, such as multiple circles, unclear or fuzzy elements, or even workpieces that have no distinguishing features.



Location of the Arrow icon on the Camera tab (turns yellow when selected)

Enabling the OptiSure AOI Feature

Two important actions are required to use the full functionality of the OptiSure AOI add-on:

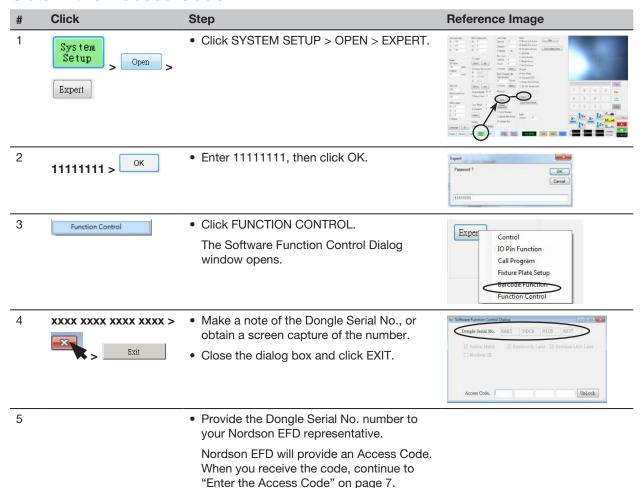
- An access code must be used to unlock the OptiSure AOI add-on. To obtain the access code, you must provide the Dongle Serial No. to Nordson EFD as described in this section.
- For some OptiSure AOI features to function properly, a script file must be present on the DispenseMotion controller. Obtain this script file from your Nordson representative.

NOTE: If you have not purchased the OptiSure AOI software key, refer to "OptiSure AOI Kit Part Numbers" on page 62 for the kit part numbers. Contact your Nordson EFD representative for assistance.

PREREQUISITES

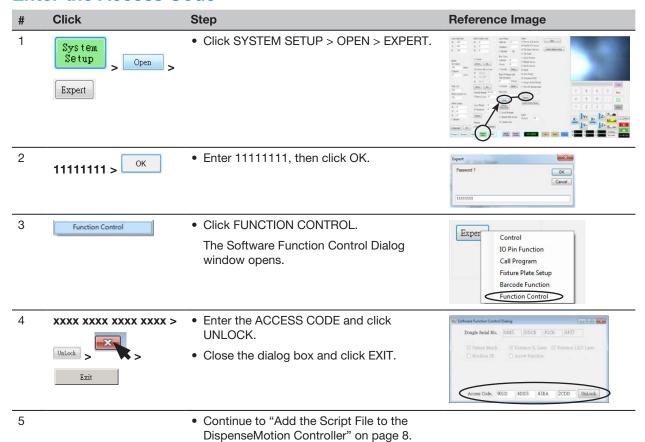
- ☐ The complete automated dispensing system is properly installed and set up in accordance with the respective system's operating manual.
- You have purchased your OptiSure AOI kit(s).
- ☐ You have obtained the main.bas file from your Nordson EFD representative.
- □ If purchased, the optional confocal laser is installed in accordance with the installation instructions.
- ☐ The DispenseMotion software is open.

Obtain the Access Code



Enabling the OptiSure AOI Feature (continued)

Enter the Access Code



Enabling the OptiSure AOI Feature (continued)

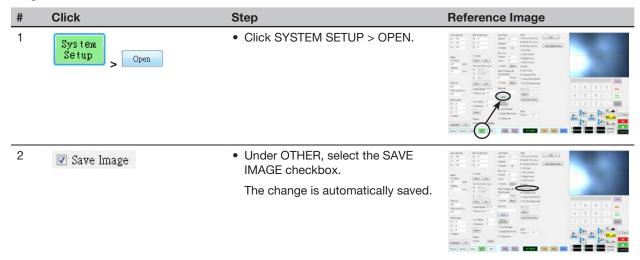
Add the Script File to the DispenseMotion Controller

NOTE: The main.bas script file is not required for all OptiSure AOI functions, but Nordson EFD recommends adding it to the DispenseMotion controller as a best practice.

#	Click	Step	Reference Image
1		 If you have not already done so, contact your Nordson EFD representative to obtain the main.bas script file. 	
		 Place the main.bas file on a USB drive. 	
		 Insert the USB drive into an empty USB port on the back of the DispenseMotion controller. 	MONITOR
		NOTE: On most controllers, USB-3 is an unused USB port.	USB-3 USB-2
2		Switch ON the DispenseMotion controller.	
		NOTE: Do not open the DispenseMotion software at this time.	
3	New Volume (Dt)	 Using the file explorer application, navigate to the USB drive and copy the main.bas file. Navigate to the D:\ever_sr directory and paste the main.bas file into the directory. 	Compart Section 1 Section 2 Sect
4		Close the file explorer application.	
		The OptiSure AOI add-on is now unlocked and ready for use. Refer to the remaining sections of this manual for detailed procedures for using the OptiSure AOI features. If you also installed the confocal laser, continue to "Setting Up the Confocal"	
		continue to "Setting Up the Confocal Laser" on page 10.	

Setting Up the System to Save Images

To ensure full functionality of all OptiSure AOI features, set up the system to automatically save any captured images.



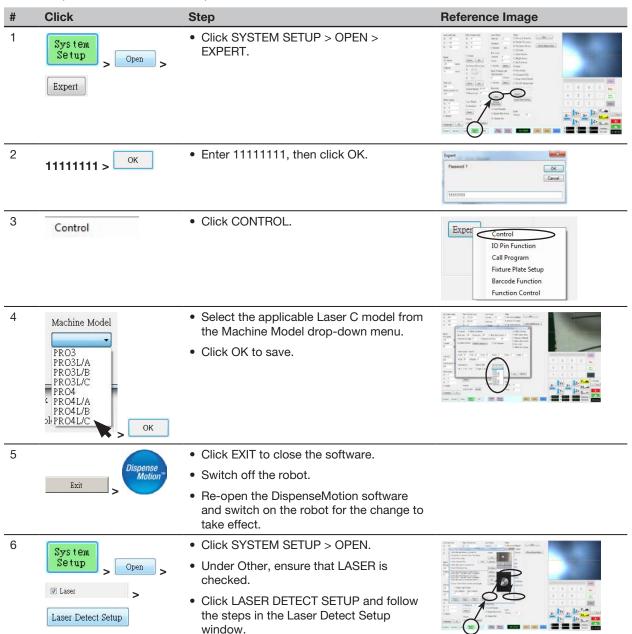
Setting Up the Confocal Laser

If you installed the confocal laser (Laser C), follow this procedure to ensure that the laser is properly selected and set up in the system.

NOTE: The confocal laser can be installed only on PROPlus / PRO systems.

PREREQUISITES

- □ If purchased, the optional confocal laser is installed in accordance with the installation instructions.
- ☐ The DispenseMotion software is open.



NOTE: If you want to use the centering feature for the most precise laser calibration, complete steps 1-3 of the wizard and then skip to "Using the Center Button for Laser C Setup" below to complete laser setup.

• Close the window after you have completed all the steps.

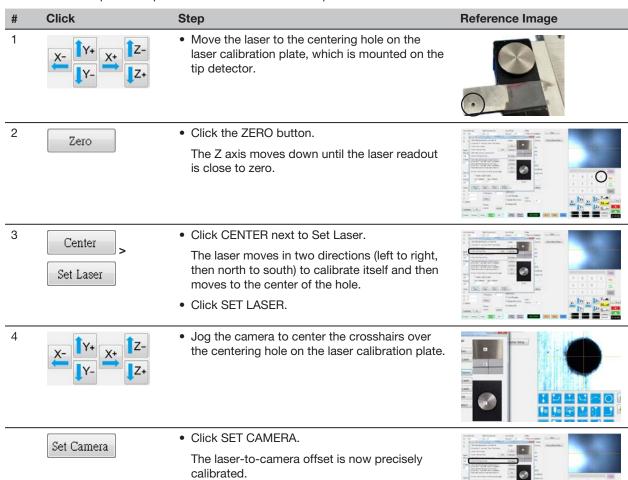
Setting Up the Confocal Laser (continued)

Using the Center Button for Laser C Setup

On systems with Laser C, the Laser Detect Setup window has a Center button that can be used for more precise laser calibration. Using the Center button is optional, but is recommended to obtain the most accurate calibration. Follow these steps to use the Center button during Laser C setup.

PREREQUISITES

- ☐ You have completed "Setting Up the Confocal Laser" on page 10.
- ☐ You have completed steps 1–3 of the Laser Detect Setup wizard.



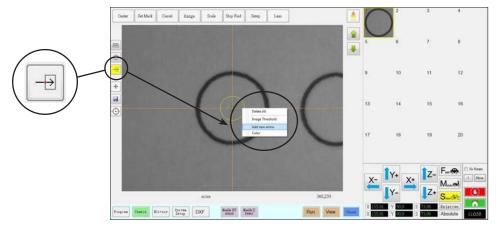
· Complete the remaining steps of the Laser Detect Setup wizard and close the window after

you have completed all the steps.

Overview of the OptiSure AOI Functions

Click the Arrow icon, then right-click in the Primary View screen to view the Arrow menu.

Arrow Menu Item		Description	Refer to
Delete All	Delete All	Deletes all arrows associated with a mark image.	n/a
Image Threshold Image Threshold		Allows you to isolate a specific portion of an image for future adjustment; the isolated portion remains visible on the screen when you are adjusting the parameters in an Arrow dialog box:	"Using Image Threshold" on page 13
		Recommended for use in tandem with any Arrow Type	
		Provides more accurate results than Template / Area	
Add New Arrow Add new arrow		Adds an arrow to a mark image; added arrows can be manipulated individually or collectively to improve the system's ability to find a mark image, or to optically check a dispense.	"Using the Arrow Types" on page 14
		Select the arrow type to use based on the characteristics of the mark image.	
Color	Color	Changes the color of the on-screen arrows, circles, and other visual aids of the Arrow functions.	n/a



Location of the Arrow icon on the Camera tab (turns yellow when selected) and the resulting menu when you right-click in the Primary View screen

Using Image Threshold

Image Threshold allows you to view changes to a mark image as you make adjustments. This feature can be used alone or in tandem with an Add New Arrow function. Nordson EFD recommends first using Image Threshold before using some of the Arrow Type functions, so that you can view the changes to the image on the screen.

NOTE: A quicker alternative to using Image Threshold is to use the Threshold slider inside each Arrow Type dialog box. If you want to use the quicker method, do not enable Image Threshold.

PREREQUISITES

☐ The mark image you want to adjust is saved in the Mark Library.

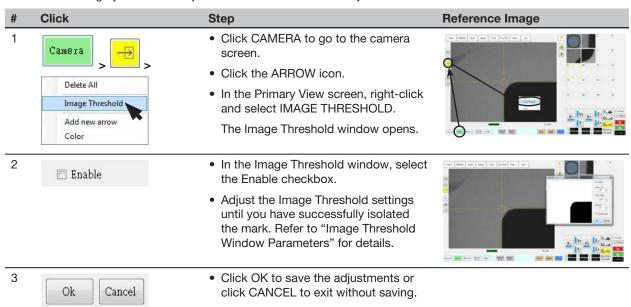


Image Threshold Window Parameters

Parameter		Function
Enable	Enable	If checked, enables the Image Threshold function.
Gray Low	Gray Low	Adjusts the minimum value of the threshold — the lower the setting, the less visible the image will be; when a valid setting is entered, the image is visible on the screen.
		Range: 0-255 (0 is full dark; 255 is full white)
Gray High	Gray High	Adjusts the maximum value of the threshold — if the maximum value is exceeded, the image will not be visible; when a valid setting is entered, the image is visible on the screen.
		Range: 0-255
Erosion	Erosion 1	Reduces and then enlarges the image to remove impurities (as long as Dilation First is not checked).
Dilation	Dilation first	If checked, enlarges and then reduces the image to remove impurities.

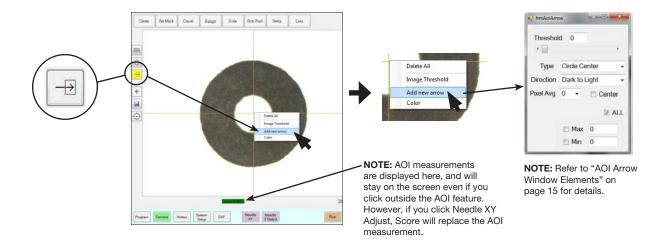
Using the Arrow Types

The Add New Arrow icon accesses advanced features that allow you to:

- Add details to a mark image to improve the system's ability to match the mark image to the corresponding location on a workpiece.
- Verify the width, length, or depth of a dispense based on parameters saved in a mark image.

There are five types of arrow function, shown below. An example procedure for using each function is provided.

Arrow Menu Type Selection			Recommended Use	Refer to
Circle Center	Туре	Circle Center •	Create a mark image that defines the center of a circular area with poorly defined boundaries.	"Circle Center Example" on page 22
Gravity Point	Туре	Gravity Point •	Create two mark images on a line so that you can use Fiducial Marks to ensure that line dispenses are made down the center of a line, regardless of its thickness.	"Gravity Point Example" on page 17
Intersect Line	Type	Intersect Line •	Create a mark image for a workpiece that does not have any obvious marks for the system to find; in this case, you must use the upper left and bottom right corners of the workpiece to create marks.	"Intersect Line Example" on page 36
Mea. Point To Line	Type	Mea. Point To Line ▼	Create a mark image that allows you to measure the width between any two points on a line. Then, using the Arrow Check Point command, the system can check the width between the specified points; if the width does not meet the criteria specified within the mark image, the system takes the specified action.	"Mea. Point To Line Example" on page 42
Mea. Width (Automated Optical Inspection)	Туре	Mea. Width ▼	Create a mark image that sets the desired width for a line. Then, using the Arrow Check Point or Arrow Check Line commands, the system can check the width of a dispensed line; if the dispensed line does not meet the criteria specified within the mark image, the system takes the specified action.	"Mea. Width Example for Verifying Line Width" on page 47



Accessing the Add New Arrow function on the Camera tab, and the resulting AOI Arrow parameter window

AOI Arrow Window Elements

The parameters in the AOI Arrow window vary depending on the selected arrow Type.







Gravity Point parameters



Intersect Line parameters



Measure Point to Line parameters



Measure Width parameters

Parameter		Applicability	Description
Threshold	Threshold 0 Range: 0–255	All arrow types	As long as Image Threshold is not enabled, you can use this parameter to adjust the mark image automatically. If Image Threshold is enabled, this parameter is disabled. Refer to "Using Image Threshold" on page 13 for details.
Type	Type Circle Center •	n/a	Sets the arrow type. Refer to "Using the Arrow Types" on page 14 for an explanation of each.
Direction	Other value: Light to Dark	All arrow types	The direction of the light on the thresholded image that matches the direction of the inserted arrow. For accurate results, the selected Direction must match the direction of that inserted arrow points toward.
			EXAMPLES:
			• If (1) an isolated mark is black, and (2) the empty space around it is white, and (3) the inserted arrow points inward toward the mark, then the light direction is white to black, in which case the correct selection for Direction is LIGHT TO DARK.
			• If (1) an isolated mark is white, and (2) the empty space around it is black, and (3) the inserted arrow points inward toward the mark, then light direction is black to white, in which case the correct selection for Direction is DARK TO LIGHT.
			NOTE: If you enable Image Threshold, the system converts the image to black and white, where black is the isolated mark and white is the dead space, or vice versa.
			Continued on next page

AOI Arrow Window Elements (continued)







Gravity Point parameters



Intersect Line parameters



Measure Point to Line parameters



Measure Width parameters

Parameter		Applicability	Description
Pixel Avg.	Pixel Avg. 0 ▼	All arrow types	Averages the pixel density, allowing higher accuracy when the system searches for the mark.
Center checkbox		All arrow types	If enabled, the system attempts to use the mark image to center the camera over the mark before acting upon the data specified in an arrow feature. By default, Center is deselected.
			NOTE: Most arrow features also attempt to center a mark, so enabling this feature might cause the system to center the camera twice: Once using the mark image in the mark library and then again using the arrow feature.
ALL checkbox	☑ ALL	All arrow types	If checked, the system adjusts any changed settings for all the arrows. By default, ALL is deselected. This setting must be selected before any other changes are made in an AOI Arrow window.
Max and Min checkboxes		Circle Center, Mea. Point To Line, Mea. Width	If checked, you can enter values to specify maximum and minimum values for the selected arrow Type.

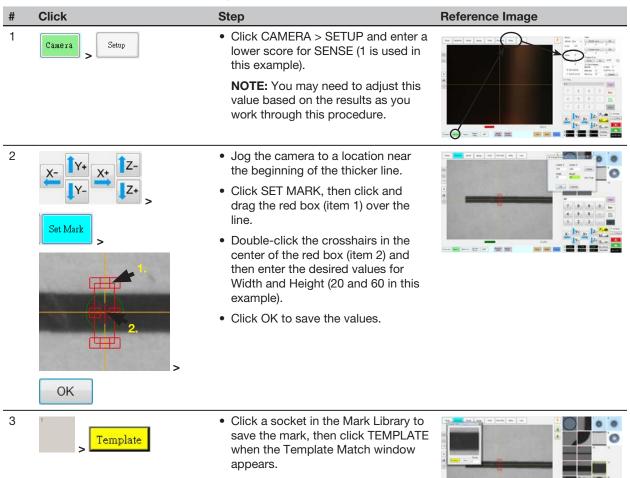
Gravity Point Example

Gravity Point is an OptiSure AOI feature that allows you to create two Fiducial Marks in the center of a line, one at the beginning of the line and the other at the end of the line. Then, if a subsequent dispense must be made on a line that is thicker or thinner, the system can dispense through the center of that line using the Fiducial Mark offsets.

PREREQUISITES

□ To learn how to use this feature, draw two lines of different thicknesses on a sheet of white paper and use it as a workpiece template.

To Create a Gravity Point Mark Image



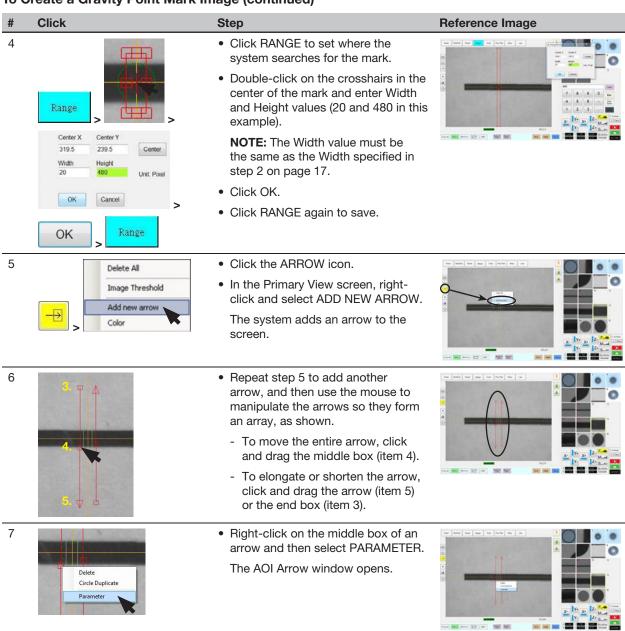
Continued on next page

The system saves the image in the

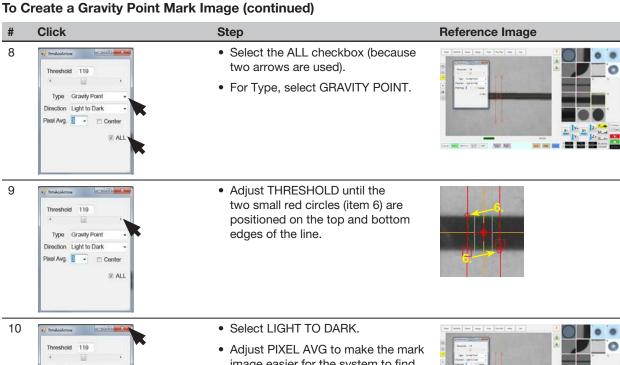
Mark Library.

Gravity Point Example (continued)

To Create a Gravity Point Mark Image (continued)



Gravity Point Example (continued)



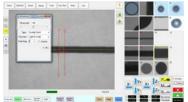
- Type Gravity Point Direction Light to Dark
- image easier for the system to find.

NOTE: Select CENTER if you want to center the image based on the image in the mark library.

· Close the dialog box to save the settings.

The saved mark image now contains additional data that will allow the system to accurately find it upon reaching its corresponding Fiducial Mark command in a program.

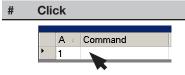
• Continue to "To Use a Gravity Point Mark Image in a Program" on page 20 to use the Gravity Point mark image.



Step

Gravity Point Example (continued)

To Use a Gravity Point Mark Image in a Program



• In the dispense program, insert one Fiducial Mark command near the beginning of the thicker line and one Fiducial Mark command near the end of the thicker line, specifying in each the Mark No. of the Gravity Point mark you created in the

previous procedure.



Insert a Line Speed command and set the value at 30.

NOTE: This setting might need to be adjusted depending on thickness of the line.

- Enter Line Start and Line End commands for the thicker line.
- Insert one Fiducial Mark command near the beginning of the thinner line and one Fiducial Mark command near the end of the thinner line, specifying Mark No. of the Gravity Point Mark you created in the previous procedure.

NOTE: These Fiducial Mark commands can specify the same Mark No. because both lines are similar in composition.

• Insert a Line Speed command that is double the previous line speed, so that less fluid is dispensed.

NOTE: This setting might need to be adjusted depending on the thickness of the line.

Insert Line Start and Line End commands for the thinner line.

When the system dispenses on any line with fiducial offsets, it will align the dispense in the middle of the line, regardless of the thickness or thinness of the line.

NOTE: The complete example program is provided on the next page.

Gravity Point Example (continued)

To Use a Gravity Point Mark Image in a Program (continued)

Α	Command	1	2	3	4	5	6
1	Z Clearance Setup	1	1				
2							
3	// Thicker Line						
4	Fiducial Mark	171.386	114.686	19.39	30		
5	Fiducial Mark	285.421	115.218	19.39	30		
6							
7	Line Speed	30					
8	Line Start	135.688	103.885	98.69			
9	Line End	723	104.417	98.69			
10							
11	// Thinner Line						
12	Fiducial Mark	171.386	119.804	19.39	30		
13	Fiducial Mark	285.421	120.336	19.39	30		
14							
15	Line Speed	60					
16	Line Start	135.688	109.003	98.69			
17	Line End	249.723	109.535	98.69			
18							
19	End Program						
20							

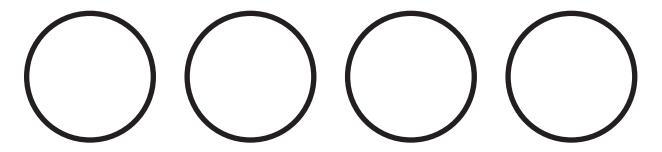
Example program that contains Fiducial Mark commands for a Gravity Point mark

Circle Center Example

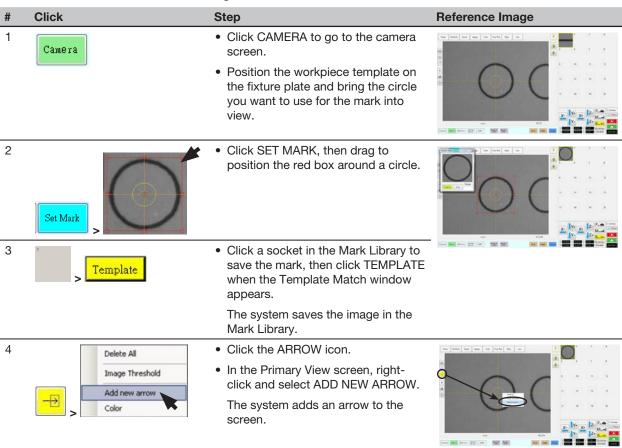
Circle Center is an OptiSure AOI feature that allows you to add details to a mark image of a circular area that has poor definition, thus allowing the system to find the mark image faster and more accurately.

PREREQUISITES

□ To learn how to use this feature, draw four large circles on a sheet of white paper and use it as a workpiece template.

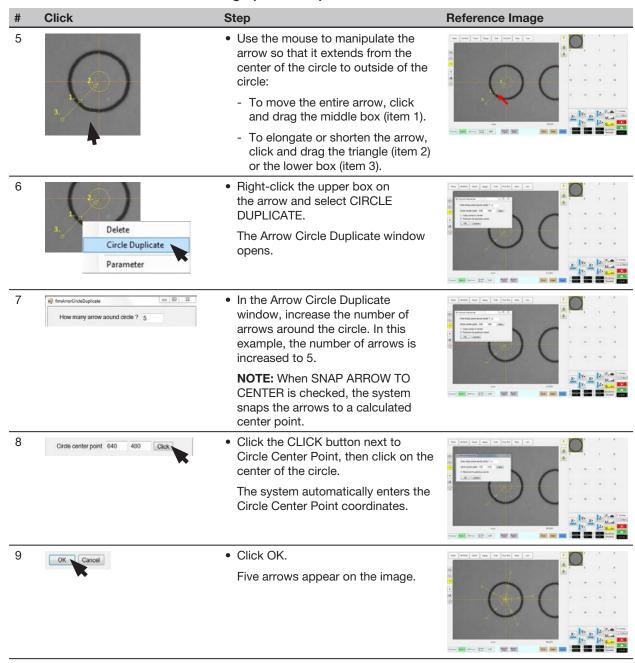


To Create a Circle Center Mark Image



Circle Center Example (continued)

To Create a Circle Center Mark Image (continued)



Direction Dark to Light

☐ Max 0

☐ Min

Using the Arrow Types (continued)

Circle Center Example (continued)

To Create a Circle Center Mark Image (continued)

Click Reference Image 10 · Right-click on any middle box (item 1) of an arrow and then select PARAMETER. Circle Duplicate The AOI Arrow window opens. 11 • Select the ALL checkbox (to cause the system to enter the same settings for all arrows). Type Circle Cente NOTE: If you want to enter settings Direction Dark to Light for each arrow individually, deselect □ Center ALL. • For Type, select CIRCLE CENTER. ☐ Min 0 12 • Adjust THRESHOLD until the all the yellow circles are located on the Threshold 0 circumference of the circle. Type Circle Cente Direction Dark to Light Pixel Avg. 0 - Center ☐ Max 0 ☐ Min 0 13 • Select LIGHT TO DARK. · Adjust PIXEL AVG to make the mark image easier for the system to find. Type Circle Center

- Check CENTER if you want to

image in the mark library.

center the image based on the

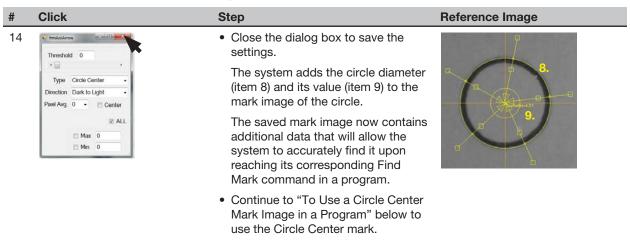
MAX and MIN are not used in this

NOTES:

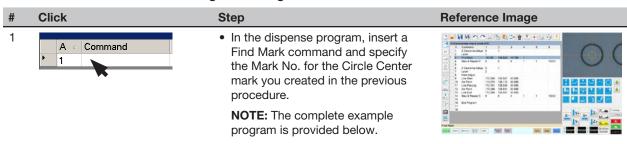
example.

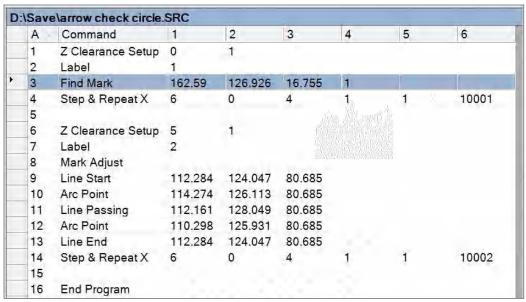
Circle Center Example (continued)

To Create a Circle Center Mark Image (continued)



To Use a Circle Center Mark Image in a Program



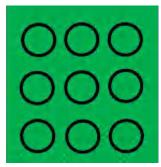


Example program that contains a Find Mark command for a Circle Center mark

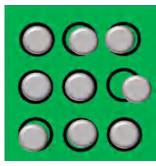
Positional Checking Example

Positional Checking is an OptiSure AOI feature that allows you to determine the exact X and Y offsets of a dispensed dot that deviates from a designated dispense location. Positional Checking is accomplished by using the Circle Center arrow type and the Positional Checking and Step & Repeat commands. The overview below shows how this feature works.

Overview of the Positional Checking Feature



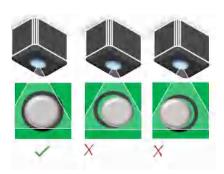
1. A workpiece with defined dispense locations.



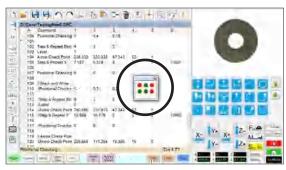
2. Dispensed dots on the workpiece.



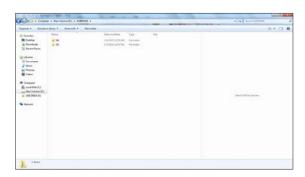
3. Using a Step & Repeat program, the camera examines each dispensed dot.



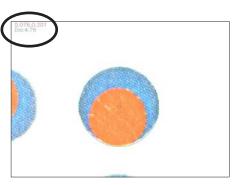
4. If a dispensed dot fits within the specified X and Y offset range, it passes; if not, it fails.



5a. Pass / fail status is displayed in a Positional Checking window. The system also captures and saves image files for all pass / fail results.



5b. Pass / fail images are saved in the D:\ directory into two folders: NG (not good) and OK.



6. Open an image to view details, including diameter and XY offset.

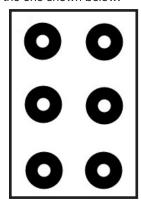
Positional Checking Example (continued)

This example uses a set of six concentric circles in which dots of white fluid are dispensed in the center of larger black circles. A Positional Checking program is created to verify the accuracy of dot placement in relation to the larger black circles.

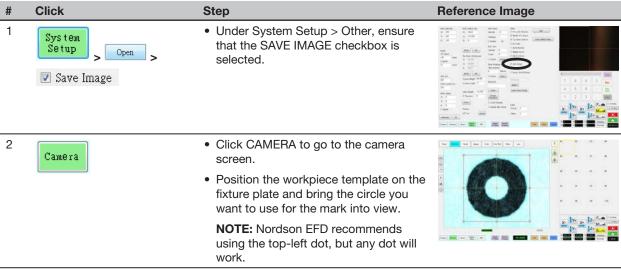
Positional Checking allows the camera to determine the X and Y offset of a dispensed circle from a given or defined location. The Step & Repeat Block command causes a window to open that shows the pass / fail status of each dispensed dot: Green for dots that pass and red for dots that fail. The camera also takes a screen capture of each dot and saves the image; the images provide dispense details, including diameter and XY offset.

PREREQUISITES

- ☐ The system is set up to save images. Refer to "Setting Up the System to Save Images" on page 9 as needed.
- □ To learn how to use this feature, create a workpiece template with defined, circular dispense locations, similar to the one shown below.

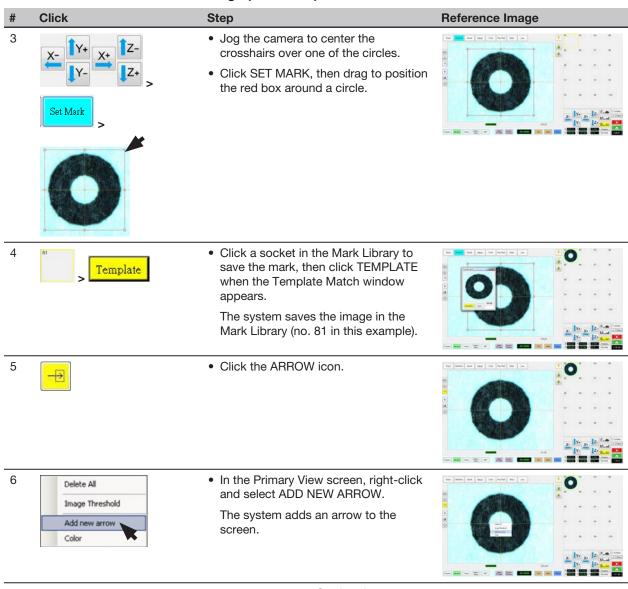


To Create a Circle Center Mark Image



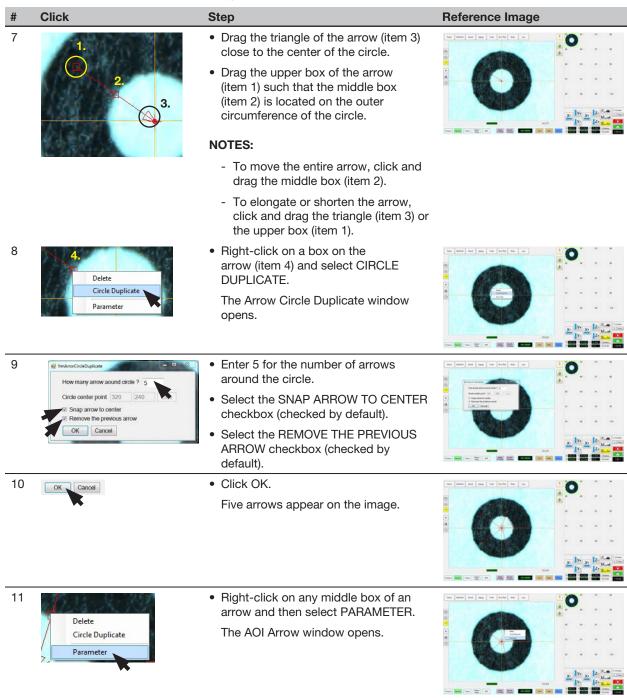
Positional Checking Example (continued)

To Create a Circle Center Mark Image (continued)



Positional Checking Example (continued)

To Create a Circle Center Mark Image (continued)



Positional Checking Example (continued)

To Create a Circle Center Mark Image (continued)

Click 12 Type Circle Cente Direction Light to Dark ☐ Min 0

Step

- · Select the ALL checkbox (to cause the system to enter the same settings for
- For Type, select CIRCLE CENTER.
- Select LIGHT TO DARK.
- Set PIXEL AVG to 3.
- · Adjust THRESHOLD until the circumference measurement appears and is stable.

NOTES:

- Alternatively, you can use the Image Threshold feature by right-clicking in the Primary View screen and selecting Image Threshold. Refer to "Using Image Threshold" on page 13 for details.
- CENTER is not used in this example.
- MAX and MIN are not used in this example but can be selected and added if desired.



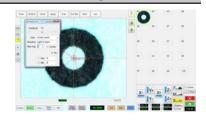
13

• Close the dialog box to save the settings.

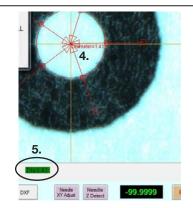
The system adds the circle diameter and its value (item 4) to the mark image of the circle and displays the measurement at the bottom of the Primary View screen (item 5).

The saved mark image now contains additional data that will allow the system to accurately find it upon reaching its corresponding Find Mark or Arrow Check Point command in a program.

• Continue to "To Use Positional Checking in a Program" on page 31.

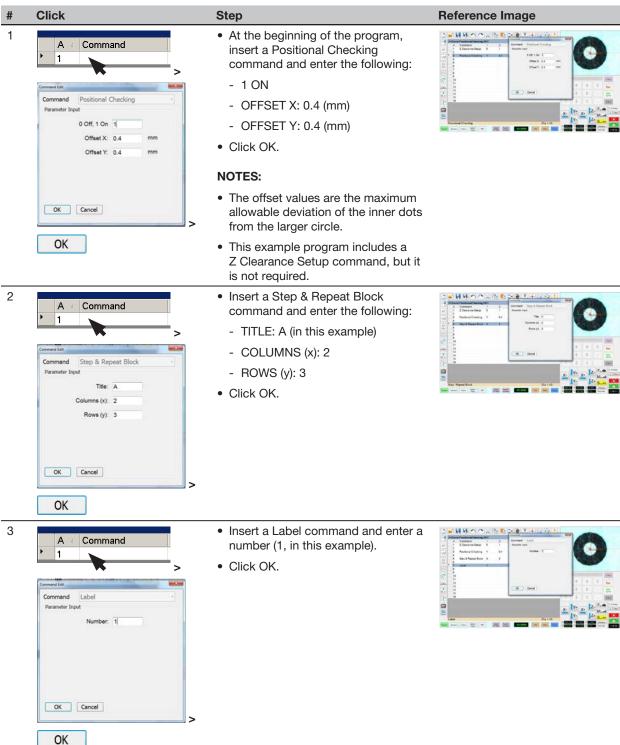


Reference Image



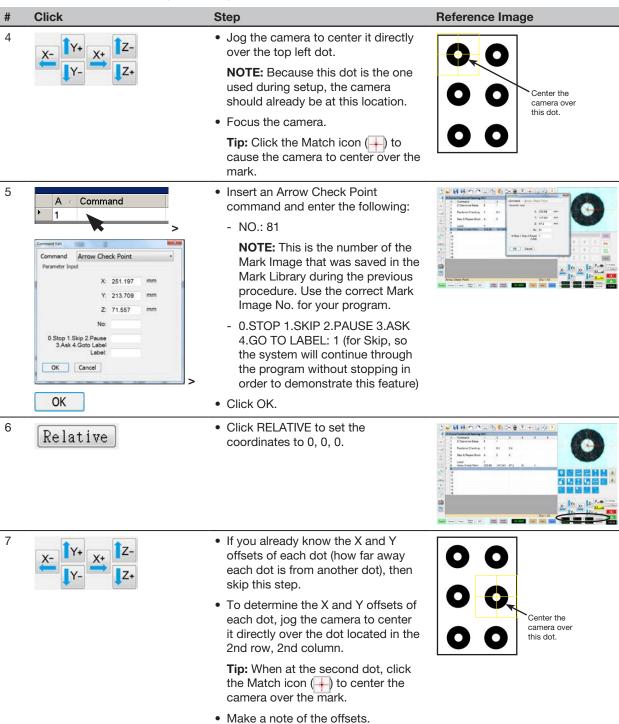
Positional Checking Example (continued)

To Use Positional Checking in a Program



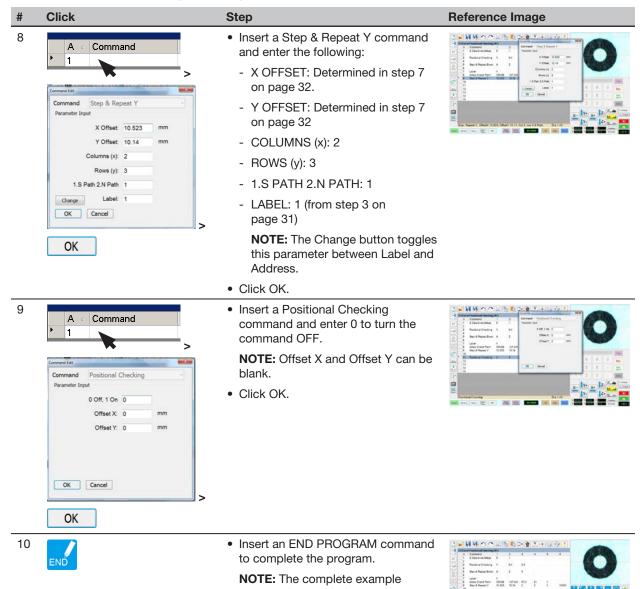
Positional Checking Example (continued)

To Use Positional Checking in a Program (continued)



Positional Checking Example (continued)

To Use Positional Checking in a Program (continued)



Continued on next page

program is provided on page 35.

Positional Checking Example (continued)

To Use Positional Checking in a Program (continued)

Click Reference Image 11 Click RUN to view the program and to observe the results of the Positional Checking.

As the program runs, the following occurs:

- · A window opens to show green or red dots (for this example, in a grid of two columns and three rows), indicating whether a deposit (the white dot) passes (green) or fails (red):
 - Pass: The deposit is within both Offset X and Offset Y values.
 - Fail: The deposit is outside one or both of the Offset X / Offset Y values.

NOTES:

- The window is named A (from step 2 on page 31).
- In this example, all dots are green because all white dots are within the specified X and Y offsets.
- If a dot fails, the system takes the action specified by the Stop, Skip, Pause, Ask, Go to Label parameter (Skip, in this example). Refer to "Arrow Check Point" on page 63 for details.
- · Screen captures of both passed and failed dots are saved as images and named automatically.

NOTE: If the screen captures are not automatically saved, ensure that the Save Images checkbox in System Setup is selected. Refer to "Setting Up the System to Save Images" on page 9 for details.

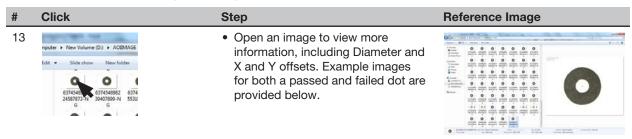


- To view the images of the marks, use the file explorer application to navigate to D:\AOIIMAGE:
 - Dots that passed (green) are saved in the OK folder.
 - Dots that did not pass (red) are saved in the NG folder.



Positional Checking Example (continued)

To Use Positional Checking in a Program (continued)





Location of diameter and offset details in the image of a dot that PASSED a positional check



Location of diameter and offset details in the image of a dot that FAILED a positional check

A	Command	1	2	3	4	5	6
1	Z Clearance Setup	5	1				
2							
3	Positional Checking	1	0.4	0.4			
4							
5	Step & Repeat Block	Α	2	3			
6							
7	Label	1					
8	Arrow Check Point	359.89	147.041	57.2	81	1	
9	Step & Repeat Y	10.523	10.14	2	3	1	10001
10							
11	Positional Checking	0	0	0			
12							
13	End Program						
14							

Example program using Positional Checking and Step & Repeat commands to check dispensed dots

Intersect Line Example

Intersect Line is an OptiSure AOI feature that allows you to create mark images for a workpiece that does not have any obvious features. To do so, you create marks using the corners and edges of the workpiece. This function also works for creating marks for an R-shaped area.

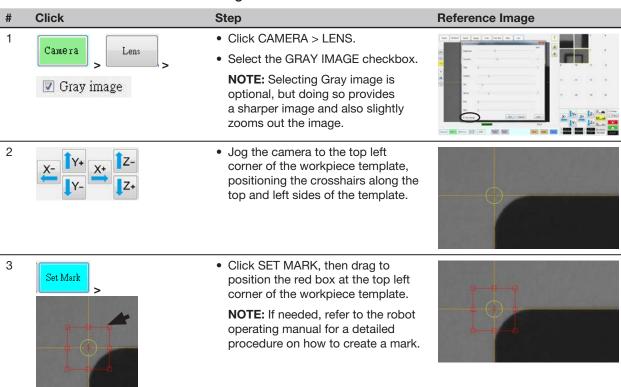
NOTE: If the rounded corners are too large to use Intersect Line, try using the Edge Adjust command. Refer to the operating manual for details.

PREREQUISITES

□ To learn how to use this feature, draw a large black rectangle with rounded corners on a sheet of white paper and use it as a workpiece template.

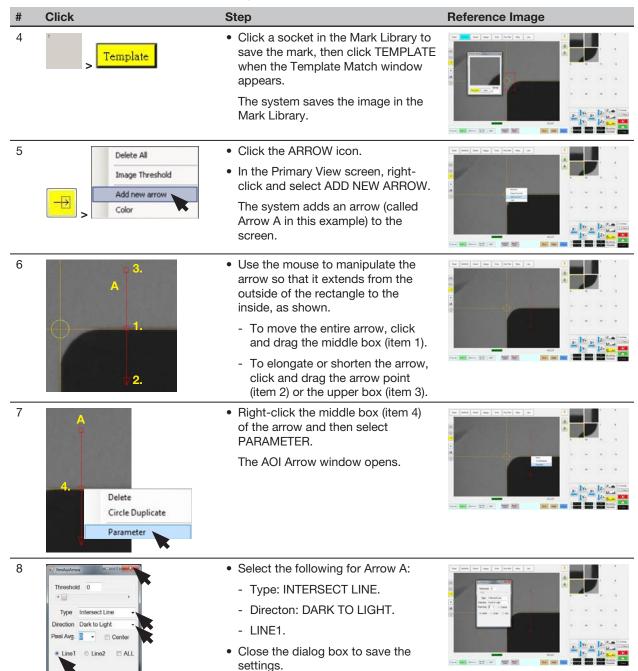


To Create an Intersect Line Mark Image



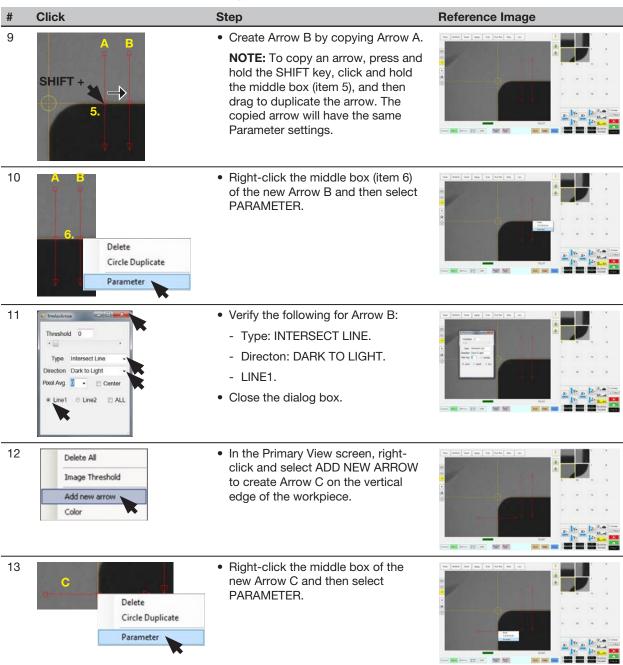
Intersect Line Example (continued)

To Create an Intersect Line Mark Image (continued)



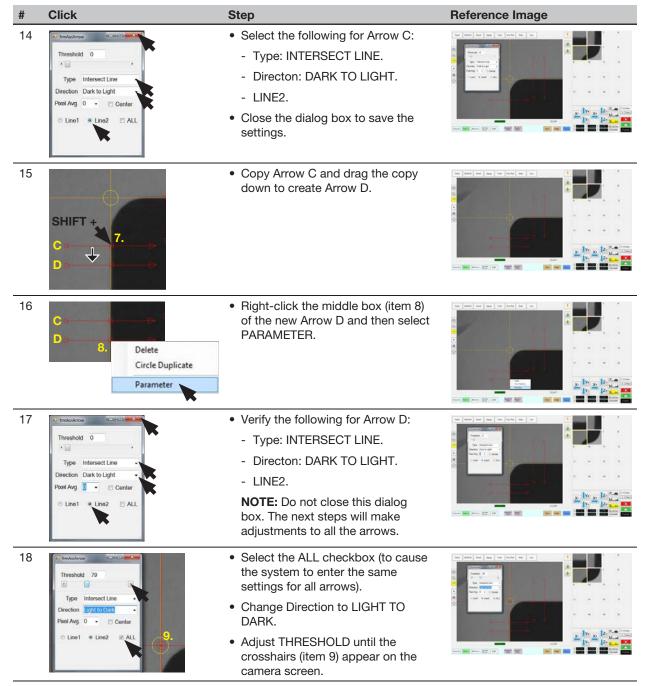
Intersect Line Example (continued)

To Create an Intersect Line Mark Image (continued)



Intersect Line Example (continued)

To Create an Intersect Line Mark Image (continued)



Intersect Line Example (continued)

To Create an Intersect Line Mark Image (continued)

Click 19 Type Intersect Line Light to Dark

Step

- Adjust PIXEL AVG to make the mark image easier for the system to find.
- Close the dialog box to save the settings.

The first mark image (No. 5 in this example) is now complete.

• If you have not already done so, start creating your program and add a Fiducial Mark command that references this mark image (No. 5 in this example).

NOTE: Refer to "To Use Intersect Line Mark Images in a Program" on page 41 for the complete example program.



Reference Image

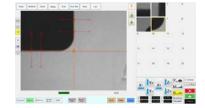
20

 Repeat the applicable steps in this procedure to create a mark image and set of arrows for the bottom right corner of the workpiece template.

This set of arrows will be the second mark image (No. 6 in this example).

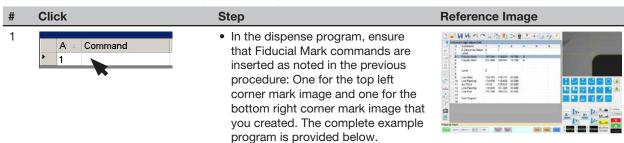
• In your program, add a second Fiducial Mark command that references this mark image (No. 6 in this example).

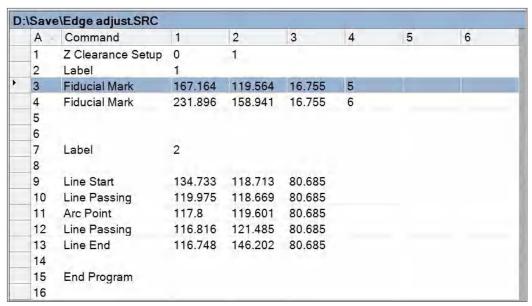
NOTE: Refer to "To Use Intersect Line Mark Images in a Program" on page 41 for the complete example program.



Intersect Line Example (continued)

To Use Intersect Line Mark Images in a Program





Example program that contains Fiducial Mark commands (lines 3-4) for Intersect Line marks

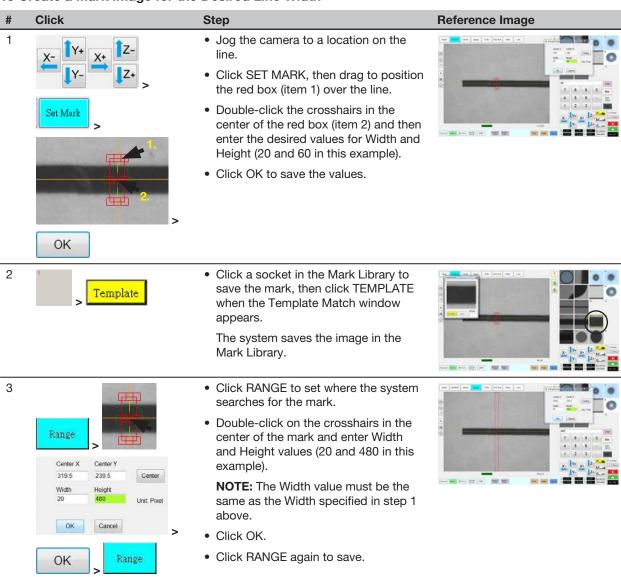
Mea. Point To Line Example

Mea. Point to Line is an OptiSure AOI feature used in tandem with the Arrow Check Point command. This feature measures the width between two specified points on a dispensed line, compares the measurement to a set of points on a subsequent dispense, and then, depending on the user-specified parameters, determines if the dispense is acceptable. If the dispense does not meet the specified criteria, the system takes the action specified in the Arrow Check Point command.

PREREQUISITES

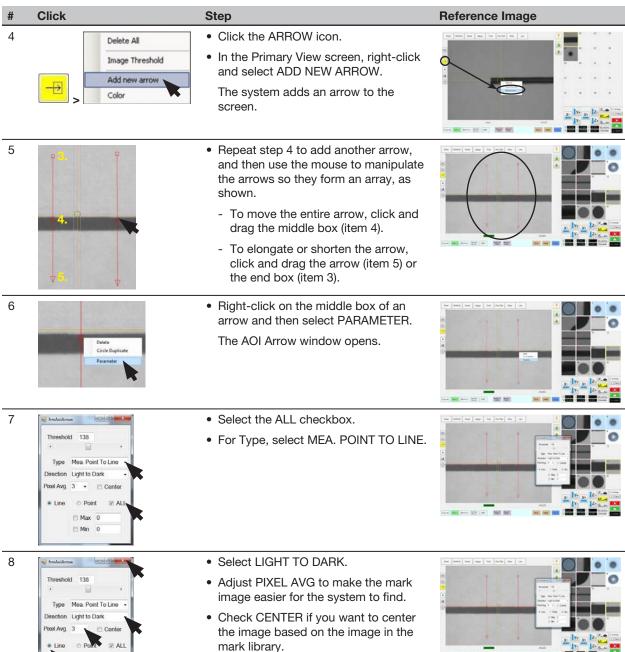
☐ To learn how to use this feature, draw a line on a sheet of white paper and use it as a workpiece template.

To Create a Mark Image for the Desired Line Width



Mea. Point To Line Example (continued)

To Create a Mark Image for the Desired Line Width (continued)



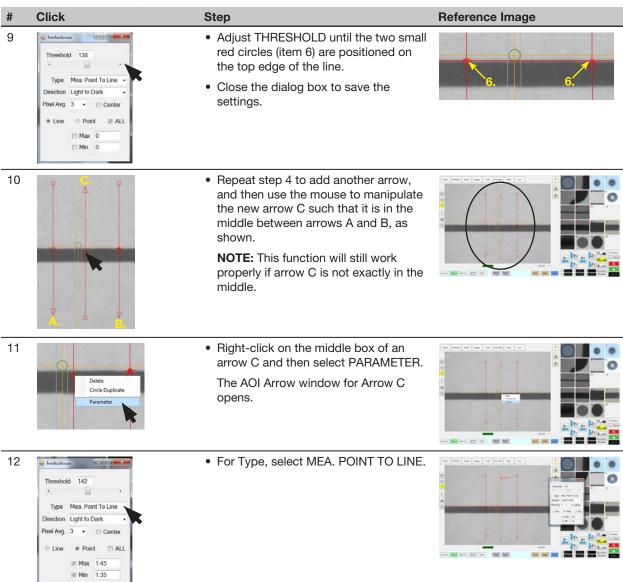
Continued on next page

· Select the LINE radio button. Deselect the MAX and MIN

checkboxes.

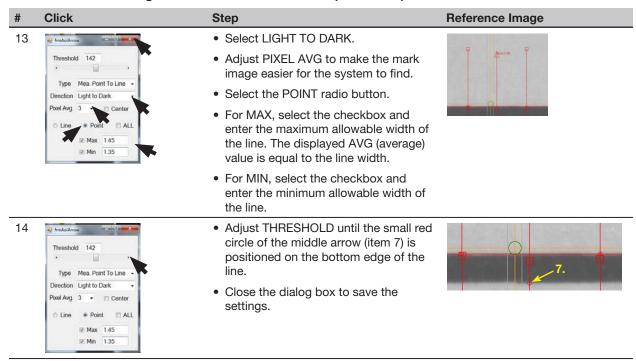
Mea. Point To Line Example (continued)

To Create a Mark Image for the Desired Line Width (continued)



Mea. Point To Line Example (continued)

To Create a Mark Image for the Desired Line Width (continued)



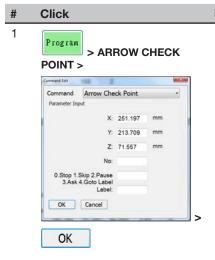
The saved mark image is now ready to be specified in an Arrow Check Point command to cause the system to check the width of a dispensed line anywhere on the line. In this example, the checked width must be within 1.35-1.45 mm (as defined in step 13). If the width is greater or lower, a warning box appears.

Continue to "To Use Arrow Check Point in a Program (Mea. Point to Line Example)" on page 46 to use the mark image.

NOTE: The system can return to the middle of a dispensed line only if the middle of the line is within the range specified in step 3 on page 42.

Mea. Point To Line Example (continued)

To Use Arrow Check Point in a Program (Mea. Point to Line Example)



Click the PROGRAM tab.

 Insert commands to dispense a line over the line on the workpiece template.

NOTE: The complete example program is provided below.

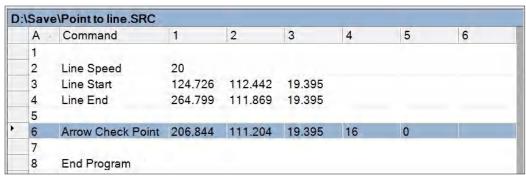
- Jog the camera to a location on the line where you want the system to check the width of a section.
- Insert an ARROW CHECK POINT command and enter parameters as follows:
 - Enter the number (No.) of the mark image created for the line in the previous procedure.
 - Select the action you want the system to take if the measured line section is above the Max value or below the Min value specified for the mark image (step 13 on page 45). Refer to "Arrow Check Point" on page 63 for details.
- Click OK.

When the system executes the Arrow Check Point command and finds an unacceptable line section, it takes the action specified by the Stop, Skip, Pause, Ask, Go to Label parameter. Refer to "Arrow Check Point" on page 63 for details.



Reference Image

C 15.365



Example program that contains an Arrow Check Point command for verifying line width

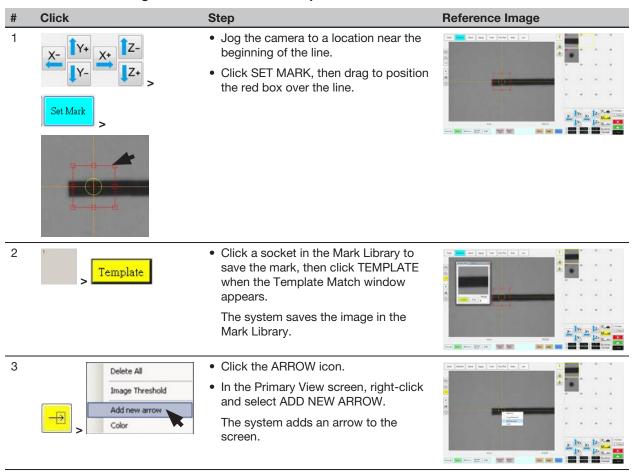
Mea. Width Example for Verifying Line Width

Mea. Width (Measure Width) is an OptiSure AOI feature that can be used in tandem with the Arrow Check Point or Arrow Check Line commands to measure the width of a predefined line, compare that measurement to subsequent dispenses (for either one section of the line or the complete line), and then, depending on the user-specified parameters, determine if the dispense is acceptable. If the dispense does not meet the specified criteria, the system takes the action specified in the Arrow Check Point or Arrow Check Line command.

PREREQUISITES

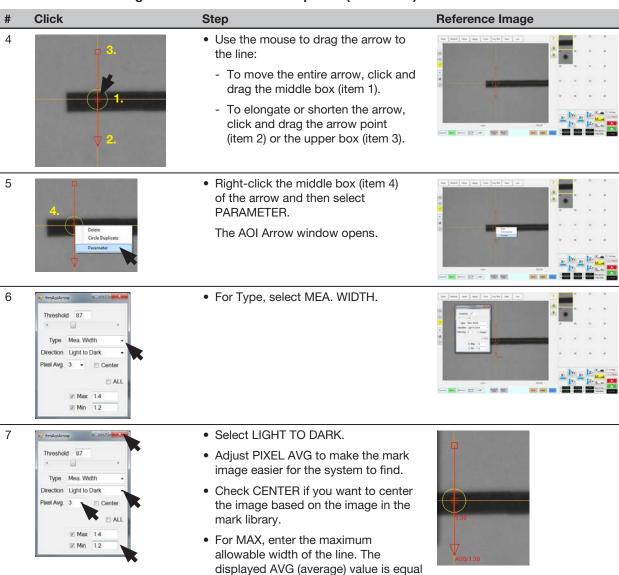
□ To learn how to use this feature, draw a line on a sheet of white paper and use it as a workpiece template.

To Create a Mark Image for the Desired Line Dispense



Mea. Width Example for Verifying Line Width (continued)

To Create a Mark Image for the Desired Line Dispense (continued)



Continued on next page

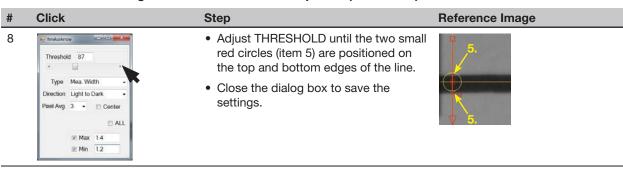
• For MIN, enter the minimum allowable

to the line width.

width of the line.

Mea. Width Example for Verifying Line Width (continued)

To Create a Mark Image for the Desired Line Dispense (continued)

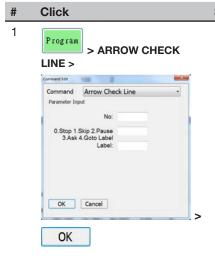


The saved mark image is now ready to be used in a program to check the width of a dispensed line:

- If you want the system to check the width of a complete line, use Arrow Check Line. Continue to "To Use Arrow Check Line in a Program (Mea. Width Example for Verifying Line Width)" on page 50.
- If you want the system to check the width of a section of line, use Arrow Check Point. Continue to "To Use Arrow Check Point in a Program (Mea. Width Example for Verifying Line Width)" on page 51.

Mea. Width Example for Verifying Line Width (continued)

To Use Arrow Check Line in a Program (Mea. Width Example for Verifying Line Width)



Click the PROGRAM tab.

 Insert commands to dispense a line directly over the line on the workpiece template.

NOTE: The complete example program is provided below.

- Jog the camera to a location on the line where you want the system to check the width of the middle of a line section.
- Insert an ARROW CHECK LINE command and enter parameters as follows:
 - Enter the number (No.) of the mark image created in the previous procedure.
 - Select the action you want the system to take if the measured line section is above the Max value or below the Min value specified for the mark image (step 7 on page 48). Refer to "Arrow Check Line" on page 64 for details.
- Click OK.



 Under the Arrow Check Line command, insert Line Start and Line End commands that include the coordinates for the start and end points of the line you want the system to check.



Reference Image

When the system executes the Arrow Check Line command and finds an unacceptable line section, it takes the action specified by the Stop, Skip, Pause, Ask, Go to Label parameter. Refer to "Arrow Check Line" on page 64 for details.

NOTE: The complete example program is provided below.



	A	Command	1	2	3	4	5	6	*
•	1	Line Start	107.741	136.201	80.685				
	2	Line End	178.571	135.401	80.685				
	4	Arrow Check Line	21	0					
	5	Line Start	107.741	136.201	80.685				
	6	Line End	178.571	135.401	80.685				£
	7								
	8	End Program							

Example program that contains an Arrow Check Line command for verifying line width

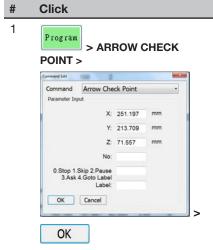
Reference Image

10 ess

Using the Arrow Types (continued)

Mea. Width Example for Verifying Line Width (continued)

To Use Arrow Check Point in a Program (Mea. Width Example for Verifying Line Width)



· Click the PROGRAM tab.

 Insert commands to dispense a line directly over the line on the workpiece template.

NOTE: The example program is provided below.

- · Jog the camera to a location on the line where you want the system to check the width of a section of the
- Insert an ARROW CHECK POINT command and enter parameters as follows:
 - Enter the number (No.) of the mark image created for the line in the previous procedure.
 - Select the action you want the system to take if the measured line section is above the Max value or below the Min value specified for the mark image (step 7 on page 48). Refer to "Arrow Check Point" on page 63 for details.
- · Click OK.

When the system executes the Arrow Check Point command and finds an unacceptable line section, it takes the action specified by the Stop, Skip, Pause, Ask, Go to Label parameter. Refer to "Arrow Check Point" on page 63 for details.

NOTE: The complete example program is provided below.



A	Command	1	2	3	4	5	6	*
1 2	Line Speed	20						
3	Line Start	90.798	95.394	80.685				
4	Line End	139.604	95.093	80.685				E
5								
6	Arrow Check Point	158.064	96.111	16.755	10	0		
7								- 5
8	End Program							19

Example program that contains an Arrow Check Point command for verifying line width

Using the Laser to Measure and Record Profiles

You can use the Laser Program and Laser Profile commands to measure and record the profile (displacement or thickness) of a fluid or a workpiece, to display the measurement data in real time, and to make the system check the laser measurement results against maximum and / or minimum threshold values. When a Laser Profile command is executed, the resulting graph and measurements are also exported as a *.JPEG image and a *.CSV file, respectively.

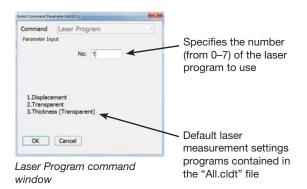
NOTE: This section applies to PROPlus/L and PRO/L systems with a confocal laser only.

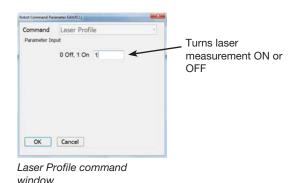
About the Laser Program and Laser Profile Commands

The Laser Program command is used to specify a number setting (from 0-7) that corresponds to a laser program that contains measurement settings. Laser measurement settings programs are created and saved in the CL-NavigatorN software. Laser programs 1-3 include default settings for Displacement (Non-Transparent), Displacement (Transparent), and Thickness (Transparent), respectively. Programs 0 and 4-7 are user-programmable via the CL-NavigatorN software. For information on using the CL-NavigatorN software, refer to the documentation supplied with the laser.

NOTE: Laser programs 1–3 can be edited using the CL-NavigatorN software.

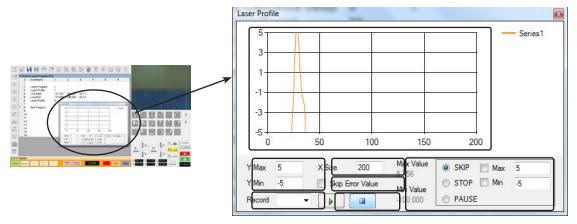
The Laser Profile command is used to turn laser measurement on and off in a dispense program. When turned on, the Laser Profile command also exports the graph and measurement data to a *.JPEG and *.CSV file, respectively.





About the Laser Profile Window

The Laser Profile command causes the system to open the Laser Profile window — this window shows the laser measurement data in real time. You can also use the settings in this window to make the system check the laser measurement results against maximum and / or minimum threshold values. Refer to "Laser Profile Window Fields" on page 59 for additional details.



The Laser Profile window opens when the system executes a Laser Profile command with a value of 1 (ON)

To Install CL-NavigatorN on the DispenseMotion Controller

The CL-NavigatorN software for the KEYENCE CL-3000 Series laser is provided on a CD, but can also be downloaded from the KEYENCE Corporation website as described below.

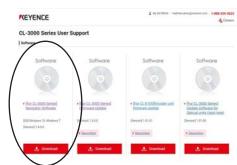
- Using an Internet-connected computer, go to KEYENCE.com/ CLsupport.
- 2. Create a KEYENCE account, or sign in if you already have an account.
- 3. Download the latest version of CL-NavigatorN to a USB drive.

NOTE: If you cannot readily find the download link, contact KEYENCE for technical support.

- Insert the USB drive into an open USB port on the DispenseMotion controller.
- 5. Navigate to the executable file on the USB drive and install the software.

After the installation completes, the CL-NavigatorN shortcut appears on the DispenseMotion controller desktop.





CL-NavigatorN software download link on the KEYENCE website



USB ports on the DispenseMotion controller

To Obtain the All.cldt File

The All.cldt file is required for the laser measurement feature to work correctly.

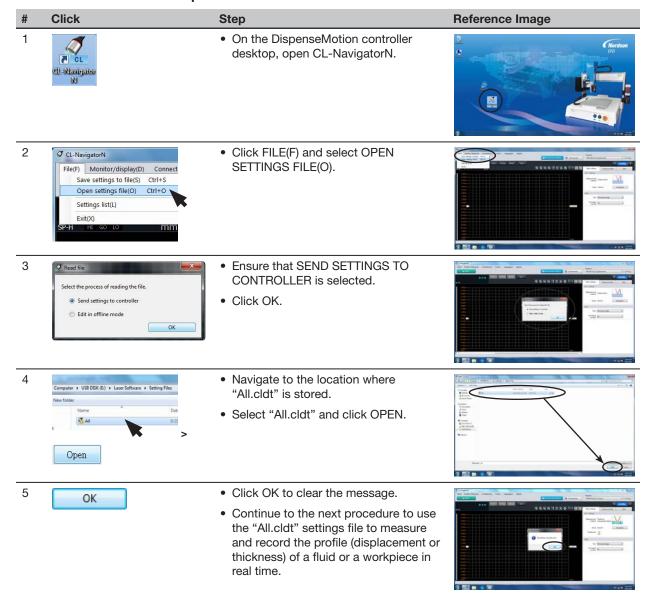
- 1. Contact your Nordson EFD representative to obtain the All.cldt
- Place the All.cldt file on a USB drive.
- Insert the USB drive into an open USB port on the DispenseMotion controller.

NOTE: You can leave All.cldt on the USB drive or copy it anywhere onto the DispenseMotion controller. Just be sure to remember where the file is located.

PREREQUISITES

- ☐ The confocal laser (Laser C) is properly installed and set up using the Laser Setup wizard. Refer to "Setting Up the Confocal Laser" on page 10.
- ☐ The CL-NavigatorN software has been installed on the DispenseMotion controller. Refer to "To Install CL-NavigatorN on the DispenseMotion Controller" on page 53.
- ☐ The All.cldt file has been obtained from Nordson EFD and can be located for transfer to the DispenseMotion conroller. Refer to "To Obtain the All.cldt File" on page 53.

To Send "All.cldt" to the DispenseMotion Controller

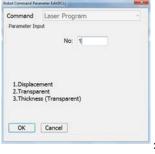


To Measure and Record the Profile of a Fluid or a Workpiece

PREREQUISITES

☐ The "All.cldt" file has been sent from CL-NavigatorN to the DispenseMotion controller as described under "To Send "All.cldt" to the DispenseMotion Controller" on page 54.

Reference Image Step 1 • On the DispenseMotion controller desktop, open DispenseMotion. 2 LASER PROGRAM > • Insert a LASER PROGRAM command and specify the laser program you



want to use. For this example, enter

NOTE: Selection 1 is the Displacement laser program for nontransparent materials or surfaces.

· Click OK.



OK

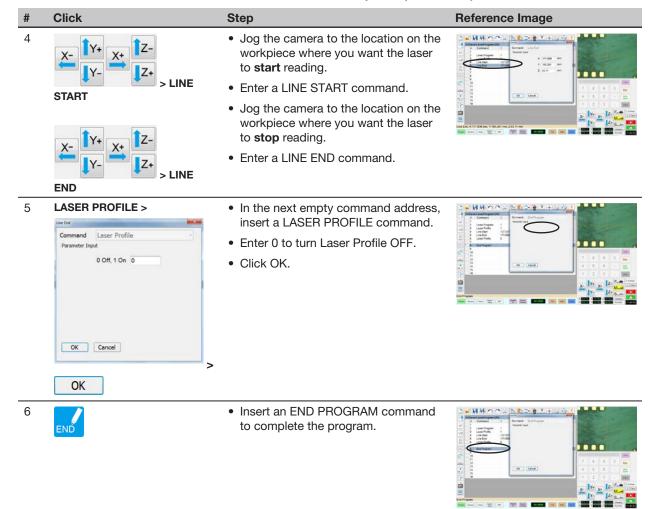
3 LASER PROFILE >



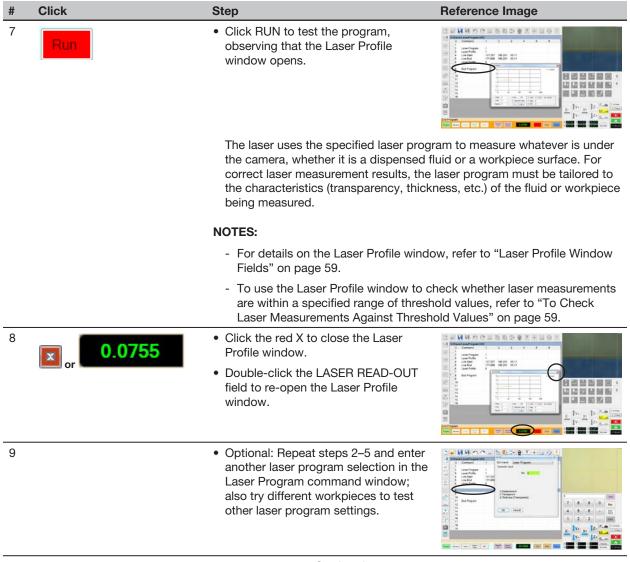
- In the next empty command address, insert a LASER PROFILE command.
- Enter 1 to turn Laser Profile ON.
- Click OK.



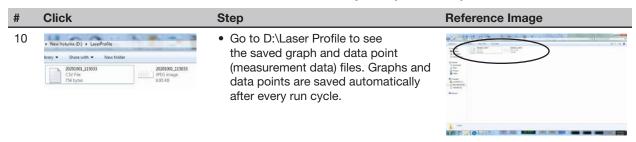
To Measure and Record the Profile of a Fluid or a Workpiece (continued)



To Measure and Record the Profile of a Fluid or a Workpiece (continued)



To Measure and Record the Profile of a Fluid or a Workpiece (continued)



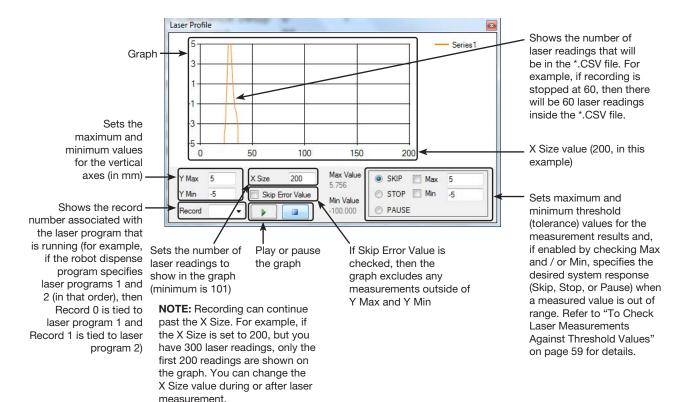
NOTES:

- All *.CSV and *.JPEG files are named with the date and time using the following format:
 - ProgramName-YYYYMMDD_HrMinSecs.CSV
 - ProgramName-YYYYMMDD_HrMinSecs.JPEG
- Every subsequent laser program will have an underscore and a number. For example:

ProgramName-YYYYMMDD_HrMinSecs_1.CSV, ProgramName-YYYYMMDD_HrMinSecs_1.JPEG

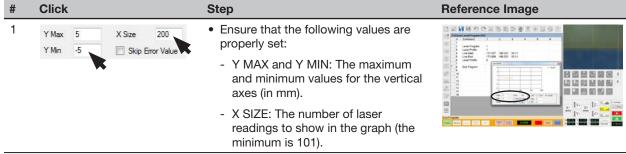
ProgramName-YYYYMMDD_HrMinSecs_2.CSV, ProgramName-YYYYMMDD_HrMinSecs_2.JPEG

Laser Profile Window Fields

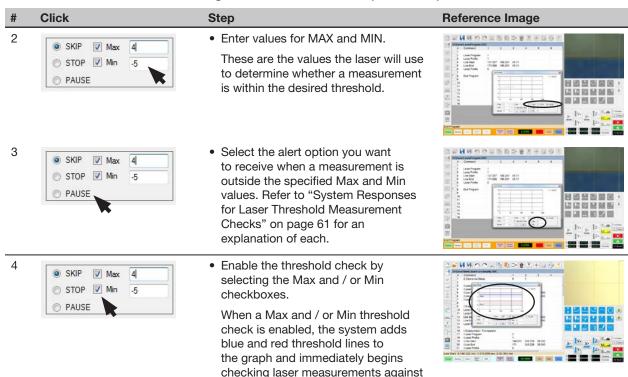


To Check Laser Measurements Against Threshold Values

When the laser is measuring and recording, you can use the Laser Profile window to specify Max and Min threshold (tolerance) values and to select the alert option to appear when a measurement is outside of the specified Max and / or Min thresholds.



To Check Laser Measurements Against Threshold Values (continued)



- If a measurement is within the Max and Min values, the measurement PASSES regardless of the selected alert. No action is required.

the entered Max and Min values:

- If a measurement is not within the Max and Min values, the system takes the action specified by the selected alert option. Refer to "System Responses for Laser Threshold Measurement Checks" on page 61 for the user action to take.

System Responses for Laser Threshold Measurement Checks

Action		Reference Image
SKIP W Max 4 STOP W Min -5	 When SKIP is selected: If a measurement is outside a Max or Min value, the program stops running after the laser measurement is done and then prompts to go to the HOME position. When this occurs, click HOME. 	
SKIP W Max 4	When STOP is selected: • If a measurement is below the Min value, the program stops running and the system generates a Surface Detect Fail warning. When this occurs, click OK and then click HOME.	
	If a measured value is above the Max value, the program stops running and the system prompts to go to the HOME position. When this occurs, click HOME.	The state of the s
SKIP V Max 4 .5 STOP V Min -5	When PAUSE is selected: If a measurement is outside a Max or Min value, the program stops running: • Select CONTINUE Continue to continue running the program. OR • Select STOP to stop the program, then click HOME to return the robot to the HOME position.	A Country of the Coun

OptiSure AOI Kit Part Numbers

Nordson EFD's OptiSure Automated Optical Inspection (AOI) software is available within the current DispenseMotion software as an optional add-on. The AOI feature inspects fluid deposit widths and diameters with exceptional certainty and determines if dispense requirements have been met. When paired with the OptiSure AOI confocal laser, the AOI feature provides three-dimensional (3D) deposit verification by measuring the height, width, and diameter of a fluid deposit and comparing it to a 3D image of a desired deposit to determine true volume accuracy. The OptiSure AOI feature also includes advanced functions for augmenting mark images to make them easier for the system find.

Item	Part #	Description
	7365229	Software key, OptiSure Automated Optical Inspection (AOI)
I		Laser C accessory kit (includes the confocal laser and laser controller)
	7364992	NOTES:
	7004332	 For use only with the OptiSure AOI add-on Includes the OptiSure AOI software key Takes the place of Laser A or Laser B

Appendix A, Command Function Reference

This appendix provides detailed information for each setup and dispense command. Commands are in alphabetical order.

The following rules apply to all commands:

- A command is in effect until it is superseded by another command.
- Command settings override system settings.

Arrow Check	V Check Point				
Click	Function				
Double-click address and select from drop- down menu	Used in tandem with the Mea. Width, Mea. Point to Line, and Positional Checking options of the OptiSure AOI feature to check the width of a section of a dispensed line (between two specified points) against a saved mark image that can specify Max and Min parameters for line width; if the width of a section of dispensed line is not within the allowable range, the system takes the action specified by the Skip, Stop, Pause, Ask, Go to Label parameter.				
	Parameter	Description			
	No.	The number of the mark image saved for the line section.			
	2.Pause, 3.Ask, 4.Go to Label specified for the sav 0.Stop The s warni the Z 1.Skip The s progr 2.Pause The s Butto click Home 3.Ask The s Next, point	The action the system takes if a dispensed line section does not meet the parameters specified for the saved mark image.			
		0.Stop	The system stops running the program and displays an Arrow Check Fail warning: Click OK to acknowledge the warning, then click HOME to move the Z axis to the Home position $(0, 0, 0)$.		
		1.Skip	The system skips the dispense and goes to the next command in the program.		
		The system stops running the program and displays a "Waiting [Start] Button]" box: Click START or CONTINUE to continue running the program; click STOP and then HOME to stop the program and send the robot to the Home position $(0,0,0)$.			
		3.Ask	The system stops running the program and displays a "Find Again, Find Next, or Stop Find" box: Click FIND AGAIN to make the system check the point again. Click FIND NEXT to go to the next command in the program. Click STOP FIND to stop the program.		
		4.Go to Label	The dispense program jumps to the specified Label.		

Appendix A, Command Function Reference (continued)

Arrow Check	Arrow Check Line					
Click	Function					
Double-click address and select from drop-	Used in tandem with the Mea. Width option of the OptiSure AOI feature to check the width of a dispensed line against a saved mark image; if the width of a dispensed line is not within the allowable range, the system takes the action specified by the Skip, Stop, Pause, Ask, or Go to Label parameter.					
down menu	Parameter	Description				
	No.	The number o	The number of the mark image saved for the line.			
	0.Stop, 1.Skip,	The action the system takes if a dispensed line does not match the saved mark image.				
	2.Pause, 3.Ask, 4.Go to Label	0.Stop	The system stops running the program and displays an Arrow Check Fail warning: Click OK to acknowledge the warning, then click HOME to move the Z axis to the Home position (0, 0, 0).			
		1.Skip	The system skips the dispense and goes to the next command in the program.			
		2.Pause	The system stops running the program and displays a "Waiting [Start] Button]" box: Click START or CONTINUE to continue running the program; click STOP and then HOME to stop the program and send the robot to the Home position (0, 0, 0).			
		3.Ask	The system stops running the program and displays a "Find Again, Find Next, or Stop Find" box: Click FIND AGAIN to make the system check the line again. Click FIND NEXT to go to the next command in the program. Click STOP FIND to stop the program.			
		4.Go to Label	The dispense program jumps to the specified Label.			

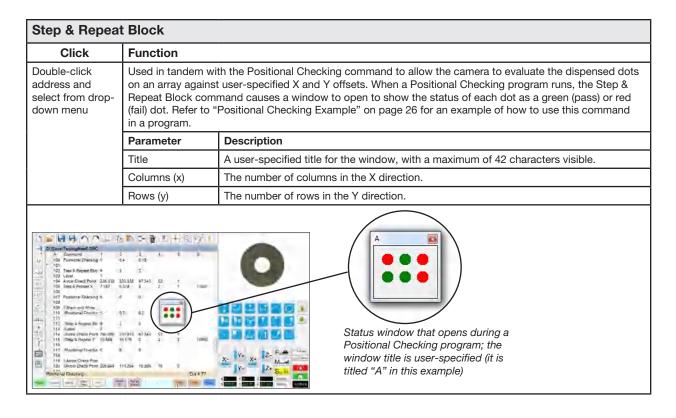
Laser Profile						
Click	Function					
Double-click address and select from drop-	uses the laser to r	with Laser Program to start or stop laser measurement. When turned ON, the system measure and record the profile (displacement or thickness) of a fluid or a workpiece. The and measurements (data points) are exported as a *.JPEG and a *.CSV file, respectively.				
down menu	When Laser Profile turns ON, the Laser Profile window opens to show the measurement data in real time. In the Laser Profile window, you can enter threshold (tolerance) values and then enable them to cause the system to check the laser measurements against the threshold values. If a measured value is outside the threshold range, the system takes the action specified by the selected Stop, Skip, or Pause radio button in the Laser Profile window. Refer to "To Check Laser Measurements Against Threshold Values" on page 59 for details. NOTES:					
	This command applies to PROPlus/L and PRO/L systems only.					
	Refer to "To Measure and Record the Profile of a Fluid or a Workpiece" on page 55 for an example of how to use this command in a program.					
		ram command tells the system which laser measurement settings program to use. Refer to " on page 65 for details.				
	Setting	Description				
	0 Off	Turns Laser Profile OFF, stopping laser measurement.				
	1 On	Turns Laser Profile ON, starting laser measurement and opening the Laser Profile Window. The Laser Profile window can be closed and reopened during active measurement.				

Appendix A, Command Function Reference (continued)

Laser Progran	າ			
Click	Function			
Double-click address and select from drop- down menu	or workpiece prof contain the follow • 1. Displaceme • 2. Displaceme • 3. Thickness (Program numbers NOTES: • This command • Laser programs	` ' /		
		command in a program.		
	The Laser Profi details.	le command starts and stops laser measurement. Refer to "Laser Profile" on page 64 for		
	Parameter	Description		
	0-7	Sets the CL-NavigatorN laser program to use when laser measurement and recording is turned on.		

Positional Checking						
Click	Function					
Double-click address and select from drop- down menu	Used in tandem with the Step & Repeat Block command to cause the camera to evaluate the dispensed dots on an array against user-specified X and Y offsets: If a dispensed dot fits within the specified offsets, it passes; if not, it fails. If Save Image under System Setup > Other is checked, the system also takes screen captures of all dispensed dots and saves the image files in the D:\ AOIIMAGE directory. Each image file includes details about the dispensed dot, including diameter and XY offset values. Refer to "Positional Checking Example" on page 26 for an example of how to use this command in a program.					
Parameter Description		Description				
	0 Off, 1 On	Turns Positional Checking OFF or ON.				
	Offset X	In the X direction, the maximum allowable deviation of an inner dot from the larger circle.				
	Offset Y	In the Y direction, the maximum allowable deviation of an inner dot from the larger circle.				

Appendix A, Command Function Reference (continued)



Notes	
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NORDSON FFD ONE YEAR I IMITED WARRANTY

This Nordson EFD product is warranted for one year from the date of purchase to be free from defects in material and workmanship (but not against damage caused by misuse, abrasion, corrosion, negligence, accident, faulty installation, or by dispensing material incompatible with equipment) when the equipment is installed and operated in accordance with factory recommendations and instructions.

Nordson EFD will repair or replace free of charge any defective part upon authorized return of the part prepaid to our factory during the warranty period. The only exceptions are those parts which normally wear and must be replaced routinely, such as, but not limited to, valve diaphragms, seals, valve heads, needles, and nozzles.

In no event shall any liability or obligation of Nordson EFD arising from this warranty exceed the purchase price of the equipment.

Before operation, the user shall determine the suitability of this product for its intended use, and the user assumes all risk and liability whatsoever in connection therewith. Nordson EFD makes no warranty of merchantability or fitness for a particular purpose. In no event shall Nordson EFD be liable for incidental or consequential damages.

This warranty is valid only when oil-free, clean, dry, filtered air is used, where applicable.



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